# NAS Enterprise Architecture



Infrastructure Roadmaps v19.2

#### **BASELINE**

July 2025



#### **Infrastructure Roadmap Overview**

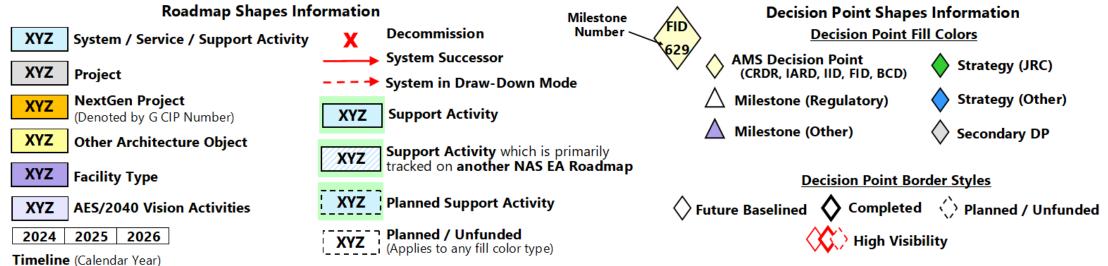
#### What are the Infrastructure Roadmaps?

- The FAA Infrastructure Roadmaps show the progression of system deployments, investments, and key decision points for major NAS acquisitions. They depict the acquisition strategy to evolve the NAS from the As-Is to the To-Be environment.
- The Infrastructure Roadmaps show all <u>Capital Investment Plan (CIP)</u> investment projects and systems identified in the NSIP that will deliver the necessary functionality to enable OIs and BTIs.

#### **Guidelines for Understanding the Roadmaps**

- The Infrastructure Roadmaps are organized by Domain (Automation, Communication, etc.) and depict projects, systems, services, decision points, and support activities.
- The timeline is in calendar years and shows a 17-year outlook.
- The roadmaps have swim lanes for Infrastructure (white), Support Activities (green), and Platform/Compute (purple).
- The DP diamonds represent the quarter in which a decision will occur.
- The Support Activity bars represent the dates that work is being performed on the activity.
- The Project bars represent the dates that CIP funding is allocated to a project.
- The System and Service bars represent the dates that a system or service is operational, with red lines indicating sustainment, drawdown, or convergence

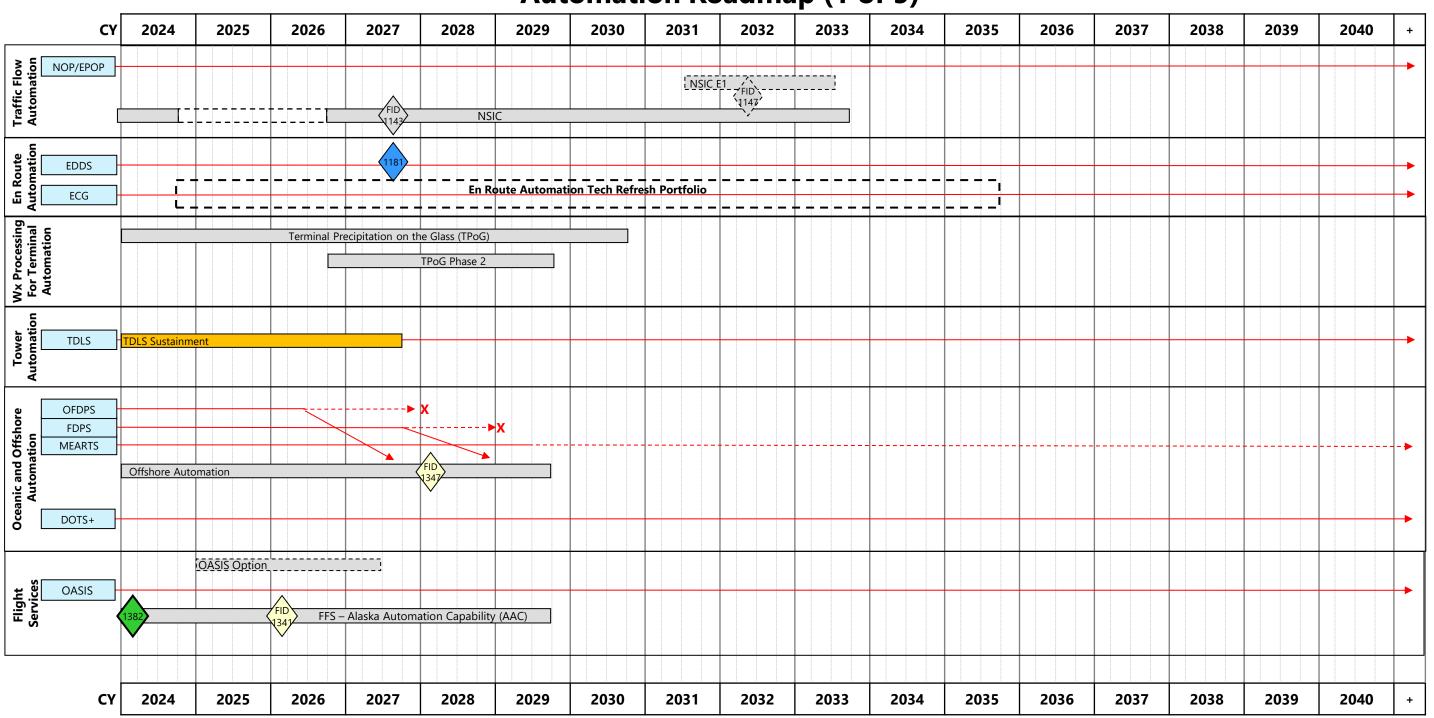
#### Infrastructure Roadmap Legend



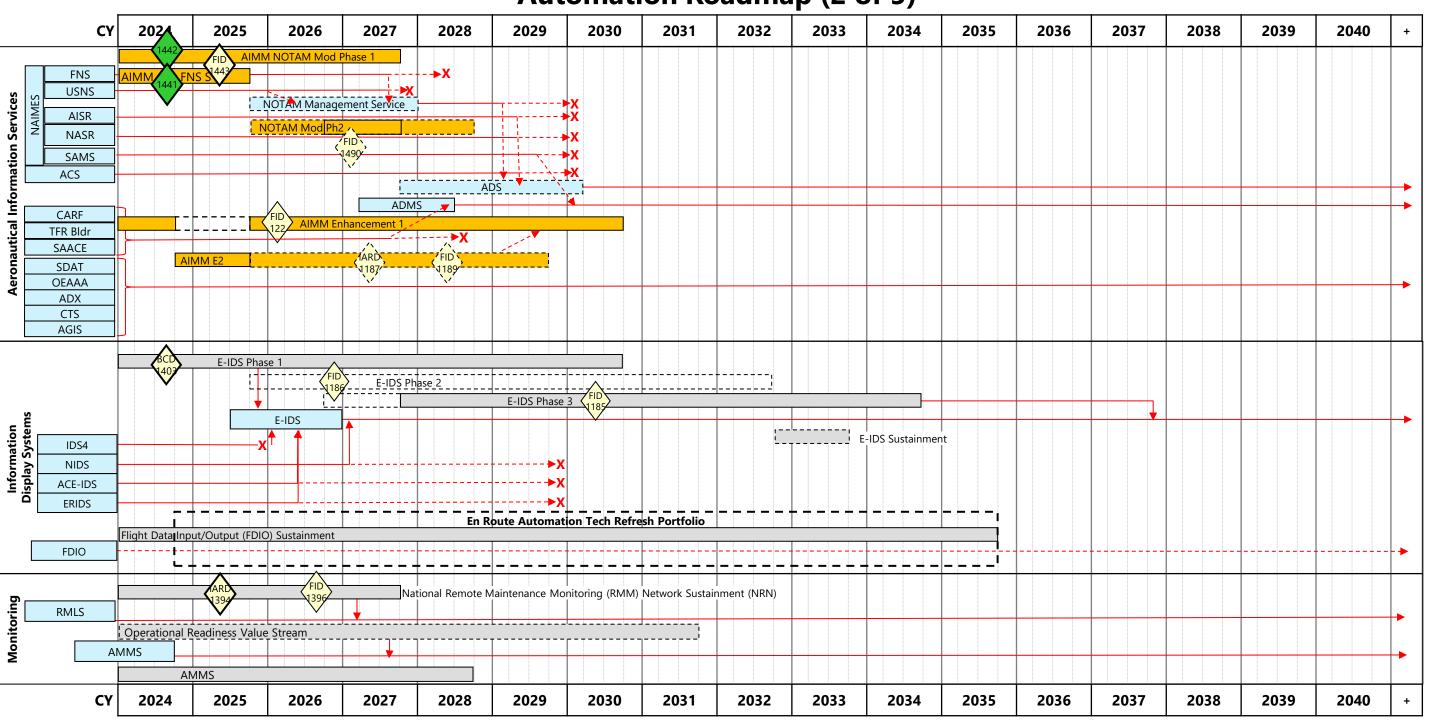
## **Automation**

The Automation Roadmap presents an Executive View (EV) of the current automation systems supporting the National Airspace System (NAS) and their enhancement, sustainment or replacement through major development programs and support activities. The Automation Roadmap is intended to convey the major automation program strategy and acquisition decision points as well as program execution through the In-Service Decision. The roadmap serves as a summary view of more detailed plans within each development program.

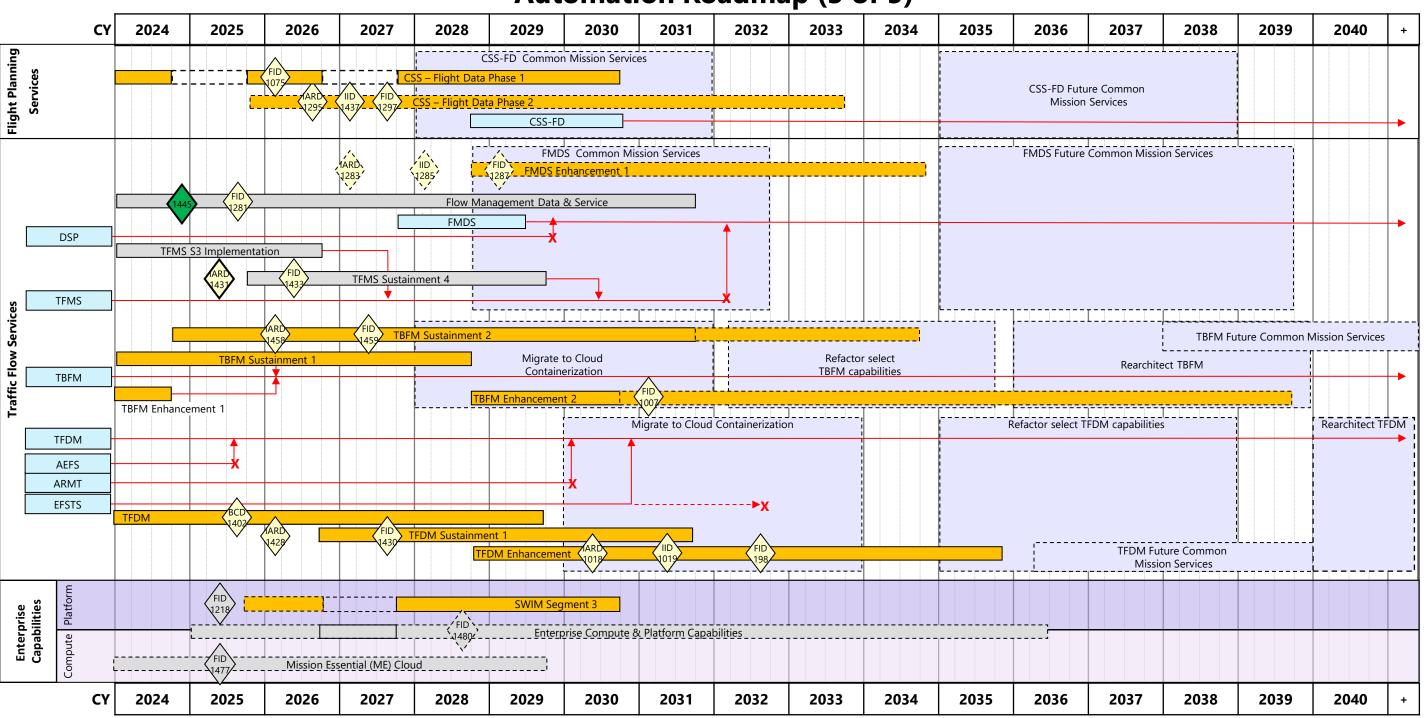
### **Automation Roadmap (1 of 5)**



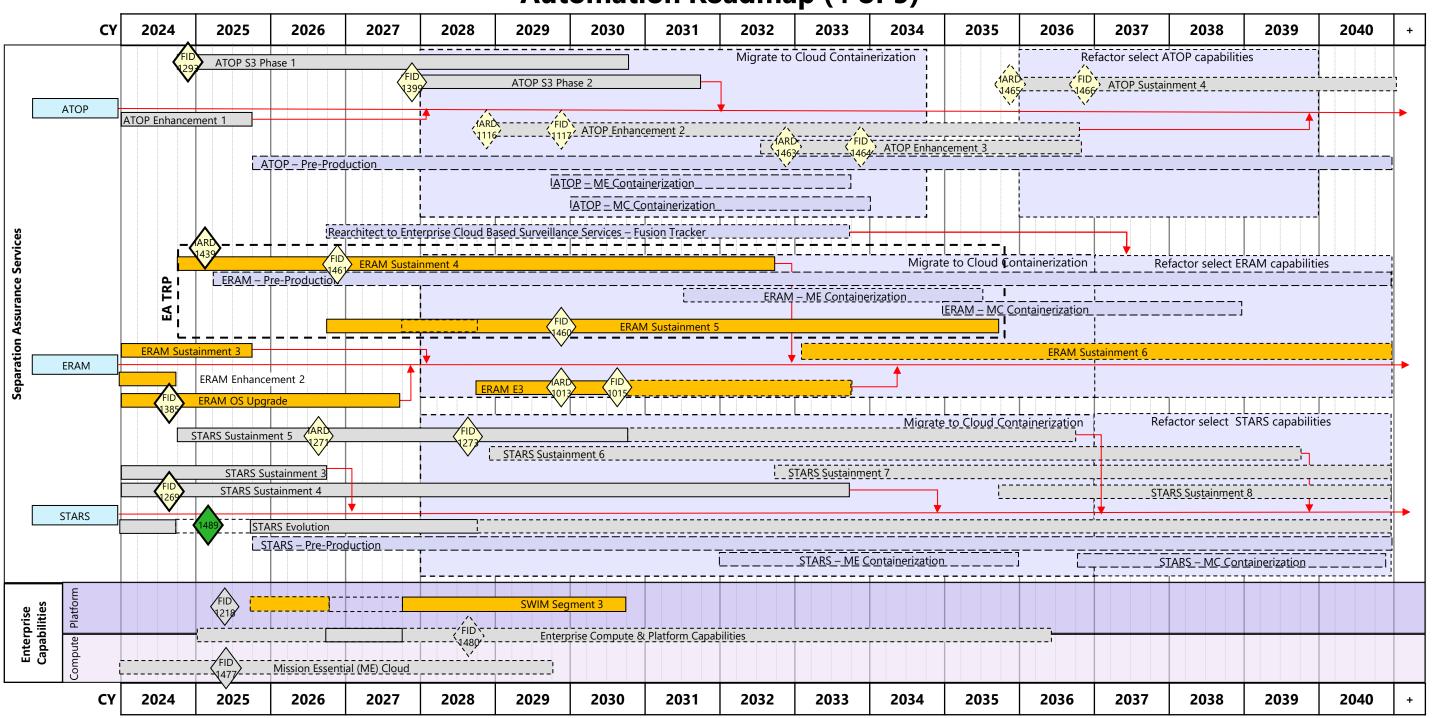
## **Automation Roadmap (2 of 5)**



### **Automation Roadmap (3 of 5)**



#### **Automation Roadmap (4 of 5)**



# **Automation Roadmap (5 of 5)**

| _  |                           |                            |                             | 1              |          |  |      |      |      | . `  |      |      |      |      |      |      |      |   |
|--|---------------------------|----------------------------|-----------------------------|----------------|----------|--|------|------|------|------|------|------|------|------|------|------|------|---|
| CY   | 2024                      | 2025                       | 2026                        | 2027           | 2028     | 2029   | 2030 | 2031 | 2032 | 2033 | 2034 | 2035 | 2036 | 2037 | 2038 | 2039 | 2040 | + |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| Adv  | <mark>vanced Met</mark> l | nods                       | <u> </u>                    |                | <u> </u> | I 1 1 1                                      |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| Flig   | ght Object                |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| Info   | ormation Ma               | anagement                  |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| 1<br>0<br>0<br>0<br>0<br>0<br>0<br>0<br>0<br>0<br>0<br>0   |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| Co   | ommon Stat                | us and Structu             | ure Data                    |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| Sep  | oaration Aut              | <mark>omation Syste</mark> | em Engineering              |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| 1<br>1<br>2<br>3<br>4<br>4<br>6<br>6<br>7<br>7<br>8<br>8<br>8<br>8<br>8<br>8<br>8<br>8<br>8<br>8<br>8<br>8<br>8<br>8<br>8<br>8 |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| Stra   | ategic Flow I             | Management .               | Application                 |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  | Strate                    | egic Flow Man              | <mark>agemerlt Engin</mark> | eering Enhance | ement    | <u>         i                           </u> |      |      |      |      |      |      |      |      |      |      |      |   |
| 1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1                                    |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| 1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1<br>1                                    |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| Sur  | rface Tactica             | l Flow                     |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
| Cor  | mmon Trajec               | ctory Models               |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |
|  | 2024                      | 2025                       | 2026                        | 2027           | 2020     | 2020   | 2020 | 2024 | 2022 | 2022 | 2024 | 2025 | 2026 | 2027 | 2020 | 2020 | 2040 |   |
| Y  | 2024                      | 2025                       | 2026                        | 2027           | 2028     | 2029   | 2030 | 2031 | 2032 | 2033 | 2034 | 2035 | 2036 | 2037 | 2038 | 2039 | 2040 | + |
|  |                           |                            |                             |                |          |  |      |      |      |      |      |      |      |      |      |      |      |   |

# **Automation Roadmap: Assumptions**

| Identifier | Description   |
|------------|---|
| AUTO-01    | Net-centric Enterprise Services will replace designated existing point to point interfaces with a system based on a Service Oriented Architecture providing enhanced data exchange, enhanced flexibility, and enhanced security for FAA Operations Personnel, and airspace users within a common information environment to support NextGen Operational Improvements. |
| AUTO-02    | ADS-B is a necessary infrastructure element to support Trajectory Based Operations, Flexible Terminal, and High Density Terminal solution sets.   |
| AUTO-03    | Data Communication is a necessary infrastructure element to support Trajectory Based Operations, Flexible Terminal, and High Density Terminal solution sets.  |
| AUTO-04    | Operational Service Units will be responsible for JRC Final Investment Decisions.   |
| AUTO-05    | Policy and standards decisions prescribing the use of hand-held devices for data messaging by General Aviation pilots and aircraft are established.   |
| AUTO-06    | Consistent security management across Data Communication, Automation and SWIM support the evolution.  |
| AUTO-07    | Human-system integration will be conducted during analysis, design, development, and testing of Automation programs.  |
| AUTO-08    | Safety analysis and considerations will be included in all applicable phases of Automation analysis, design, development, and testing and platforms will provide data as required for safety monitoring and analysis.   |
| AUTO-09    | Automation platform designs will support environmental and energy saving initiatives.   |