



June 25, 2015

Exemption No. 11915 Regulatory Docket No. FAA–2015–1340

Mr. William K. Pedersen 400 East Trade Street Forest City, NC 28043

Dear Mr. Pedersen:

This letter is to inform you that we have granted your request for exemption. It transmits our decision, explains its basis, and gives you the conditions and limitations of the exemption, including the date it ends.

By letter dated April 20, 2015, you petitioned the Federal Aviation Administration (FAA) for an exemption. The petitioner requested to operate an unmanned aircraft system (UAS) to conduct aerial video and photography of construction sites, real estate, and landscape.

See Appendix A for the petition submitted to the FAA describing the proposed operations and the regulations that the petitioner seeks an exemption.

The FAA has determined that good cause exists for not publishing a summary of the petition in the Federal Register because the requested exemption would not set a precedent, and any delay in acting on this petition would be detrimental to the petitioner.

#### **Airworthiness Certification**

The UAS proposed by the petitioner is a DJI Phantom 2 and DJI S1000.

In accordance with the statutory criteria provided in Section 333 of Public Law 112–95 in reference to 49 U.S.C. § 44704, and in consideration of the size, weight, speed, and limited operating area associated with the aircraft and its operation, the Secretary of Transportation has determined that this aircraft meets the conditions of Section 333. Therefore, the FAA finds that relief from 14 CFR part 21, *Certification procedures for products and parts*,

Subpart H—Airworthiness Certificates, and any associated noise certification and testing requirements of part 36, is not necessary.

#### The Basis for Our Decision

You have requested to use a UAS for aerial data collection<sup>1</sup>. The FAA has issued grants of exemption in circumstances similar in all material respects to those presented in your petition. In Grants of Exemption Nos. 11062 to Astraeus Aerial (*see* Docket No. FAA–2014–0352), 11109 to Clayco, Inc. (*see* Docket No. FAA–2014–0507), 11112 to VDOS Global, LLC (*see* Docket No. FAA–2014–0382), and 11213 to Aeryon Labs, Inc. (*see* Docket No. FAA–2014–0642), the FAA found that the enhanced safety achieved using an unmanned aircraft (UA) with the specifications described by the petitioner and carrying no passengers or crew, rather than a manned aircraft of significantly greater proportions, carrying crew in addition to flammable fuel, gives the FAA good cause to find that the UAS operation enabled by this exemption is in the public interest.

Having reviewed your reasons for requesting an exemption, I find that—

- They are similar in all material respects to relief previously requested in Grant of Exemption Nos. 11062, 11109, 11112, and 11213;
- The reasons stated by the FAA for granting Exemption Nos. 11062, 11109, 11112, and 11213 also apply to the situation you present; and
- A grant of exemption is in the public interest.

#### **Our Decision**

In consideration of the foregoing, I find that a grant of exemption is in the public interest. Therefore, pursuant to the authority contained in 49 U.S.C. 106(f), 40113, and 44701, delegated to me by the Administrator, William K. Pedersen is granted an exemption from 14 CFR §§ 61.23(a) and (c), 61.101(e)(4) and (5), 61.113(a), 61.315(a), 91.7(a), 91.119(c), 91.121, 91.151(a)(1), 91.405(a), 91.407(a)(1), 91.409(a)(1) and (2), and 91.417(a) and (b), to the extent necessary to allow the petitioner to operate a UAS to perform aerial data collection. This exemption is subject to the conditions and limitations listed below.

#### **Conditions and Limitations**

In this grant of exemption, William K. Pedersen is hereafter referred to as the operator.

<sup>&</sup>lt;sup>1</sup> Aerial data collection includes any remote sensing and measuring by an instrument(s) aboard the UA. Examples include imagery (photography, video, infrared, etc.), electronic measurement (precision surveying, RF analysis, etc.), chemical measurement (particulate measurement, etc.), or any other gathering of data by instruments aboard the UA.

Failure to comply with any of the conditions and limitations of this grant of exemption will be grounds for the immediate suspension or rescission of this exemption.

- 1. Operations authorized by this grant of exemption are limited to the DJI Phantom 2 and DJI S1000 when weighing less than 55 pounds including payload. Proposed operations of any other aircraft will require a new petition or a petition to amend this exemption.
- 2. Operations for the purpose of closed-set motion picture and television filming are not permitted.
- 3. The UA may not be operated at a speed exceeding 87 knots (100 miles per hour). The exemption holder may use either groundspeed or calibrated airspeed to determine compliance with the 87 knot speed restriction. In no case will the UA be operated at airspeeds greater than the maximum UA operating airspeed recommended by the aircraft manufacturer.
- 4. The UA must be operated at an altitude of no more than 400 feet above ground level (AGL). Altitude must be reported in feet AGL.
- 5. The UA must be operated within visual line of sight (VLOS) of the PIC at all times. This requires the PIC to be able to use human vision unaided by any device other than corrective lenses, as specified on the PIC's FAA-issued airman medical certificate or U.S. driver's license.
- 6. All operations must utilize a visual observer (VO). The UA must be operated within the visual line of sight (VLOS) of the PIC and VO at all times. The VO may be used to satisfy the VLOS requirement as long as the PIC always maintains VLOS capability. The VO and PIC must be able to communicate verbally at all times; electronic messaging or texting is not permitted during flight operations. The PIC must be designated before the flight and cannot transfer his or her designation for the duration of the flight. The PIC must ensure that the VO can perform the duties required of the VO.
- 7. This exemption and all documents needed to operate the UAS and conduct its operations in accordance with the conditions and limitations stated in this grant of exemption, are hereinafter referred to as the operating documents. The operating documents must be accessible during UAS operations and made available to the Administrator upon request. If a discrepancy exists between the conditions and limitations in this exemption and the procedures outlined in the operating documents, the conditions and limitations herein take precedence and must be followed. Otherwise, the operator must follow the procedures as outlined in its operating documents. The operator may update or revise its operating documents. It is the operator's responsibility to track such revisions and present updated and revised

documents to the Administrator or any law enforcement official upon request. The operator must also present updated and revised documents if it petitions for extension or amendment to this grant of exemption. If the operator determines that any update or revision would affect the basis upon which the FAA granted this exemption, then the operator must petition for an amendment to its grant of exemption. The FAA's UAS Integration Office (AFS-80) may be contacted if questions arise regarding updates or revisions to the operating documents.

- 8. Any UAS that has undergone maintenance or alterations that affect the UAS operation or flight characteristics, e.g., replacement of a flight critical component, must undergo a functional test flight prior to conducting further operations under this exemption. Functional test flights may only be conducted by a PIC with a VO and must remain at least 500 feet from other people. The functional test flight must be conducted in such a manner so as to not pose an undue hazard to persons and property.
- 9. The operator is responsible for maintaining and inspecting the UAS to ensure that it is in a condition for safe operation.
- 10. Prior to each flight, the PIC must conduct a pre-flight inspection and determine the UAS is in a condition for safe flight. The pre-flight inspection must account for all potential discrepancies, e.g., inoperable components, items, or equipment. If the inspection reveals a condition that affects the safe operation of the UAS, the aircraft is prohibited from operating until the necessary maintenance has been performed and the UAS is found to be in a condition for safe flight.
- 11. The operator must follow the UAS manufacturer's maintenance, overhaul, replacement, inspection, and life limit requirements for the aircraft and aircraft components.
- 12. Each UAS operated under this exemption must comply with all manufacturer safety bulletins.
- 13. Under this grant of exemption, a PIC must hold either an airline transport, commercial, private, recreational, or sport pilot certificate. The PIC must also hold a current FAA airman medical certificate or a valid U.S. driver's license issued by a state, the District of Columbia, Puerto Rico, a territory, a possession, or the Federal government. The PIC must also meet the flight review requirements specified in 14 CFR § 61.56 in an aircraft in which the PIC is rated on his or her pilot certificate.
- 14. The operator may not permit any PIC to operate unless the PIC demonstrates the ability to safely operate the UAS in a manner consistent with how the UAS will be operated under this exemption, including evasive and emergency maneuvers and maintaining appropriate distances from persons, vessels, vehicles and structures. PIC qualification flight hours and currency must be logged in a manner consistent with

- 14 CFR § 61.51(b). Flights for the purposes of training the operator's PICs and VOs (training, proficiency, and experience-building) and determining the PIC's ability to safely operate the UAS in a manner consistent with how the UAS will be operated under this exemption are permitted under the terms of this exemption. However, training operations may only be conducted during dedicated training sessions. During training, proficiency, and experience-building flights, all persons not essential for flight operations are considered nonparticipants, and the PIC must operate the UA with appropriate distance from nonparticipants in accordance with 14 CFR § 91.119.
- 15. UAS operations may not be conducted during night, as defined in 14 CFR § 1.1. All operations must be conducted under visual meteorological conditions (VMC). Flights under special visual flight rules (SVFR) are not authorized.
- 16. The UA may not operate within 5 nautical miles of an airport reference point (ARP) as denoted in the current FAA Airport/Facility Directory (AFD) or for airports not denoted with an ARP, the center of the airport symbol as denoted on the current FAA-published aeronautical chart, unless a letter of agreement with that airport's management is obtained or otherwise permitted by a COA issued to the exemption holder. The letter of agreement with the airport management must be made available to the Administrator or any law enforcement official upon request.
- 17. The UA may not be operated less than 500 feet below or less than 2,000 feet horizontally from a cloud or when visibility is less than 3 statute miles from the PIC.
- 18. If the UAS loses communications or loses its GPS signal, the UA must return to a pre-determined location within the private or controlled-access property.
- 19. The PIC must abort the flight in the event of unpredicted obstacles or emergencies.
- 20. The PIC is prohibited from beginning a flight unless (considering wind and forecast weather conditions) there is enough available power for the UA to conduct the intended operation and to operate after that for at least five minutes or with the reserve power recommended by the manufacturer if greater.
- 21. Air Traffic Organization (ATO) Certificate of Waiver or Authorization (COA). All operations shall be conducted in accordance with an ATO-issued COA. The exemption holder may apply for a new or amended COA if it intends to conduct operations that cannot be conducted under the terms of the attached COA.
- 22. All aircraft operated in accordance with this exemption must be identified by serial number, registered in accordance with 14 CFR part 47, and have identification (N–Number) markings in accordance with 14 CFR part 45, Subpart C. Markings must be as large as practicable.

- 23. Documents used by the operator to ensure the safe operation and flight of the UAS and any documents required under 14 CFR §§ 91.9 and 91.203 must be available to the PIC at the Ground Control Station of the UAS any time the aircraft is operating. These documents must be made available to the Administrator or any law enforcement official upon request.
- 24. The UA must remain clear and give way to all manned aviation operations and activities at all times.
- 25. The UAS may not be operated by the PIC from any moving device or vehicle.
- 26. All Flight operations must be conducted at least 500 feet from all nonparticipating persons, vessels, vehicles, and structures unless:
  - a. Barriers or structures are present that sufficiently protect nonparticipating persons from the UA and/or debris in the event of an accident. The operator must ensure that nonparticipating persons remain under such protection. If a situation arises where nonparticipating persons leave such protection and are within 500 feet of the UA, flight operations must cease immediately in a manner ensuring the safety of nonparticipating persons; and
  - b. The owner/controller of any vessels, vehicles or structures has granted permission for operating closer to those objects and the PIC has made a safety assessment of the risk of operating closer to those objects and determined that it does not present an undue hazard.
  - The PIC, VO, operator trainees or essential persons are not considered nonparticipating persons under this exemption.
- 27. All operations shall be conducted over private or controlled-access property with permission from the property owner/controller or authorized representative. Permission from property owner/controller or authorized representative will be obtained for each flight to be conducted.
- 28. Any incident, accident, or flight operation that transgresses the lateral or vertical boundaries of the operational area as defined by the applicable COA must be reported to the FAA's UAS Integration Office (AFS-80) within 24 hours. Accidents must be reported to the National Transportation Safety Board (NTSB) per instructions contained on the NTSB Web site: www.ntsb.gov.

If this exemption permits operations for the purpose of closed-set motion picture and television filming and production, the following additional conditions and limitations apply.

29. The operator must have a motion picture and television operations manual (MPTOM) as documented in this grant of exemption.

- 30. At least 3 days before aerial filming, the operator of the UAS affected by this exemption must submit a written Plan of Activities to the local Flight Standards District Office (FSDO) with jurisdiction over the area of proposed filming. The 3-day notification may be waived with the concurrence of the FSDO. The plan of activities must include at least the following:
  - a. Dates and times for all flights;
  - b. Name and phone number of the operator for the UAS aerial filming conducted under this grant of exemption;
  - c. Name and phone number of the person responsible for the on-scene operation of the UAS:
  - d. Make, model, and serial or N-Number of UAS to be used;
  - e. Name and certificate number of UAS PICs involved in the aerial filming;
  - f. A statement that the operator has obtained permission from property owners and/or local officials to conduct the filming production event; the list of those who gave permission must be made available to the inspector upon request;
  - g. Signature of exemption holder or representative; and
  - h. A description of the flight activity, including maps or diagrams of any area, city, town, county, and/or state over which filming will be conducted and the altitudes essential to accomplish the operation.
- 31. Flight operations may be conducted closer than 500 feet from participating persons consenting to be involved and necessary for the filming production, as specified in the exemption holder's MPTOM.

Unless otherwise specified in this grant of exemption, the UAS, the UAS PIC, and the UAS operations must comply with all applicable parts of 14 CFR including, but not limited to, parts 45, 47, 61, and 91.

This exemption terminates on July 31, 2017, unless sooner superseded or rescinded.

Sincerely,

/s/

John S. Duncan Director, Flight Standards Service

**Enclosures** 

# UNITED STATES OF AMERICA DEPARTMENT OF TRANSPORTATION FEDERAL AVIATION ADMINISTRATION WASHINGTON, DC

Regulatory Docket No. Section 333

#### IN THE MATTER OF THE PETITION FOR EXEMPTION OF:

William K. Pedersen

FOR AN EXEMPTION SEEKING RELIEF FROM THE REQUIREMENTS OF TITLE 14 OF THE CODE OF FEDERAL REGULATIONS

SECTIONS 61.113(a) & (b), 91.7(a), 91.121, 91.151(b), 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), AND 91.417(a) & (b) CONCERNING COMMERCIAL

**OPERATION OF DJI PHANTOM2UNMANNED** 

AIRCRAFT SYSTEMS PURSUANT TO SECTION 333 OF

THE FAA MODERNIZATION AND REFORM ACT OF 2012 (PUBLIC LAW 112-95)

Submitted on April 20, 2015

William K. Pedersen 400 E. Trade Street Forest City, NC 28043 (828) 305-0139

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#### **GLOSSARY OF ABBREVIATIONS**

Federal Aviation Administration

AGL Above Ground Level

AOI Area of Interest

ATC Air Traffic Control

ATO Air Traffic Organization

AV Aerial Vehicle

FAA

CFR Code of Federal Regulations
COA Certificate of Authorization

Corr Certificate of Munorization

FAR Federal Aviation Regulation

GCS Ground Control Station

GPS Global Positioning System

LOL Loss of Link

NAS National Airspace System

NOTAM Notice to Airman
PIC Pilot In Command

Section 333 FAA Modernization and Reform Act of 2012 (FMRA) Section 333

SO Safety Observer

SOP Standard Operating Procedures

UA Unmanned Aircraft

UAS Unmanned Aircraft System

VFR Visual Flight Rules

VLOS Visual Line of Sight

VMC Visual Meteorological Conditions

VTOL Vertical Takeoff and Landing

#### **SUMMARY**

William K. Pedersen seeks exemption from the requirements of 14 C.F.R §§ 61.113(a) & (b), 91.7(a), 91.121, 91.151(b), 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), and 91.417(a) & (b), to operate an Unmanned Aircraft System pursuant to Section 333 of the FAA Modernization and Reform Act of 2012 (FMRA). This exemption will permit William K. Pedersen to operate an Unmanned Aircraft System (UA) for the commercial purpose of conducting aerial video and photography of construction sites, real estate, and landscape over certain areas of the United States.

### INTRODUCTION AND INTERESTS OF THE PETITIONER

William K. Pedersen provides its clients with expertise and knowledge in advanced technologies and solutions to increase efficiency, productivity and effectiveness. William K. Pedersen has over 30 years of professional experience in business and commercial aviation operations. He has over 2 years recreational/hobby experience in all aspects of aerial video and photography. William K. Pedersen holds a FAA private pilot certificate issued December 1998.

The objective of William K. Pedersen aerial video and photography operations is to provide high quality imaging for a variety of commercial, public, and residential uses, specifically targeting:

- Construction sites before and after
- Appraisals
- Real-estate marketing
- Motion Picture Filming
- Aerial acquisitions used for inspections of public and private structures.
- Search and Rescue operations

#### **BACKGROUND**

### Unmanned Aircraft Systems: DJI Phantom2, DJI S1000 UA

William K. Pedersen seeks an exemption to operate DJI systems for compensation or hire within the NAS. The DJI Phantom2 is a vertical takeoff and landing (VTOL) Unmanned Aircraft (UA) with a Ground Control Station (GCS) utilizing electronic tablet or smart phone systems. . The DJI Phantom2 has a maximum gross weight of approximately 2 pounds 5 ounces, while having a length of 16 inches, width of 16 inches and height of 8 inches, and a maximum speed of approximately 19.4 knots. The DJI S1000 has a maximum gross weight of approximately 24 pounds, while having a length of 41 inches, width of 41 inches and a height of 20 inches. The DJI Phantom2 is equipped with four main rotors; driven by a Lithium Polymer battery powered electric motors. The DJI S1000 is equipped with eight main rotors driven by a Lithium Polymer battery powered electric motors. The DJI Phantom2 that will be operated by William K. Pedersen will be registered in accordance with 49 U.S.C. 44103, *Registration of Aircraft*, as well as 14 C.F.R. Part 47, *Aircraft Registration*, and marked in accordance with 14 C.F.R. Part 45, *Identification and Registration Marking*.

#### **BASIS FOR PETITION**

Petitioner, William K. Pedersen, pursuant to the provisions of the Federal Aviation Regulations (14 C.F.R. § 11.61) and the FAA Modernization and Reform Act of 2012 (FMRA), Section 333, *Special Rules for Certain Unmanned Aircraft Systems*, hereby petitions the Administrator to commercially operate the DJI Phantom2 UA in the National Airspace System (NAS), and for an exemption from the requirements of 14 C.F.R §§ 61.113(a) & (b), 91.7(a), 91.121, 91.151(b), 91.405(a),

91.407(a)(1), 91.409(a)(1) & (a)(2), and 91.417(a) & (b).

In consideration of the speed, weight, size, and limited operating area associated with the unmanned aircraft and its operation, William K. Pedersen operation of DJI Phantom2 UA meets the conditions of FMRA Section 333 and therefore, will not require an airworthiness certificate in accordance with 14 C.F.R. Part 21, Subpart H.

Accordingly, William K. Pedersen requests relief from Sections 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), and 91.417(a) & (b), as these sections set forth requirements for maintenance that only apply to aircraft with an airworthiness certificate.

William K. Pedersen submits that the requested relief is proper since an equivalent level of safety will be ensured. William K. Pedersen will use experienced personnel or technicians to perform maintenance, alterations, or preventive maintenance on the UA using the methods, techniques, and practices prescribed in the operating documents (i.e., Monthly Maintenance Log, and DJI Phantom2 Instruction Manual). Furthermore, William K. Pedersen will document and maintain all maintenance records for the DJI Phantom2 UA.

Relief from certain requirements of Section 61.113(a) and (b), entitled *Private pilot privileges and limitations: Pilot in command*, is requested by William K. Pedersen to the extent necessary to allow a Pilot in Command (PIC) holding a private pilot or higher level certificate, as well as an airman medical certificate, and who has demonstrated, by meeting minimum flight-hour and currency requirements, that the PIC is able to safely operate the DJI Phantom2 UA in a manner consistent with this exemption, including evasive and emergency maneuvers and maintaining appropriate distances from people, vessels, vehicles and structures.

William K. Pedersen seeks relief from Section 91.7(a), entitled *Civil aircraft* airworthiness, because the DJI Phantom2 UA do not require an airworthiness certificate in accordance with 14 C.F.R. Part 21, Subpart H. As such, William K. Pedersen submits that he will

ensure that the DJI Phantom2 UA Is in an airworthy condition, prior to every flight, by determining that the UA Is in compliance with the operating documents (i.e., Monthly Maintenance Log, and DJI Phantom2 Instruction Manual), and that the aircraft are in a condition for safe flight.

William K. Pedersen also seeks an exemption from the requirements of Section 91.121, entitled *Altimeter Settings*, as the DJI Phantom2 UA will not have a typical barometric altimeter onboard. However, altitude information of the DJI Phantom2 UA will be provided to the PIC via Global Positioning System (GPS) equipment and radio communications telemetry data link, which downlinks from the UA to the GCS for active monitoring of the flight path. This altitude information, combined with William K. Pedersen's operation of the DJI Phantom2 UA within visual line of sight, at or below 200 feet AGL, will ensure a level of safety equivalent to Section 91.121.

Additionally, William K. Pedersen seeks an exemption from the requirements of Section 91.151(b), entitled *Fuel requirements for flight in VFR conditions*. William K. Pedersen submits that safety will not be affected by operation of the DJI Phantom2 UA during daylight hours in visual meteorological conditions (VMC) under visual flight rules (VFR), with enough battery power to fly for a total duration of approximately 13.5 minutes to the first point of intended landing and, assuming normal cruising speed, to fly after that for at least 4.5 minutes.

In accordance with 14 C.F.R. § 11.81, William K. Pedersen provides the following information in support of its petition for exemption:

#### A. Name And Address Of The Petitioner.

The name and address of the Petitioner and point of contact is:

William K. Pedersen 400 E. Trade Street

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Email: kris.pedersen@icarusgrp.com

### B. The Specific Sections Of 14 C.F.R. From Which William K. Pedersen Seeks Exemption.

### 1. William K. Pedersen Seeks Exemption From The Requirements Of Section 61.113(a) And (b).

Section 61.113, entitled Private pilot privileges and limitations: *Pilot in command*,

subsections (a) and (b) prescribe the following, in relevant part:

- (a) No person who holds a private pilot certificate may act as a pilot in command (PIC) of an aircraft that is carrying passengers or property for compensation or hire; nor may that person, for compensation or hire, act as PIC of an aircraft.
- (b) A private pilot may, for compensation or hire, act as PIC of an aircraft in connection with any business or employment if—
  - (1) The flight is only incidental to that business or employment; and
- (2) The aircraft does not carry passengers or property for compensation or hire.

### 2. William K. Pedersen Seeks Exemption From The Requirements Of Section 91.7(a).

Section 91.7, entitled *Civil aircraft airworthiness*, subsection (a), states the following:

(a) No person may operate a civil aircraft unless it is in an airworthy condition.

### 3. William K. Pedersen Seeks Exemption From The Requirements Of Section 91.121.

Section 91.121, entitled Altimeter settings, subsection (a), states the following, in part:

- (a) Each person operating an aircraft shall maintain the cruising altitude or flight level of that aircraft, as the case may be, by reference to an altimeter that is set, when operating--
  - (1) Below 18,000 feet MSL, to--
    - (i) The current reported altimeter setting of a station along the route and within 100 nautical miles of the aircraft;

- (ii) If there is no station within the area prescribed in paragraph (a)(1)(i) of this section, the current reported altimeter setting of an appropriate available station; or
- (iii) In the case of an aircraft not equipped with a radio, the elevation of the departure airport or an appropriate altimeter setting available before departure.

### 4. William K. Pedersen Seeks Exemption From The Requirements Of Section 91.151(b).

Section 91.151, entitled Fuel requirements for flight in VFR conditions, subsection

- (b), states the following:
- (b) No person may begin a flight in a rotorcraft under VFR conditions unless (considering wind and forecast weather conditions) there is enough fuel to fly to the first point of intended landing and, assuming normal cruising speed, to fly after that for at least 20 minutes.

### 5. William K. Pedersen Seeks Exemption From The Requirement Of Section 91.405(a).

Section 91.405, entitled *Maintenance required*, subsection (a), states the following:

Each owner or operator of an aircraft—

(a) Shall have that aircraft inspected as prescribed in subpart E of this part and shall between required inspections, except as provided in paragraph (c) of this section, have discrepancies repaired as prescribed in part 43 of this chapter[.]

# 6. William K. Pedersen Seeks Exemption From The Requirements Of Section 91.407(a)(1)

Section 91.407, entitled Operation after maintenance, preventive maintenance,

rebuilding, or alteration, subsection (a)(1), states the following:

- (a) No person may operate any aircraft that has undergone maintenance, preventive maintenance, rebuilding, or alteration unless--
  - (1) It has been approved for return to service by a person authorized under § 43.7 of this chapter[.]

#### 7. William K. Pedersen Seeks Exemption From The Requirements Of Sections

#### 91.409(a)(1) And 91.409(a)(2).

Section 91.409, entitled *Inspections*, subsection (a), states the following:

- (a) Except as provided in paragraph (c) of this section, no person may operate an aircraft unless, within the preceding 12 calendar months, it has had --
  - (1) An annual inspection in accordance with part 43 of this chapter and has been approved for return to service by a person authorized by § 43.7 of this chapter; or
  - (2) An inspection for the issuance of an airworthiness certificate in accordance with part 21 of this chapter.

### 8. William K. Pedersen Seeks Exemption From The Requirements Of Sections 91.417(a) And 91.417(b).

Section 91.417, entitled *Maintenance records*, subsections (a) and (b), state the following:

- (a) Except for work performed in accordance with §§ 91.411 and 91.413, each registered owner or operator shall keep the following records for the periods specified in paragraph (b) of this section:
  - (1) Records of the maintenance, preventive maintenance, and alteration and records of the 100-hour, annual, progressive, and other required or approved inspections, as appropriate, for each aircraft (including the airframe) and each engine, propeller, rotor, and appliance of an aircraft. The records must include--
    - (i) A description (or reference to data acceptable to the Administrator) of the work performed; and
    - (ii) The date of completion of the work performed; and
    - (iii) The signature, and certificate number of the person approving the aircraft for return to service.
- (2) Records containing the following information:
  - (i) The total time in service of the airframe, each engine, each propeller, and each rotor.
  - (ii) The current status of life-limited parts of each airframe, engine, propeller, rotor, and appliance.

- (iii) The time since last overhaul of all items installed on the aircraft which are required to be overhauled on a specified time basis.
- (iv) The current inspection status of the aircraft, including the time since the last inspection required by the inspection program under which the aircraft and its appliances are maintained.
- (v) The current status of applicable airworthiness directives (AD) and safety directives including, for each, the method of compliance, the AD or safety directive number and revision date. If the AD or safety directive involves recurring action, the time and date when the next action is required.
- (vi) Copies of the forms prescribed by § 43.9(d) of this chapter for each major alteration to the airframe and currently installed engines, rotors, propellers, and appliances.
- (b) The owner or operator shall retain the following records for the periods prescribed:
  - (1) The records specified in paragraph (a)(1) of this section shall be retained until the work is repeated or superseded by other work or for 1 year after the work is performed.
  - (2) The records specified in paragraph (a)(2) of this section shall be retained and transferred with the aircraft at the time the aircraft is sold.
  - (3) A list of defects furnished to a registered owner or operator under § 43.11 of this chapter shall be retained until the defects are repaired and the aircraft is approved for return to service.

### C. The Extent Of Relief William K. Pedersen Seeks And The Reason William K. Pedersen Seeks The Relief.

1. Extent Of Relief William K. Pedersen Seeks And The Reason William K. Pedersen Seeks Relief From Section 61.113(a) And (b).

Relief from Section 61.113(a) and (b) entitled *Private pilot privileges and limitations:*Pilot in command, is requested to the extent necessary to allow a PIC holding a private pilot or higher level certificate, as well as a current and valid airman medical certificate, and who has met certain flight-hour and currency requirements, to conduct the proposed UA flight operations for compensation or hire.

This relief is requested since the limitations set forth in Section 61.113(a) and (b) state that a private pilot may, for compensation or hire, act as PIC of an aircraft in connection with any business or employment if: (1) The flight is only incidental to that business or employment; and (2) The aircraft does not carry passengers or property for compensation or hire.

As set forth more fully below, William K. Pedersen submits that an equivalent level of safety will be maintained because no PIC will be allowed to operate the DJI Phantom2 UA unless that PIC has met certain flight-hour and currency requirements, demonstrating that the PIC is able to safely operate either the DJI Phantom2 UA in a manner consistent with the operations specifications as described in this exemption, including evasive and emergency maneuvers, as well as maintaining appropriate distances from people, vessels, vehicles and structures. Further, William K. Pedersen submits that all flights of the DJI Phantom2 UA, conducted by the PIC pursuant to the grant of this Petition: (1) will be incidental to William K. Pedersen's business; and (2) will not carry passengers or property for compensation or hire.

## 2. Extent Of Relief William K. Pedersen Seeks And The Reason William K. Pedersen Seeks Relief From Section 91.7(a).

Relief from Section 91.7(a) entitled *Civil aircraft airworthiness*, is requested to the extent required to allow William K. Pedersen to determine that the DJI Phantom2 and DJI S1000 UA Is in airworthy condition prior to every flight by ensuring that the UA is in compliance with the operating documents (i.e., the William K. Pedersen Aerial Operations Manual, Monthly Maintenance Log, and DJI Phantom2 UA Instruction Manual). William K. Pedersen seeks the requested relief because the DJI Phantom2 UA do not require an airworthiness certificate in accordance with 14

C.F.R. Part 21, Subpart H. Therefore, William K. Pedersen will ensure that the DJI Phantom2 UA Is in airworthy condition based upon its compliance with the operating documents (i.e., Monthly Maintenance Log, and DJI Phantom2 Instruction Manual) prior to every flight, and further, determine that the aircraft are in condition for safe flight, as stated in the conditions and limitations below.

### 3. Extent Of Relief William K. Pedersen Seeks And The Reason William K. Pedersen Seeks Relief From Section 91.121.

Relief from Section 91.121, entitled Altimeter settings, may be required to allow flight operations of the DJI Phantom2 UA, which utilize a barometric pressure sensor, GPS equipment, and a radio communications telemetry data link to downlink altitude information from the UA to the PIC at the ground control station (GCS). Since the FAA requires that any altitude information concerning UA operations be reported to air traffic control (ATC) in feet above ground level (AGL), William K. Pedersen seeks the requested relief because the DJI Phantom2UA's altimeter may be set on the ground to zero feet AGL, rather than the local barometric pressure or field altitude, before each flight.

Considering the limited altitude of the proposed operations, relief from 14 CFR 91.121 is sought to the extent necessary to comply with the applicable conditions and limitations stated below. As more fully set forth herein, an equivalent level of safety will be maintained since the DJI Phantom2 UA Is equipped with a barometric pressure sensor and GPS equipment, which automatically ensures that a ground level pressure setting will be established prior to each flight, and provides the PIC with altitude information of the UA on the heads-up display of the GCS.

4. Extent Of Relief William K. Pedersen Seeks And The Reason William K. Pedersen Seeks Relief From Section 91.151(b).

Relief from Section 91.151(b) entitled Fuel requirements for flight in VFR conditions, is requested to the extent required to allow flights of the battery powered DJI Phantom2 UA during daylight hours in visual meteorological conditions (VMC), under visual flight rules (VFR), for a total duration of 13.5 minutes to the first point of intended landing and, assuming normal cruising speed, to fly after that for at least 4.5 minutes. William K. Pedersen seeks the requested relief because without an exemption from Section 91.151(b), the flight time duration of the battery powered DJI Phantom2 UA will severely constrain the practicality of any aerial video or still photo flight operations that William K. Pedersen proposes to conduct pursuant to this Petition.

Significantly, as set forth below, the technical specifications of the DJI Phantom2 UA, the DJI Phantom2 operating documents, and William K. Pedersen's proposed operating limitations, ensure that William K. Pedersen will safely operate the battery powered DJI Phantom2 UA during daylight hours in visual meteorological conditions (VMC), under visual flight rules (VFR), with enough battery power to fly for a total duration of 13.5 minutes to the first point of intended landing and, assuming normal cruising speed, to fly after that for at least 4.5 minutes.

5. Extent Of Relief William K. Pedersen Seeks And The Reason William K. Pedersen Seeks Relief From Sections 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), And 91.417(a) & (b).

Since Sections 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), and 91.417(a) & (b) only apply to aircraft with an airworthiness certificate, William K. Pedersen requests relief from these Sections because the DJI Phantom2 UA do not require airworthiness certificates. As set forth more fully below, the DJI Phantom2 UA meet the conditions of FMRA Section 333 for operation without an airworthiness certificate. Accordingly, William K. Pedersen will use trained

technicians to perform maintenance, alterations, or preventive maintenance on the UA using the methods, techniques, and practices prescribed in the UA operating documents (i.e., the William K. Pedersen Aerial Operations Manual, Monthly Maintenance Log, and DJI Phantom2 Instruction Manual). Furthermore, William K. Pedersen will document and maintain all maintenance records for the DJI Phantom2 UA.

## D. The Reasons Why Granting William K. Pedersen Request Would Be In The Public Interest; That Is, How It Would Benefit The Public As A Whole.

Granting the present Petition will further the public interest by allowing William K. Pedersen to safely, efficiently, and economically perform aerial video and photography of construction sites, real estate, and landscape over certain areas of the United States.

Additionally, use of the DJI Phantom2 UA will decrease congestion of the NAS, reduce pollution, and provide significant benefits to the economy. Notably, the benefits of William K. Pedersen's proposed operation of the DJI Phantom2 UA will be realized without implicating any privacy issues.

#### 1. The Public Will Benefit From Decreased Congestion Of The NAS.

The DJI Phantom2 UA Is battery powered and serve as a safe, efficient, and economical alternative to the manned aircraft traditionally utilized to obtain aerial imagery. By reducing the amount of manned aircraft needed to perform aerial acquisitions, an exemption allowing the use of a DJI Phantom2 UA would reduce the amount of manned aircraft in the NAS, reduce noise and air pollution, as well as increase the safety of life and property in the air and on the ground.

Furthermore, by reducing the number of manned aircraft operating in the NAS, congestion around airports caused by arriving and departing aircraft will be reduced. The DJI Phantom2 UA do not require an airport to takeoff or land. Likewise, a reduction of manned aircraft conducting aerial video and photography missions would result in fewer aircraft that

must be handled by air traffic control during the ground, takeoff, departure, arrival, and landing phases of flight operations.

### 2. The Public Will Benefit From The Safety And Efficiency Of The DJI Phantom2 UA.

Conducting aerial acquisitions with the DJI Phantom2 UA, instead of manned aircraft, will greatly benefit the public by drastically reducing the levels of air and noise pollution generated during traditional aerial video and still photography flight operations. By using battery power and electric motors, the DJI Phantom2 UA produce no air pollution, and is the most viable environmentally conscious alternative to the cabin class, six cylinder internal combustion engine aircraft that are typically utilized for aerial video and photography, while burning approximately 20-30 gallons per hour of leaded aviation fuel. The DJI Phantom2 UA, while reducing the carbon footprint of aerial acquisitions, also eliminates noise pollution, as the UA Is propelled by battery powered electric motors, rather than an internal combustion engine.

By using the DJI Phantom2 UA to perform aerial acquisitions, the substantial risk to life and property in the air and on the ground, which is usually associated with traditional manned aircraft flight operations, will be substantially reduced or completely eliminated. Aside from the lack of flight crew members located onboard the aircraft, the DJI Phantom2 UA (weighing approximately 2 pounds 11 ounces and 9 pounds respectively, at their maximum gross weights with lengths of 16 inches and 41 inches respectively, widths of 16 inches and 41 inches respectively, and with no fuel on board), has less physical potential for collateral damage to life and property on the ground, and in the air, compared to the manned aircraft that typically conduct similar operations (weighing approximately 6,000 pounds with a wingspan of approximately 42 feet, a length of 34 feet, and a fuel capacity of 180 gallons) conduct similar operations (weighing

approximately 6,000 pounds with a wingspan of approximately 42 feet, a length of 34 feet, and a fuel capacity of 180 gallons).

### 3. Performing Aerial Video and Photography Operations With The DJI Phantom2 UA Will Benefit The Economy.

In addition to being safe and efficient, the DJI Phantom2 UA Is also an economical alternative to using manned aircraft to conduct similar aerial operations. As such, operation of the DJI Phantom2 UA will allow United States based companies, like William K. Pedersen, to remain competitive and contribute to growth of the U.S. economy. Specifically, with the rising cost of aviation fuel and the Environmental Protection Agency ("EPA") regulatory actions phasing out leaded aviation fuels, U.S. owned and operated companies must adopt new and alternative technology in order to remain competitive. Operating the battery powered DJI Phantom2 UA is one such technology that not only allows companies greater operational flexibility compared to manned aircraft, but provides such flexibility without the high operational cost of a traditional manned aircraft.

By operating the DJI Phantom2 UA, companies such as William K. Pedersen, can remain competitive and profitable, and therefore, provide greater job stability to employees and contractors, which will ultimately contribute to growth of the U.S. economy. Improved financial performance of U.S. companies, through commercial use of the DJI Phantom2 UA, provides a stable workforce that increases consumer spending; improves local, state, and federal tax revenues; and allows companies to invest in research and development in order to remain competitive both in the United States and abroad.

### 4. There Are No Privacy Issues.

Similar to the manned aerial acquisition flight operations that have been conducted for decades, William K. Pedersen's proposed operation of the DJI Phantom2 UA will not implicate any

privacy issues. Specifically, the DJI Phantom2 UA will be operated only in compliance with operating documents (i.e., the William K. Pedersen Aerial Operations Manual, Monthly Maintenance Log, and DJI Phantom2 Instruction Manual) which requires property owner involvement as well as local law enforcement notification, and in accordance with the Federal Aviation Regulations, including the minimum altitude requirements of 14 C.F.R. § 91.119.

- E. The Reasons Why Granting The Exemption Would Not Adversely Affect Safety, Or How The Exemption Would Provide A Level Of Safety At Least Equal To That Provided By The Rule From Which William K. Pedersen Seeks Exemption.
  - 1. Reasons Why The DJI Phantom2 UA Meet The Conditions Of The FAA Modernization and Reform Act of 2012 (FMRA) Section 333.

In consideration of the size, weight, speed, and limited operating area associated with the unmanned aircraft and its operation, William K. Pedersen's operation of the DJI Phantom2 UA meet the conditions of FMRA Section 333, and will not require an airworthiness certificate in accordance with 14 C.F.R. Part 21, Subpart H.

Section 333 provides authority for a UA to operate without airworthiness certification and sets forth requirements for considering whether a UA will create a hazard to users of the NAS or the public, or otherwise pose a threat to national security. Specifically, FMRA Section 333 states the following, in part:

- (a) In General.--Notwithstanding any other requirement of this subtitle, and not later than 180 days after the date of enactment of this Act, the Secretary of Transportation shall determine if certain unmanned aircraft systems may operate safely in the national airspace system before completion of the plan and rulemaking required by section 332 of this Act or the guidance required by section 334 of this Act.
- (b) Assessment of Unmanned Aircraft Systems.--In making the determination under subsection (a), the Secretary shall determine, at a minimum--
  - (1) which types of unmanned aircraft systems, if any, as a result of their size, weight, speed, operational capability, proximity to airports and populated areas, and operation within visual line of sight do not create a hazard to users

- of the national airspace system or the public or pose a threat to national security; and
- (2) whether a certificate of waiver, certificate of authorization, or airworthiness certification under section 44704 of title 49, United States Code, is required for the operation of unmanned aircraft systems identified under paragraph (1).
- (c) Requirements for Safe Operation.--If the Secretary determines under this section that certain unmanned aircraft systems may operate safely in the national airspace system, the Secretary shall establish requirements for the safe operation of such aircraft systems in the national airspace system.

In seeking this exemption, William K. Pedersen submits that the DJI Phantom2 UA can operate safely in the NAS pursuant to FMRA Section

333, as demonstrated by: (a) the characteristics of the DJI Phantom2 UA; (b) the pilot certification requirement; and (c) the specific operating limitations.

### a. The Specifications Of The DJI Phantom2 UA Demonstrate Its Safe Characteristics.

The DJI Phantom2 UA do not create a hazard to users of the NAS or the public, or otherwise pose a threat to national security considering its size, weight, speed, and operational capability.

#### i. Technical Specifications Of The DJI Phantom2 UA.

The technical specifications of the DJI Phantom2 UA Is set forth by the DJI Phantom2 Specifications and Data

Sheet, attached hereto as Exhibit A.

### ii. The DJI Phantom2 UA Autonomous Flight And Navigation Modes Enable The UA To Remain Within A Defined Operational Area.

The DJI Phantom2 UA may be operated in both manual and fully autonomous flight modes. A complete description of the flight and navigational modes of the DJI Phantom2 UA is provided at pages 25-30 of the DJI Phantom2 User Manual, attached hereto as Exhibit B.

### iii. The DJI Phantom2 UA Is Designed For Automatic Return To Home Point Or Hover In The Event Of Loss Of The Control Link Or Navigation.

When the Control Link is lost, the DJI Phantom2 UA will remain stationary, in flight, for 3 seconds or more. If, after 3 seconds, the DJI Phantom2 UA do not reacquire control link data from the GCS, the UA will assume that the Control Link is lost and the UA will return to the home position (i.e., failsafe mode) via GPS, and will descend to the takeoff position and shutdown.

A complete description of the Failsafe Functions of the DJI Phantom2 UA Is set forth at page 25 through 26 of the DJI Phantom2 User Manual, attached hereto as Exhibit B.

### iv. The DJI Phantom2 GCS And Its Operation.

A complete description of the operation and specifications of the DJI Phantom2 GCS and flight control software is provided at pages 28 through 33 of the DJI Phantom2 User Manual User Manual attached hereto as Exhibit B.

## b. Flight Operations Of DJI Phantom2 UA Is Limited To The Line Of Sight Of A Certificated Pilot in Command With A Safety Observer.

William K. Pedersen will only utilize certificated pilots who possess a current and valid airman medical certificate to act as a pilot in command (PIC) of the DJI Phantom2 UA.

Additionally, a safety observer will assist all pilots during flight time.

## c. Flights Of DJI Phantom2 UA Will Be Conducted Pursuant To Specific Operating Limitations.

In seeking this exemption, William K. Pedersen proposes to commercially operate DJI Phantom2 UA for the special purpose of conducting aerial video and photography over certain areas of United States, pursuant to the following specific operating limitations:

1. Operations authorized by this grant of exemption will be limited to the following aircraft described in the operating documents, rotorcraft UA weighing less than 55 pounds maximum gross weight: DJI Phantom2 Unmanned Aircraft Systems.

- Proposed operations of any other aircraft will require a new petition or a petition to amend this grant.
- 2. UA operations under this exemption will be limited to conducting operations for the purpose of aerial video and photography.
- 3. The UA may not be flown at an indicated airspeed exceeding 20 knots.
- 4. The UA must be operated at an altitude of no more than 200 feet above ground level (AGL), as indicated by the procedures specified in the operating documents unless a special request is made and approved by ATC. All altitudes reported to ATC must be in feet AGL.
- 5. The UA must be operated within visual line of sight (VLOS) of the PIC at all times. This requires the PIC to be able to use human vision unaided by any device other than corrective lenses, as specified on the PIC's FAA-issued airman medical certificate.
- 6. The use of first person view (FPV) by the PIC or safety observer (SO) is not permitted.
- 7. All operations must utilize a safety observer (SO). The SO may be used to satisfy the VLOS requirement as long as the PIC always maintains VLOS capability. The SO and PIC must be able to communicate verbally at all times. Electronic messaging or texting is not permitted during flight operations. The PIC must be designated before the flight and cannot transfer his or her designation for the duration of the flight. The PIC must ensure that the SO can perform the functions prescribed in the operating documents.
- 8. The SO must not perform any other duties beyond assisting the PIC with seeing and avoiding other air traffic and other ground based obstacles/obstructions and is not permitted to operate the camera or other instruments.
- 9. The operating documents and the grant of exemption must be accessible during UA operations and made available to the Administrator upon request. If a discrepancy exists between the conditions and limitations contained in the grant of exemption and the procedures outlined in the operating documents, the conditions and limitations contained in the grant of exemption take precedence and must be followed. Otherwise, the operator must follow the procedures as outlined in its operating documents. The operator may update or revise its operating documents. It is the operator's responsibility to track such revisions and present updated and revised documents to the Administrator upon request. The operator must also present updated and revised documents if it petitions for extension or amendment to the grant of exemption. If the operator determines that any update or revision would affect the basis upon which the FAA granted the exemption, then the operator must petition for amendment to its grant of exemption. The FAA's UA Integration Office (AFS-80)

- may be contacted if questions arise regarding updates or revisions to the operating documents.
- 10. Prior to each flight the PIC must inspect the UA to ensure that it is in a condition for safe flight. If the inspection reveals a condition that affects the safe operation of the UA, the aircraft is prohibited from operating until the necessary maintenance has been performed and the UA is found to be in a condition for safe flight. The Ground Control Station must be included in the preflight inspection. All maintenance and alterations must be properly documented in the aircraft records.
- 11. Any UA that has undergone maintenance or alterations that affect the UA operation or flight characteristics, e.g. replacement of a flight critical component, must undergo a functional test flight. The PIC who conducts the functional test flight must make an entry in the aircraft records.
- 12. The pre-flight inspection must account for all potential discrepancies, e.g. inoperable components, items, or equipment, not already covered in the relevant sections of the operating documents.
- 13. The operator must follow the UA manufacturer's aircraft/component, maintenance, overhaul, replacement, inspection, and life limit requirements.
- 14. The operator must carry out its maintenance, inspections, and record keeping requirements, in accordance with the operating documents. Maintenance, inspection, alterations, and status of replacement/overhaul component parts must be noted in the aircraft records, including total time in service, description of work accomplished, and the signature of the authorized person returning the UA to service.
- 15. Each UA operated under this exemption must comply with all manufacturer Safety Bulletins.
- 16. The authorized person must make an entry in the aircraft record of the corrective action taken against discrepancies discovered between inspections.
- 17. The PIC must possess at least a private pilot certificate and at least a current thirdclass medical certificate.
- 18. The operator may not permit any PIC to operate unless the PIC meets the operator's qualification criteria and demonstrates the ability to safely operate the UA in a manner consistent with how the UA will be operated under the exemption, including evasive and emergency maneuvers and maintaining appropriate distances from persons, vessels, vehicles and structures. PIC qualification flight hours must be logged in a manner consistent with 14 C.F.R. § 61.51(b). Flights for the purposes of training the operator's PICs are permitted under the terms of the exemption. However, training operations may only be conducted during dedicated training sessions. During training, proficiency, and experience-building flights, all persons not essential for flight operations are considered nonparticipants, and the PIC must

- operate the UA with appropriate distance from nonparticipants in accordance with 14 C.F.R. § 91.119.
- 19. UA operations may not be conducted during night, as defined in 14 C.F.R. §
  1.1. All operations must be conducted under visual meteorological conditions (VMC). If flight at night is required, a special request will be made at the FAA office closest to proposed area of operations. Flights under special visual flight rules (SVFR) are not authorized.
- 20. The UA may not operate within 5 nautical miles of an airport reference point as denoted on a current FAA-published aeronautical chart unless a letter of agreement with that airport's management is obtained, and the operation is conducted in accordance with a NOTAM as required by the operator's COA. The letter of agreement with the airport management must be made available to the Administrator upon request.
- 21. The UA may not be operated less than 200 feet below or less than 2,000 feet horizontally from a cloud or when visibility is less than 3 statute miles from the PIC.
- 22. If the UA loses communications or loses its GPS signal, it must return to a predetermined location within the planned operating area and land or be recovered in accordance with the operating documents.
- 23. The PIC must abort the flight in the event of unpredicted obstacles or emergencies in accordance with the operating documents.
- 24. The PIC is prohibited from beginning a flight unless (considering wind and forecast weather conditions) there is enough power to fly at normal cruising speed to the intended landing point and land the UA with 25% battery power remaining.
- 25. The operator must obtain an Air Traffic Organization (ATO) issued Certificate of Waiver or Authorization (COA) prior to conducting any operations under the grant of exemption. This COA will also require the operator to request a Notice to Airman (NOTAM) not more than 72 hours in advance, but not less than 48 hours prior to the operation. All operations shall be conducted in accordance with airspace requirements in the ATO issued COA including class of airspace, altitude level and potential transponder requirements.
- 26. All aircraft operated in accordance with the exemption must be identified by serial number, registered in accordance with 14 C.F.R. part 47, and have identification (N-Number) markings in accordance with 14 C.F.R. part 45, Subpart C. Markings must be as large as practicable.
- 27. Before conducting operations, the radio frequency spectrum used for operation and control of the UA must comply with the Federal Communications Commission (FCC) or other appropriate government oversight agency requirements.

- 28. The documents required fewer than 14 C.F.R. 91.9 and 91.203 must be available to the PIC at the Ground Control Station of the UA any time the UA is operating. These documents must be made available to the Administrator or any law enforcement official upon request.
- 29. The UA must remain clear and yield the right of way to all manned aviation operations and activities at all times.
- 30. The UA may not be operated by the PIC from any moving device or vehicle.
- 31. Flight operations must be conducted at least 500 feet from all nonparticipating persons (persons other than the PIC, SO, operator trainees or essential persons), vessels, vehicles, and structures unless:
  - a. Barriers or structures are present that sufficiently protect nonparticipating persons from the UA and/or debris in the event of an accident. The operator must ensure that nonparticipating persons remain under such protection. If a situation arises where nonparticipating persons leave such protection and are within 500 feet of the UA, flight operations must cease immediately and/or;
  - b. The aircraft is operated near vessels, vehicles or structures where the owner/controller of such vessels, vehicles or structures has granted permission and the PIC has made a safety assessment of the risk of operating closer to those objects and determined that it does not present an undue hazard, and;
  - c. Operations nearer to the PIC, SO, operator trainees or essential persons do not present an undue hazard to those persons per § 91.119(a).
- 32. All operations shall be conducted over private or controlled-access property with permission from the land owner/controller or authorized representative. Permission from land owner/controller or authorized representative will be obtained for each flight to be conducted.
- 33. Any incident, accident, or flight operation that transgresses the lateral or vertical boundaries of the operational area as defined by the applicable COA must be reported to the FAA's UA Integration Office (AFS-80) within 24 hours. Accidents must be reported to the National Transportation Safety Board (NTSB) per instructions contained on the NTSB Web site: www.ntsb.gov.
- 2. Reasons Why An Exemption From The Requirements Of Section 61.113(a) And (b) Would Not Adversely Affect Safety.

William K. Pedersen submits that the equivalent level of safety established by Section

61.113(a) and (b) will be maintained because no PIC will be allowed to operate the DJI

Phantom2 UA unless that PIC has demonstrated, by meeting minimum flight-hour and currency

requirements, that the PIC is able to safely operate the DJI Phantom2 UA in a manner consistent with the exemption, including evasive and emergency maneuvers and maintaining appropriate distances from people, vessels, vehicles and structures.

Considering William K. Pedersen's proposed area of operations, and the operating limitations set forth-above; the parallel nature of private pilot aeronautical knowledge requirements to those of commercial pilot requirements (See Exemption No. 11062); and the airmanship skills necessary to safely operate the DJI Phantom2 UA, William K. Pedersen submits that the additional manned airmanship experience of a commercially certificated pilot would not correlate to the airmanship skills necessary for William K. Pedersen's specific proposed flight operations.

The FAA has previously granted relief from Section 61.113(a) and (b) specific to UA, in circumstances similar, in all material respects, to those presented herein (e.g. Exemption Nos. 11062, 11063, 11064, 11065, 11066, 11067, 11080, 11109, 11110, 11112, 11136, 11138, 11150, 11153, 11156, 11158, 11159, 11160, 11161).

William K. Pedersen will not allow any PIC to operate the DJI Phantom2 UA unless that PIC has demonstrated, by meeting minimum flight-hour requirements or the DJI Phantom2 UA training and currency requirements, that the PIC is able to safely operate the DJI Phantom2 UA in a manner consistent with this exemption, including evasive and emergency maneuvers and maintaining appropriate distances from people, vessels, vehicles and structures.

Specifically, the PIC must have accumulated and logged, in a manner consistent with 14 C.F.R. § 61.51(b), 25 hours of total time as a UA rotorcraft pilot (with a minimum of 5 hours of those hours as a UA pilot operating the same make and model of UA to be used for operations

under the exemption). In addition to the hour requirements, the PIC must accomplish 3 takeoffs and landings in the preceding 90 days (for currency purposes).

As in Exemption Nos. 11062, 11138, and 11153, prior documented flight experience that was obtained in compliance with applicable regulations will ensure an equivalent level of safety during William K. Pedersen's proposed operations. The Administrator has held that prior documented flight experience that was obtained in compliance with applicable regulations would ensure safe operations, stating as follows:

In Exemption No. 11062, the FAA required that prior to conducting operations for the purpose of motion picture filming (or similar operations), the PIC must have accumulated and logged, in a manner consistent with 14 CFR 61.51(b), 25 hours of total time as a UA rotorcraft pilot including at least 10 hours logged as a UA pilot with a multi-rotor UA. Prior to operations under Exemption No. 11062, the PIC must also have accumulated and logged a minimum of 5 hours as a UA pilot operating the same make and model of UA to be used for operations under the exemption. For clarification, the FAA considers these minimum hour requirements to be inclusive rather than additive; i.e. 5 hours make and model time may be included in the 10 hours of multi-rotor time and the 10 hours may be included in the total 25 hours of UA rotorcraft time. In addition to the hour requirements, the PIC must accomplish 3 takeoffs and landings in the preceding 90 days (for currency purposes). The FAA finds that at a minimum, the flight-hour requirements in Exemption No. 11062 are appropriate to practice and build proficiency in the skills necessary to safely conduct the petitioner's proposed operations. The FAA also finds that prior documented flight experience that was obtained in compliance with applicable regulations would satisfy this requirement. Training, proficiency, and experiencebuilding flights can also be conducted under the grant of exemption to accomplish the required flight time. During training, proficiency, and experience-building flights the PIC is required to operate the UA with appropriate distances in accordance with 14 C.F.R 91.119.

Exemption No. 11138 at page 15.

Accordingly, William K. Pedersen will ensure safe operations by not allowing any PIC to operate the DJI Phantom2 UA unless that PIC has demonstrated, by meeting minimum flight-hour and currency requirements, that the PIC is able to safely operate the DJI Phantom2 UA in a

manner consistent with the exemption, including evasive and emergency maneuvers and maintaining appropriate distances from people, vessels, vehicles and structures.

# 3. Reasons Why An Exemption From The Requirements Of Section 91.7(a) Would Not Adversely Affect Safety.

The equivalent level of safety established by Section 91.7(a) will be maintained because prior to every flight, William K. Pedersen will ensure that the DJI Phantom2 UA is in an airworthy condition based upon the UA's compliance with its operating documents and as stated in the conditions and limitations herein.

Additionally, the FAA has previously granted relief from Section 91.7(a) specific to UA, in circumstances similar, in all material respects, to those presented herein (e.g. Exemption Nos. 11062, 11063, 11064, 11065, 11066, 11067, 11080, 11109, 11110, 11112, 11136, 11138, 11150, 11153, 11156, 11157, 11158, 11159, 11160, 11161).

# 4. Reasons Why An Exemption From The Requirements Of Section 91.121 Would Not Adversely Affect Safety.

The equivalent level of safety established by Section 91.121 will be maintained because the altitude information of the DJI Phantom2 UA will be provided to the PIC via GPS equipment and a radio communications telemetry data link, which downlinks from the UA to the GCS for active monitoring of the flight path and altitude. This altitude information, combined with William K. Pedersen's operation of the DJI Phantom2 UA within visual line of sight, at or below 200 feet AGL, will ensure a level of safety equivalent to Section 91.121. The altitude information will be generated by GPS equipment installed onboard the aircraft. Prior to each flight, a zero altitude initiation point is automatically established by the UA at ground level.

The FAA has previously granted relief from Section 91.121 specific to UA, in circumstances similar, in all material respects, to those presented herein (e.g. Exemption

Nos. 11062, 11063, 11064, 11065, 11066, 11067, 11080, 11109, 11112, 11136, 11138, 11150, 11153, 11156, 11157, 11158, 11159, 11160, 11161).

### 5. Reasons Why An Exemption From The Requirements Of Section 91.151(b) Would Not Adversely Affect Safety.

A grant of this exemption would ensure an equivalent level of safety established by 14 C.F.R. Section 91.151(b) as a result of (1) the technical specifications of the DJI Phantom2 UA; (2) the limitations on the proposed flight operations; and (3) the location of the proposed flight operations. Accordingly, William K. Pedersen will ensure that it will safely operate the battery powered DJI Phantom2 UA during daylight hours in VFR conditions, with enough battery power to fly for a total duration of 13.5 minutes to the first point of intended landing and, assuming normal cruising speed, to fly after that for at least 4.5 minutes.

Here, as in Exemption No. 11109, the technical specifications of the DJI Phantom2 UA; the limitations on the proposed flight operations; and the location of the proposed operations, will ensure an equivalent level of safety established by 14 C.F.R. Section 91.151(b). Furthermore, safety will be ensured as the DJI Phantom2 UA provide audible and visual warnings to the PIC at the GCS when the UA experiences low battery voltage, the first warning occurring at approximately 33% remaining battery power, and again at approximately 10% remaining battery power. At the critically low battery level, the DJI Phantom2 UA will descend and land automatically.

Significantly, previous exemptions granted by the FAA concerning Section 91.151 establish that safety is not adversely affected when the technical characteristics and operating limitations of the UA Is considered. Relief has been granted for manned aircraft to operate at less than the minimums prescribed in Section 91.151, including

Exemption Nos. 2689, 5745, and 10650. Moreover, the FAA has previously granted relief from Section 91.151 specific to UA, in circumstances similar, in all material respects, to those presented herein (e.g. Exemption Nos. 8811, 10808, 10673, 11042, 11062, 11063, 11064, 11065, 11066, 11067, 11080, 11109, 11110, 11136, 11138, 11150, 11153, 11156, 11157, 11158, 11159, 11160, 11161).

6. Reasons Why An Exemption From The Requirements Of Sections 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), And 91.417(a) & (b) Would Not Adversely Affect Safety.

In seeking this exemption, William K. Pedersen submits that the equivalent level of safety with regard to the regulatory maintenance and alteration requirements established by Sections 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), and 91.417(a) & (b) will be met because William K. Pedersen will use trained technicians to perform maintenance, alterations, or preventive maintenance on the UA using the methods, techniques, and practices prescribed in the operating documents (i.e., the William K. Pedersen Aerial Operations Manual, Monthly Maintenance Log, and DJI Phantom2 Instruction Manual). Furthermore, William K. Pedersen will document and maintain all maintenance records for the DJI Phantom2 UA.

Since the DJI Phantom2 UA will be inspected as prescribed by the operating documents, William K. Pedersen will maintain the equivalent level of safety established by Sections 91.405(a), 91.409(a)(1), and 91.409(a)(2). A copy of the DJI Phantom2 User Manual are attached hereto as Exhibit C and D; a copy of the DJI Phantom2 UA Maintenance LOG is attached hereto as Exhibit E.

Likewise, the exemption sought will not adversely affect safety because William K. Pedersen will use trained technicians to perform maintenance, alterations or preventive maintenance on the UA using the methods, techniques, and practices prescribed by the operating documents.

Furthermore, the exemption sought would maintain an equivalent level of safety established by Sections 91.407, 91.417(a) and 91.417(b), because all maintenance of the DJI Phantom2 UA will be performed by trained technicians.

Maintenance will be documented and maintained utilizing the monthly maintenance log.

Significantly, previous exemptions granted by the FAA concerning Sections 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), and 91.417(a) & (b) establish that safety is not adversely affected when the technical characteristics and operating limitations of the UA Is considered.

In consideration of William K. Pedersen's proposed operating limitations, the operating documents, and the technical aspects of the DJI Phantom2 UA, William K. Pedersen submits that safety will not be adversely affected by granting exemption from 14 C.F.R. Sections 91.405(a), 91.407(a)(1) and (a)(2), 91.409(a)(2), and 91.417(a) and (b). The FAA has previously granted relief specific to UA in circumstances similar, in all material respects, to those presented herein (e.g. Exemption Nos. 11062, 11063, 11064, 11065, 11066, 11067, 11080, 11109, 11110, 11112, 11136, 11138, 11150, 11153, 11156, 11157, 11158, 11159, 11160, 11161).

## 7. The FAA May Prescribe Any Other Conditions For Safe Operation.

In accordance with Section 333 of the FAA Modernization and Reform Act of 2012 (FMRA) and 14 C.F.R. § 21.16 entitled Special Conditions, William K. Pedersen requests that the FAA prescribe special conditions for the intended operation of the DJI Phantom2 UA, which contain such safety standards that the Administrator finds necessary to establish a level of safety equivalent to that established by

14 C.F.R. Part 21, Subpart H, and 14 C.F.R §§ 61.113(a) & (b), 91.7 (a), 91.121, 91.151(b), 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), and 91.417(a) & (b). Such special conditions will

permit safe operation of the UA for the limited purpose of conducting aerial video and photography over certain areas of the United States for compensation or hire. FMRA Section 333 sets forth the requirements for considering whether a UA will create a hazard to users of the NAS or the public, or otherwise pose a threat to national security; and further, provides the authority for such UA to operate without airworthiness certification in accordance with any requirements that must be established for the safe operation of the UA in the NAS.

Likewise, the Administrator may prescribe special conditions pursuant to 14 C.F.R. § 21.16, for operation of the DJI Phantom2 UA, since the airworthiness regulations of 14 C.F.R. Part 21 do not contain adequate or appropriate safety standards, due to the novel or unusual design features of the aircraft. Section 21.16, entitled Special Conditions, states the following:

If the FAA finds that the airworthiness regulations of this subchapter do not contain adequate or appropriate safety standards for an aircraft, aircraft engine, or propeller because of a novel or unusual design feature of the aircraft, aircraft engine or propeller, he prescribes special conditions and amendments thereto for the product. The special conditions are issued in accordance with Part 11 of this chapter and contain such safety standards for the aircraft, aircraft engine or propeller as the FAA finds necessary to establish a level of safety equivalent to that established in the regulations.

See 14 C.F.R. § 21.16.

Therefore, in accordance with FMRA Section 333 and 14 C.F.R. § 21.16, the FAA may prescribe special conditions for Icarus Group's intended operation of the DJI Phantom2 UA, which contain such safety standards that the Administrator finds necessary to establish a level of safety equivalent to that established by

14 C.F.R. Part 21, Subpart H, and 14 C.F.R Sections 61.113(a) & (b), 91.7(a), 91.121, 91.151(b), 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), and 91.417(a) & (b).

F. A Summary That Can Be Published In The Federal Register, stating: The Rules From Which William K. Pedersen Seeks Exemption:

William K. Pedersen seeks exemption from the requirements of 14 C.F.R Sections 61.113(a)&(b), 91.7(a), 91.121, 91.151(b), 91.405(a), 91.407(a)(1), 91.409(a)(1) & (a)(2), and 91.417(a) & (b).

## A Brief Description Of The Nature Of The Exemption William K. Pedersen Seeks:

This exemption will permit William K. Pedersen to commercially operate an Unmanned Aircraft System (UA) for the purpose of conducting aerial video and photography over certain areas of the United States.

# G. Any Additional Information, Views, Or Arguments Available To Support William K. Pedersen's Request.

This Petition is made pursuant to the FAA Modernization and Reform Act of 2012 (FMRA) Section 333, which directs the Secretary of Transportation to determine if certain UA may operate safely in the NAS. As such, William K. Pedersen's request for exemption may be granted pursuant to the authority of FMRA Section 333 and 14 C.F.R. Part 11, as set forth above.

FMRA Section 333 sets forth the requirements for considering whether a UA will create a hazard to users of the NAS or the public, or otherwise pose a threat to national security; and further, provides the authority for such UA to operate without airworthiness certification.

As discussed in detail above, William K. Pedersen will operate the DJI Phantom2 UA safely in the NAS, without creating a hazard to users of the NAS, or the public, or otherwise pose a threat to national security.

## **CONCLUSION**

As set forth herein, William K. Pedersen seeks an exemption pursuant to 14 C.F.R. §

11.61 and Section 333 of the FAA Modernization and Reform Act of 2012 (FMRA), which will permit safe operation of the DJI Phantom2 UA commercially, without an airworthiness certificate, for the limited purpose of conducting aerial video and photography over certain areas of the United States. By granting this

Petition, the FAA Administrator will be fulfilling the Congressional mandate of the FAA

Modernization and Reform Act of 2012, while also advancing the interests of the public, by

allowing William K. Pedersen to safely, efficiently, and economically operate the DJI Phantom2

UA commercially within the NAS.

WHEREFORE, in accordance with the Federal Aviation Regulations and the FAA

Modernization and Reform Act of 2012, Section 333, William K. Pedersen respectfully requests

that the Administrator grant this Petition for an exemption from the requirements of 14 C.F.R

Sections 61.113(a) & (b), 91.7(a), 91.121, 91.151(b), 91.405(a), 91.407(a)(1), 91.409(a)(1) &

(a)(2), and 91.417(a) & (b), and permit Icarus Group to operate the DJI Phantom2 UA

commercially for the purpose of conducting aerial video and photography over certain areas of

the United States. Dated: April 20, 2015

Respectfully submitted,

William K. Pedersen

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## Appendices:

- A DJI Phantom2 Specifications Data Sheet
- $B-DJI\ Phantom 2\ Manufacturer's\ User\ Manual$
- C Monthly Maintenance Log & Pilot Log

#### APPENDIX – A

## DJI PHANTOM2 TECHNICAL SPECIFICATIONS

William K. Pedersen only utilizes safe and reliable UA. DJI is an industry leader in small UA production. DJI UA Is loaded with ground breaking software enabling the user to set parameters which will not allow flight into controlled airspace. Parameters can also be set to limit flight to no higher than a predetermined and set altitude as well as limit flight to a predetermined and set distance. In addition, DJI software provides real-time altitude and location information to the PIC via the linked monitor (smart phone/tablet devices)

#### 1.1 DJI Phantom2

## 1.1.1 Aircraft

- 1.1.1.1 Supported Battery DJI 5200mAH, 11.1V LiPo Battery
- 1.1.1.2 Weight (Battery & Propellers Included) 2lbs 11.810oz (1242g)
- 1.1.1.3 Hover Accuracy (Ready to Fly) Vertical: .8m; Horizontal: 2.5m
- 1.1.1.4 Max Yaw Angular Velocity 200%
- 1.1.1.5 Max Tilt Angel 35°
- 1.1.1.6 Max Ascent Speed 6m/s
- 1.1.1.7 Max Descent Speed 2m/s
- 1.1.1.8 Max Flight Speed 15m/s (NOT RECOMMENDED)

#### **1.1.2** Gimbal

- 1.1.2.1 Working Current Static: 750mA; Dynamic: 900mA
- 1.1.2.2 Control Accuracy  $\pm 0.03^{\circ}$
- 1.1.2.3 Controllable Range Pitch: -90° 0°
- 1.1.2.4 Maximum Angular Speed Pitch: 90%

## 1.1.3 Camera

- 1.1.3.1 Operating Temperature Range 32°F 104°F (0°C 40°C)
- 1.1.3.2 Sensor Size 1/2.3"
- 1.1.3.3 Effective Pixels 14M
- 1.1.3.4 Resolution 4384x3288
- 4.1.3.5 HD Video Recording 1080p30 & 720p
- 4.1.3.6 Recording Field of View 110º/85º

## 1.1.4 Transmitter

- 1.1.4.1 Operating Frequency 2.4GHz ISM
- 1.1.4.2 Communication Distance (unobstructed) FCC Compliance: 1000m
- 1.1.4.3 Receiver Sensitivity (1%PER) -97dBm
- 1.1.4.4 Transmitter Power FCC Compliance: 100mW
- 1.1.4.5 Working Voltage 120mA@3.7V

## APPENDIX - B

## PHANTOM 2 User Manual VI.4

For PHANTOM 2 Flight Controller Firmware version V3.10 & PHANTOM 2 Assistant version V3.8 & PHANTOM RC Assistant version VI.1 2015.01

Congratulations on purchasing your new DJI product. Please thoroughly read the entire contents of this manual to fully use and understand the product.

It is advised that you regularly check the PHANTOM 2's product page at **www.dji.com** which is updated on a regular basis. This will provide services such as product information, technical updates and manual corrections. Due to any unforeseen changes or product upgrades, the information contained within this manual is subject to change without notice.

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If you have any questions or concerns regarding your product, please contact your dealer or DJI Customer Service.

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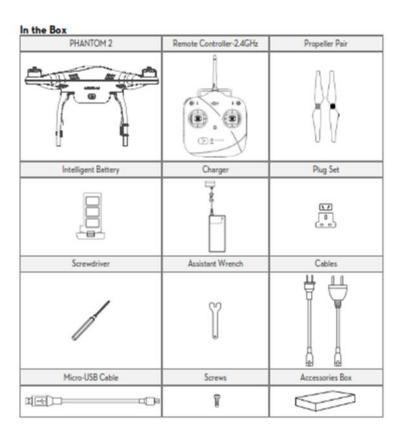
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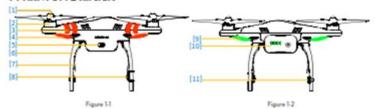
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## 1 PHANTOM 2 Aircraft



[I]Propeller [2]Motor [3]Front Side [4]Front LEDs [5]Micro-USB Port [6]Landing Gear [7]Receiver Antenna [8]CAN-Bus Connector [9]LED Flight Indicators [10]DJI Intelligent Bettery [11]Compass

#### 1.1 Built-in Flight Control System Instructions

The built-in flight control system is used to control the entire aircraft's functions in flight such as Pitch (forwards and backwards), Roll (left and right), Elevator (up and down) and Yaw (turn left or right). The flight controller contains the MC (Main Controller), IMU, GPS, compass, receiver.

The IMU (Inertial Measurement Unit) has a built-in inertial sensor and a barometric altimeter that measures both attitude and altitude. The compass reads geomagnetic information which assists the GPS (Global Position System) to accurately calculate the aircrafts position and height in order to lock the aircraft in a stable hover. The receiver is used to communicate with the remote controller and the MC acts as the brains of the complete flight control system connecting and controlling all the modules together.

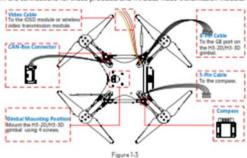


The PHANTOM 2 can be configured in the Assistant, by choosing Naza-M mode or Phantom 2 mode.

This manual is for Phantom 2 mode. Please refer to the Naza-M V2 Quick Start Manual for more information.

#### 1.2 Connections with Other DJI Products

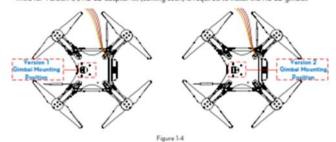
PHANTOM 2 is compatible with other DJI products, including ZENMUSE H3-2D and H3-3D gimbal, iOSD mini, iOSD Mark II. Below are connections for these products and wireless video transmission module.



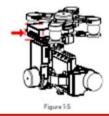
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#### Important Notes of Using with Other DJI Products

- The video cable can provide power for the wireless video transmission module with a battery voltage (ILIV-I2.6V) and a maximum current 2A.
- (2) Make sure the working current of the wireless video transmission module you connect can work with an operational voltage between ILIV-I2.6V and the total working current of the iOSD and wireless video transmission module is under 2A, as an overcurrent will damage the central board's components. If the total current exceeds 2A, please be sure to provide power supplied from a separate power source for the wireless video transmission module.
- (3) PHANTOM 2 uses a 2.4GHz RC system. To avoid communication interference, it's not recommended to use other 2.4GHz devices (including 2.4G Wi-Fi or 2.4G wireless video transmission module) except the 2.4G Bluetooth and 2.4G Datalink.
- (4) Be sure to keep the wireless video transmission module and other communicating devices away from the compass during installation and connection to avoid interference.
- (5) To improve the compatibility with ZENMUSE gimbals, the latest factory deliveries of PHANTOM 2 has updated to the Version 2 shown below. H3-2D/H3-3D gimbal can be directly installed for the Version 2 while for Version 1, a H3-3D adapter kit (coming soon) is required to install the H3-3D gimbal.



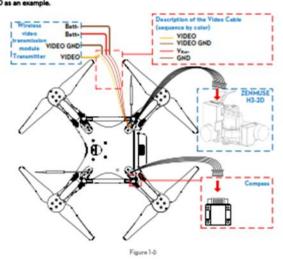
(6) When using the H3-3D gimbal, please connect the 8-Pin cable of PHANTOM 2 to the G8 port of H3-3D shown below.



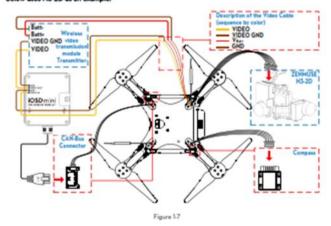
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## Connections with Other DJI Products

 Connecting the H3-2D and H3-3D gimbal and wireless video transmission module, the figure below uses H3-2D as an example.

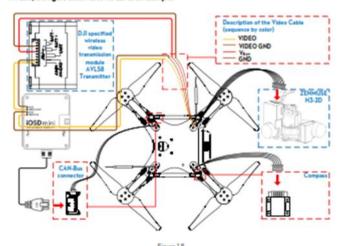


(2) Connecting the H3-2D and H3-3D gimbal, iOSD mini and wireless video transmission module, the figure below uses H3-2D as an example.



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(3) Connecting the H3-2D and H3-3D gimbal, IOSD mini and DJI specified wireless video transmission module AVL58, the figure below uses H3-2D as an example.



\*

We recommend connecting the  $Va_{NP}$ -port of the video cable to the two BATT+ ports of the AVL58 simultaneously. The same is true of the GND port of the video cable and two BATT- ports.

(4) Connecting the H3-2D and H3-3D gimbal, IOSD Mark II and wireless video transmission module, the figure below uses H3-2D as an example.

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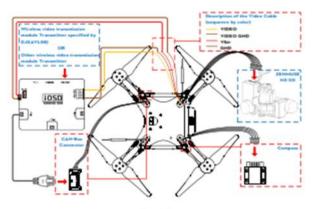
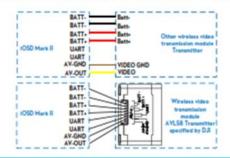


Figure 10

The diagram below illustrates the conneciton between the iOSD Mark II and the wireless video transmission module.

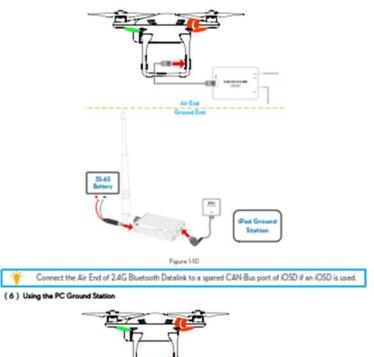


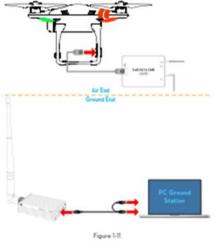


Use the 8-Pin cable in the iOSD Mark II package when connecting to the DJI specified wireless video transmission module AVL58.

## (5) Using the iPad Ground Station

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## 1.3 LED Flight Indicators Description

1. LED flight indicators are used to show the aircraft's current status. Once powered on, the indicators will light



Aircraft in Normal status	Descriptions
00000	Power On Self-Test
	Warming Up & Aircraft cannot take off during warming up
	Ready to Fly
00000	Ready to Fly (non-GPS)
Aircraft in abnormal status	Warnings and errors
000000	Remote Controller Signal Lost
••••	1" Level Low Battery Capacity Warning
•••••	2 <sup></sup> Level Low Battery Capacity Warning
•••	Not Stationary or Sensor Bias is too big
	Errors & Aircraft cannot fly.
••••	Compass data abnormal because of ferro-magnetic interference or the compass needs calibration.



- The LED indicators diagram above are for Phantom 2 mode. In Naza-M mode, LED indicators will work according to the Naza-M flight control system.
- (2) Connect to the PHANTOM 2 Assistant for detailed information about warnings and errors.
- The front LEDs are for indicating where the nose of the aircraft is. They light up solid red only after the motors have spooled up.



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## 1.4 Notes for PHANTOM 2 using with other DJI products

Before using PHANTOM 2 with other DJI products, users should connecting the products correctly and upgrade the firmware as requirements below.

Items to upgrade	Firmware versions required	Assistant for upgrading	Assistant version
P330CB (built-in central board)	VI.0.1.19 or above	PHANTOM 2	V1.08 or above
Zenmuse H3-2D	CMU VI.O , IMU VI.ó or above	PHANTOM 2	V1.08 or above
iOSD Mark II	V3.01 or above	iOSD	V4.0 or above
iOSD mini	V1.06 or above	iOSD	V4.0 or above

<sup>\*</sup>The iOSD Assistant is applied to both iOSD Mark II and iOSD mini.

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## 2 Propellers

PHANTOM 2 uses the original 9-inch propellers which are classified by the color of each central nut. Damaged propellers should be replaced by purchasing new ones if necessary.

Propellers	Grey Nut (9450)	Black Nut (9450 R)
Diagram		
Assembly Location	Attach to the motor thread that does not have a black dot.	Attach to the motor thread that has a black dot.
Fastening/Un-fastening Instructions	Lock: Tighten the propeller in th	is direction.

#### 2.1 Assembly

- 1. (Figure 2-1) Remove the four warning cards from the motors after you've read them.
- ( Figure 2-2 ) Prepare the two grey nut propellers and two black nut propellers. Make sure to match the black nut propellers with the correctly marked black dot motors. Tighten the propellers according to the fastening instructions.



## 2.2 Disassembly

( Figure 2-3 ) Keep the motor deadlocked in place with the assistant wrench (or one hand) and remove the propeller according to the un-fastening instructions.

#### 2.3 Notes

- 1. Propellers are self tightening during flight. DO NOT use any thread locker on the threads.
- 2. Make sure to match the propeller nut colors with the corresponding motors.
- 3. It is advised to wear protective gloves during propeller assembly and removal.
- 4. Check that the propellers and motors are installed correctly and firmly before every flight.
- Check that all propellers are in good condition before flight. DO NOT use any ageing, chipped, or broken propellers.
- 6. To avoid injury, STAND CLEAR of and DO NOT touch the propellers or motors when they are spinning.
- 7. ONLY use original DJI propellers for a better and safer flight experience.

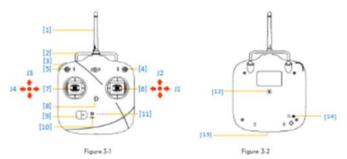
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#### **3 Remote Controller**

The PHANTOM 2 remote controller can be configured in the PHANTOM RC Assistant. The sticks mode is Mode 2 on delivery.



For upgraded remote controller (models: NDJ6 or NRC900), select "Upgrade Version" in Phantom Assistant. For basic remote controller (models: DJ6 or RC900), select "Basic Version" in Phantom Assistant.



[1]Antenna [2]Carrying Handle [3]Left Dial [4]3-Position Switch S1 [5]3-Position Switch S2 [6]Joystick](JI;J2) [7] Joystick 2(J3;J4) [8] Neck Strap Attachment [9] Power Switch [10] Power Indicator [11]Battery Level Indicators LEDI/LED2/LED3/LED4 (from left to right) [12]Trainer Port [13]Battery Charge & RC Assistant Port (micro-USB port) [14] Potentiometer

## 3.1 Power on the Remote Controller

- 1. Set the SI and S2 switches to the upper most position and ensure both joysticks are at the mid-point position. Then toggle on the power switch.
- 2. Push the power switch to the right to power on the remote controller. If the power LED indicator is solid on, the remote controller is functioning normally. The battery level indicators display the current battery level.



1. Please make sure the battery level of remote controller is enough. If the low voltage warning alert sounds (refer to «Remote Controller Power LED Indicator Status»), please recharge the battery as soon as possible.



- 2. Charge the remote controller's battery by using the included micro-USB cable. Using the incorrect type of charging cable may cause damage.
  - 3. Turn off the remote controller before charging. The power LED indicator will display solid red when charging is in progress. The LED indicators will display solid green when the battery is fully charged.

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## 3.2 Remote Controller LED Indicator Status

## 3.2.1 Remote Controller Power LED Indicator Status

Power LED Indicator	Sound	Remote Controller Status
	None	Functioning normally.
	None	Charging( remote controller is powered off)
	None	Remote controller joysticks calibration error, need to be re-calibrate.
	888888	Low voltage (from 3.5V-3.53V), recharge the remote controller.
•••••	B-B-B	Critical low voltage (from 3.45V-3.5V). Recharge the remote controller immediately.
••••	8-8-8	Alert will sound after 15 minutes of inactivity. It will stop once you start using the remote controller.

The remote controller will power off automatically when battery voltage drops below 3.45V. Land and recharge the battery as soon as possible when the low voltage alert occurs to avoid loss of control during flight.

## 3.2.2 Remote Controller Battery Level Indicator Status

The battery level indicators will show the current battery level during both the discharging process. The following is a description of the indicators.

: The LED is solid on

. The LED will blink regularly

The LED is light off

Discha	Discharging process				
LEDI	LED2	LED3	LED4	Current battery level	
				75%-100%	
				50w-75w	
				25%-50%	
				12.5%-25%	
•				0%-12.5%	
				-0%	

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#### 3.3 Antenna Orientation

The remote controller's antenna should point skywards without obstructions for maximum communication range during flight.



Figure 3-3

## 3.4 Remote Controller Operation

The operations of remote controller are based on mode 2 stick configuration.

## Definitions

The 'atick neutral' positions and 'atick released' mean the control sticks of the remote controller are placed at the central position.

To 'move the stick' means that the stick of remote controller is pushed away from the central position.

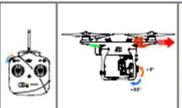
Slide Lever is used for the pitch control of the H3-2D and H3-3D gimbal.

Remote Controller (Mode 2)	Aircreft ( * nose direction )	Operation details
		The throttle stick controls aircraft altitude/elevation. Push the stick up and the aircraft will rise. Pull the stick down and the aircraft will descend. The aircraft will automatically hover and hold its altitude if the sticks are centered. Push the throttle stick above the centered (mid-point) position to make the aircraft take off. When flying, we suggest that you push the throttle stick slowly to prevent the aircraft from sudden and unexpected elevation changes.

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(a)		The yaw stick controls the aircraft rudder.  Push the stick left and the aircraft will rotate counter clock-wise.  Push the stick right and the aircraft will rotate clock-wise. If the stick is centered, the aircraft will remain facing the same direction.  The yaw stick controls the rotating angular velocity of the aircraft. Pushing the stick further away from center results in a faster aircraft rotation velocity.
		The pitch stick controls the aircraft 's front & back tilt. Push the stick up and the aircraft will tilt and fly forward. Pull the stick down and the aircraft will tilt and fly backward. The aircraft will keep level and straight if the stick is centered. Pushing or pulling the stick further away from center will result in a larger tilt angle (maximum of is 35') and faster flight velocity.
	- 1 -	The roll stick controls the aircraft 's left & right tilt.  Push the stick left and the aircraft will tilt and fly left.  Push the stick right and the aircraft will tilt and fly right.  The aircraft will keep level and straight if the stick is centered.  Pushing the stick further away from center will result in a larger tilt angle (maximum of 35") and faster flight velocity.
	Position-1 Position-2 Position-3	SI is for compass calibration. Toggle the SI switch from position-1 to position-3 and back to position-1 at least 5 times, which will force the aircraft to enter into compass calibration mode.  Users can configure position 3(bottom position) of the SI switch to trigger the Failsafe in the Assistant.
	OFF Course Lock Home	S2 is the IOC mode switch. IOC (Intelligent Orientation Control) function can be enabled in the Assistant when in Naza-M mode. Only use the IOC function after you are familiar with flying.

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The left dial controls the pitch of the H3-2D and H3-3D gimbal. The position of left dial determines the pitch angle relative to the horizontal level.

Turn the left dial to the right to make the gimbal pitch

Turn the left dial to the left to make the gimbal pitch down.

The gimbal will keep its current position if the dial is static.



- (1) For 'Ready to Fly' the aircraft will hover when all sticks are released.
- (2) For 'Ready to Fly (non-GPS)' the aircraft will only keep the altitude when all sticks are released.

## 3.5 Linking the Remote Controller & Built-in Receiver

PHANTOM 2 has a built-in receiver, the link button and indicator located on the bottom of the aircraft as illustrated in the Figure 3-4.

The link between the remote controller and aircraft is already established for you so you can initially skip this procedure. If you ever replace the remote controller, re-establishing the link is required.

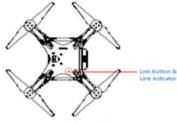


Figure 3-4

## Linking procedures

- 1. Power on the PHANTOM 2.
- 2. Turn on the remote controller and place it 0.5m-lm away from the aircraft.
- 3. Push the link button with a thin object and hold it until the Link indicator blinks red, then release it.
- When the Link indicator turns solid green, the link between the remote controller and the built-in receiver
  has been successfully established.

Link Indicator	Status  The remote controller is turned off and there is no 2.4GHz signal around, please turn on the remote controller.	
*****	The receiver is ready for linking.	
•••••	There is 2.4GHz signal around but the remote controller is not linked with the receive	

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please carry out the linking procedures.	
The remote controller is linked with the receiver successfully.	

## 4 Intelligent Battery

The intelligent battery is specially designed for the PHANTOM 2, with a battery capacity of 5200mAh, voltage of 11.1V and charge-discharge management functionality. The battery should only be charged with the DJI charger.



	Intelligent Batt	ery Charger
DJI In	telligent Battery Functions	
(1)	Balance Charging	Automatically balance the voltage of each battery cell during charging.
(2)	Capacity Display	Display the current battery level.
(3)	Communicating	The main controller communicates with the battery via communication port for battery voltage, capacity, current and other information.
(4)	Overcharging Protection	Charging stops automatically when the battery voltage reaches 12.8V to prevent overcharging damage.
(5)	Over Discharging Protection	Discharging stops automatically when the battery voltage reaches 8.4V to prevent over discharging damage.
(6)	Short Circuit Protection	Automatically cuts off the power supply when a short circuit is detected.
(7)	Sleep Protection	The battery will enter sleep mode after 10 minutes of inactivity to save power. The static current is 10nA in sleep mode when the battery is powered on without connecting to other devices.
(8)	Charging Temperature Detection	The battery will charge only when its temperature is within O°C-55°C. If the battery temperature is out of this range, the battery will stop charging.



- Before use, please read and follow the user manual, disclaimer, and the warnings on the battery.
   Users take full responsibility for all operations and usage.
- (2) The battery should only be charged with the charger provided by DJI. DJI does not take any responsibility for operation of any charger from a third party.

## 4.1 Charging Procedures

- 1. Connect the charger to a wall socket (Use the plug set if necessary).
- Connect the battery to the charger. If the current capacity of the battery is over 75%, you should power on the battery to begin charging.
- 3. The Battery Level indicators display current capacity level as the battery charges. Please refer to battery

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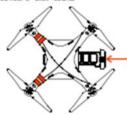
level indicator description for details.

The battery is fully charged when the Battery Level indicator lights are off. Please disconnect the charger
and battery when the charging is completed.



#### 4.2 Install the Battery

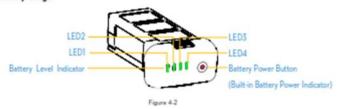
Push the battery into the battery compartment correctly as the following diagram shows. Make sure to push the battery into the compartment until you hear a 'click' sound.



 $\Lambda$ 

An incorrectly inserted battery may cause one of the following to occur: (1) Bad contact. (2) Unavailable battery information. (3) Unsafe for flight. (4) Unable to take off.

#### 4.3 Battery Usage



- (1) Checking the battery level. When the battery is powered off; pressing the battery power button once will indicate the current battery level. Refer to « Battery Level Indicator Description» for details.
- (2) Powering on: When the battery is powered off; press the battery power button once and then press and hold for 2 seconds to turn on the intelligent battery.
- (3) Powering offs. When the battery is powered on; press the battery power button once and then press and hold for 2 seconds to turn off the intelligent battery.

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(4) Checking the battery life. When the battery is powered off; press and hold the battery power button for 5 seconds to check the battery life. The battery level indicators will show the life and the battery power indicator will blink for 10 seconds, then all LEDs will light out and the intelligent battery will turn off. Refer to < Battery Level Indicator Description> for details.

More battery information is available in the battery tab of the PHANTOM 2 Assistant.

#### 4.4 Description of the Battery Level Indicator

The battery level indicators will show the current battery level during both the charging and discharging process as well as battery life. The following is a description of the indicators.

: The LED is solid on :

: The LED will blink regularly

: The LED is light off

Charg	Charging process			
LEDI	LED2	LED3	LED4	Current battery level
•				Ow-25%
•	•			25%-50%
•	•			50%-75%
•	•	•	•	75%-100%
				Full charged

Discha	rging pro	cess		
LEDI	LED2	LED3	LED4	Current battery level
				87.5%-100%
			•	75%-87.5%
				62.5%-75%
		•		50%-625%
				37.5%-50%
	•			25%-37.5%
				12.5%-25%
•				0%-12.5%
				-0%

Bettery life					
LEDI	DI LED2 LEDS I		LED4	Current bettery life	
				90%-100%	

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			•	80%-90%
				70%-80%
		•		60%-70%
				50%-60%
	•			40%-50%
				30%~40%
•				20%-30%
				Less than 20%

#### 4.5 Correct Battery Usage Notes

- 1. Never plug or unplug the battery into the aircraft when it is powered on.
- The battery should be charged in an environment that is between 0°C to 40°C, and be discharged in an
  environment that is between -20°C to 50°C. Both charging and discharging should be in an environment
  where the relative humidity is lower than 80%.
- 3. It's recommended to charge and discharge the battery thoroughly once every 20 charge/discharge cycles.
  Users should discharge the battery until there is less than 8% power left or until the battery can no longer be turned on. Users should then fully recharge the battery to maximum capacity. This power cycling procedure will ensure the battery is working at its optimal level.
- For long term storage please place the battery with only a 40-50% capacity in a strong battery box securely. We recommend discharging and charging the battery completely once every 3 months to keep it in good condition. The capacity should be varied in such a cycle (40%-50%)—0%—100%—(40%-50%).
- It's suggested you purchase a new battery after you have discharged your current battery over 300 times.Please completely discharge a battery prior to disposal.
- 6. It's suggested that you purchase a new battery if the current battery is swollen or damaged in any way.
- 7. Never try to recharge or fly with a battery that is swollen or damaged in any way.
- Never charge the battery unattended. Always charge the battery on a non-flammable surface such as concrete and never near any flammable materials.
- 9. Safety is extremely important and users can get more information in the DISCLAIMER.

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## 5 Calibrating the Compass

## IMPORTANT: Make sure to perform the Compass Calibration procedures prior to the first flight.

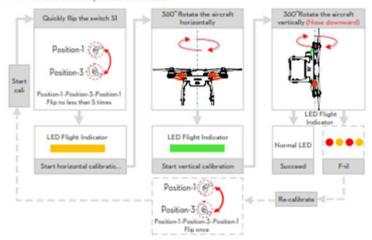
The compass is very sensitive to electromagnetic interference which causes abnormal compass data and leads to poor flight performance or even flight failure. Regular calibration of the compass enables the compass to perform at its optimal level.

## 5.1 Calibration Warnings

- (1) DO NOT calibrate your compass where there is a possibility for the existence of strong magnetic interference such as magnetite, parking structures, and steel reinforcement underground.
- (2) DO NOT carry ferromagnetic materials with you during calibration such as keys or cellular phones.
- (3) Compass Calibration is very important; otherwise the flight control system will work abnormally.

#### 5.2 Calibration Procedures

Please carry out the calibrating procedures in the flight field before flight. Please watch the quick start video of the PHANTOM 2 for more compass calibration details.



## 5.3 When Recalibration is required

- (1) When Compass Data is abnormal, the LED flight indicator will blink alternating between red and yellow.
- (2) Last compass calibration was performed at a completely different flying field/location.
- (3) The mechanical structure of the aircraft has changed, i.e. changed mounting position of the compass.
- (4) Evident drifting occurs in flight, i.e. the aircraft doesn't fly in straight lines.

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## 6 Flight

#### 6.1 Flying Environment Requirements

- (1) Before your first flight, please allow yourself some flight training (Using a flight simulator to practice flying, getting instruction from an experienced person, etc.).
- (2) DO NOT fly in bad weather, such as rain or wind (more than moderate breeze) or fog.
- (3) The flying field should be open and void of tall buildings or other obstacles; the steel structure within buildings may interfere with the compass.



- (4) Keep the aircraft away from obstacles, crowds, power lines, trees, lakes and rivers etc.
  - (5) Try to avoid interference between the remote controller and other wireless equipment (No base stations or cell towers around).
  - (6) The flight control system will not work properly at the South Pole or North Pole.
  - (7) Never use the aircraft in a manner that infringes upon or contravenes international or domestic lays and regulations.

## 6.2 Starting the Motors

A Combination Stick Command (CSC) is used to start the motors. Push the sticks according to one of the options below to start motors. Once the motors have started, release both sticks simultaneously. The same CSC is used to stop the motors.

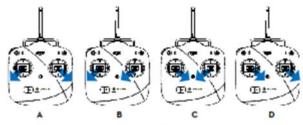


Figure 6-1

## 6.3 Takeoff/Landing Procedures

- 1. Start by placing the PHANTOM 2 on the ground with the battery level indicators facing you.
- 2. Turn on the remote controller.
- 3. Power on the aircraft by turning on the intelligent battery.
- 4. When LED flight indicator blinks green/yellow, the PHANTOM 2 is entering Ready to Fly/Ready to Fly (non-GPS) mode. Start the motors with the CSC command.
- 5. Push the throttle stick up slowly to lift the aircraft off the ground. Refer to «Remote Controller Operation»
- 6. Be sure you are hovering over a level surface. Pull down the throttle stick to descend. The stick will lock into

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place and the aircraft will descend steadily.

7. After landing, leave the throttle stick down for 3 to 5 seconds to stop the motors. Return throttle stick to middle position after the motors have stopped.



You SHOULD NOT execute the CSC during normal flight! This will stop the motors and cause the aircraft to descend rapidly and drop without any type of control.

- (1) When the LED flight indicator blinks yellow rapidly during flight, the aircraft has entered into Failsafe mode, refer to «Failsafe Function» for details.
- (2) A low battery capacity warning is indicated by the LED flight indicator blinking red slowly or rapidly during flight. Refer to the «Low Battery Capacity Warning Function» for details.
- (3) Watch the quick start video about flight for more flight information.



- 1 (4) Aircraft and battery performance is subject to environmental factors such as air density and temperature. Be very careful when flying 3000 meters (9800 feet) or more above sea level, as battery and aircraft performance may be reduced.
  - (5) When used with a H3-3D gimbal, a GoPro camera, and the iOSD mini, your Phantom 2 will be very close to its maximum takeoff weight. It is not recommended that you attach the Phantom 2 propeller guards at this weight. Otherwise, the aircraft will be unable to fly normally.

#### 6.4 Failsafe Function

The aircraft will enter Failsafe mode when the connection from the remote controller is lost. The flight control system will automatically control the aircraft to return to home and land to reduce injuries or damage. The following situations would make the aircraft fail to receive a signal from the remote controller and enter Failsafe mode:

- (1) The remote controller is powered off.
- (2) The remote controller is powered on but the SI is toggled in the position triggering the Failsafe (this must have been configured in the PHANTOM 2 Assistant).
- (3) The aircraft has flown out of the effective communication range of the remote controller.
- (4) There is an obstacle obstructing the signal between the remote controller and the aircraft, essentially reducing the distance the signal can travel.
- (5) There is interference causing a signal problem with the remote controller.

Failsafe works differently depending on the mode the aircraft is in when Failsafe mode is initiated whether it is in the Ready to Fly or Ready to Fly (non-GPS) mode.

#### Ready to Fly (non-GPS) --- Automatic landing

The flight control system will try to keep the aircraft level during descent and landing. Note that the aircraft may be drifting during the descent and landing process.

#### Reedy to Fly - Autometic go home and land

The flight control system will automatically control the aircraft to fly back to the home point and land.

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#### Home Point

When the aircraft is initializing the Ready to Fly status, the aircraft will record the current GPS coordinates as the home point. It is recommended to lift off only after Ready to Fly status is confirmed for the safety of being able to fly back to home point successfully in case the Failsafe mode is initiated.

#### Go Home Procedures

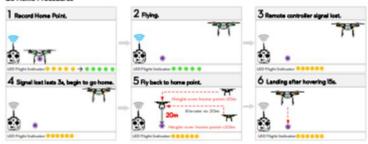


Figure 0-



- In a Failsafe situation, if less than 6 GPS satellites are found for more than 20 seconds, the aircraft will descend automatically.
- (2) When the aircraft is landing automatically, users can control the aircraft's position and altitude if the remote controller signal is recovered.

In Phantom 2 mode, users can set a new home point manually when the aircraft is in "Ready to fly" status as long as a home point has been recorded automatically. Quickly flipping the S2 switch of the remote controller from upper most to lower most positions 5 times or more will reset the current aircraft position as a new home point of PHANTOM 2. When successfully reset, you will see a series of rapid green blinks on the LED Flight Indicator. The definition of "home point" is:



- The home point is the place PHANTOM 2 returns to when the control signal is lost, which is recorded last time.
- (2) The home point is used to calculate the horizontal distance between you and the aircraft, the distance will be displayed as Du if using iOSD module.

## Regaining Control during Failsafe Procedure

Position of Switch S1	Position-1	Position-2	Position-3 (No triggering the Fallsefe)
How to regain control	When the SI switch is switched to Position-I, toggle the SI switch to any other position once to regain control. If remote controller's signal is recovered, control is returned back to the pilot.	Regain cont recovered.	rol as soon as signal is

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#### 6.5 Low Battery Capacity Warning Function

The low battery capacity warning alerts users when the battery is close to depletion during flight. When it appears, users should promptly fly back and land to avoid accidental damage. The PHANTOM 2 has two levels of low battery capacity warning. The first appears when the battery has less than 30% power and the second appears when it has less than 15% power.

- (1) When battery power drops below 30% and LED indicator will blink red slowly.
- (2) At lower than 15% the LED indicator will blink red rapidly, the PHANTOM 2 will also begin to descend and land automatically. After it has landed, keep the throttle stick at its lowest point or execute CSC.
- (3) There is a hidden third low battery threshold in addition to the 1st and 2nd level warnings. This uses 10.65V as its threshold. Both this voltage threshold and the 2nd Level Low Battery Warning will trigger auto-landing. Altitude can be maintained if necessary by pushing up on the throttle stick.
  - (1) Remember to fly your PHANTOM 2 back as soon as you see a low battery capacity warning.



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(2) Keeping the battery contact needles and pads clean is very important. Any dirt and dust may cause a communication failure.

#### 6.6 Flight Limits Function

All UAV (unmanned aerial vehicle) operators should abide by all regulations from such organizations at ICAO (International Civil Aviation Organization) and per country airspace regulations. For safety reasons, the flight limits function is enabled by default to help users use this product safely and legally. The flight limits function includes height, distance limits.

In Ready to Fly status, height, distance limits works together to restrict the flight. In Ready to Fly (non-GPS) status, only height limit works and the flying height restricted to be not over 120m.

- (1) The default parameters in the Assistant is compliant within the definitions of class G ruled by ICAO. (Refer to <u>Airsource Classification</u> to get more details). As each country has its own rules, make sure to configure the parameters to comply with these rules too, before using the PHANTOM 2.
- (2) Users in Mainland China can refer to 民用航空空域任用力法

#### Max Height & Radius Limits

The Max Height & Radius restricts the flying height and distance. Configuration can be done in the PHANTOM 2 Assistant. Once complete, your aircraft will fly in a restricted cylinder.

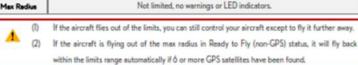
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Figure 0-3 Figure 0-4

Ready to Fly				
	Limits	Ground Station	Rear LED flight indicator	
Max Height	The flight height is restricted to fly under the max height.	Warning: Height limit reached.	None.	
Max Radius	The flight distance is restricted to fly within the max radius.	Warning: Distance limit reached.	Rapid red flashings ************************************	

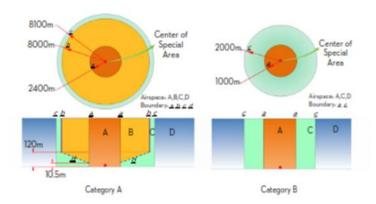
Ready to Fly(	non-GPS)		
	Flight Limits	Ground Station	Rear LED flight indicator
Max Height	The flight height is restricted to fly under the minor height between the Max height and 120m.		None.
Max Radius	Not limite	d, no warnings or LED indicators.	



## 6.7 Flight Limits of Special Areas

Special areas include airports worldwide. All special areas are listed on the DJI official website. Please refer to <a href="http://www.dji.com/fig-safe/category-mc">http://www.dji.com/fig-safe/category-mc</a> for details. These areas have been divided into category A and category B.

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Airspace	Limits	Rear LED Flight Indicato
A Orange	Motors will not start.	
	If the Phantom flies into a special area in Ready to Fly	1
	(non-GPS) mode and Ready to Fly mode activates, it will	
	automatically descend and land then stop its motors.	
В	If the Phantom flies into a special area in Ready to Fly	1
Yellow	(non-GPS) mode and Ready to Fly mode activates, it will	*****
	descend to airspace C and hover 5 meters below edge <u>d</u> .	•••••
	No restrictions of flight, but the Phantom will not enter	
С	Category A, the aircraft can fly free, but it will not enter	
	Airspace B through Boundary b & d.	
Green	Around Category B sites, the phantom can fly freely, but it will	
	not enter into Airspace A through Boundary a.	
D Blue	No restrictions.	None.

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- Semi-automatic descent: All stick commands are available except the throttle stick command during the descent and landing process. Motors will stop automatically after landing. Users will regain control once the motors have stopped. There is no need to toggle the S1 switch.
  - When flying in the airspace (A/B/C) of restricted special area, LED flight indicators will blink red equickly and continue for 3 seconds, then switch to indicate current flying status and continue for 5 seconds at which point it will switch back to red blinking.
  - (2) For safety reasons, please do not fly close to airports, highways, railway stations, railway lines, city centers and other special areas. Try to ensure the aircraft is visible.

#### 6.8 Conditions of Flight Limits

In different working modes and flight modes, flight limits will differ according to number of GPS satellites found. The following table demonstrates all the cases(vi available; × sunavailable).

All flights are restricted by height, distance and special areas simultaneously.

Phantom mode					
Flight Status	Limits of Special Area	Max Height	Max Radius		
Ready to Fly	<b>V</b>	<b>√</b>	<b>√</b>		
Ready to Fly (non-GPS)	×	¥	×		

Neze-M mode					
Control Mode	number of GPS found	Limits of Special Area	Max Height	Max Radius	
GPS	≥6	V	V	√	
	<6	×	<b>√</b>	×	
ATTI	≥6	V	V	×	
ATTI.	<6	×	V	×	
м .	≥6	×	×	×	
Manual	<6	×	×	×	

#### Disclaimer

Please ensure that you are kept up to date with International and Domestic airspace rules and regulations before using this product. By using this product, you hereby agree to this disclaimer and signify that you have read this fully. You agree that you are responsible for your own conduct and content while using this product, and for any direct or indirect consequences caused by not following this manual, violate or disregard any other applicable local laws, administrative rules and social habits thereof.

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## 7 Assistant Installation and Configuration

#### 7.1 Installing Driver and PHANTOM 2 Assistant

## Installing and running on Windows

- Download driver installer and Assistant installer in EXE format from the download page of PHANTOM 2
- 2. Connect the PHANTOM 2 to a PC via a Micro-USB cable.
- 3. Run the driver installer and follow the prompts to finish installation.
- 4. Next, run the Assistant installer and follow the prompts to finish installation.
- 5. Double click the PHANTOM 2 icon on your Windows desktop to launch the software.

⚠ The installer in EXE format only supports Windows operating systems (Win XP, Win7, Win8 (32 or 64)

## Installing and running on Mac OS X

- 1. Download the Assistant installer in DMG format from the download page of PHANTOM 2 on the DJI
- 2. Run the installer and follow the prompts to finish installation.

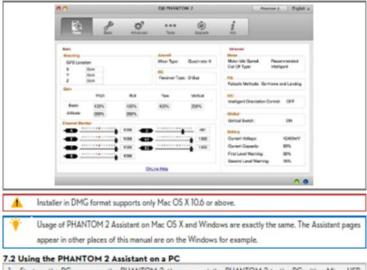


3. When launching for the first time if use Launchpad to run the PHANTOM 2 Assistant, Launchpad won't allow access because the software has not been reviewed by Mac App Store.



- 4. Locate the PHANTOM 2 icon in the Finder, press the Control key and then click the PHANTOM 2 icon (or right-click the PHANTOM 2 icon using a mouse). Choose Open from the shortcut menu, click open in the prompt dialog box and then software will launch.
- 5. After the first successful launch, directly launching of the software can be achieved by double-clicking the PHANTOM 2 icon in the Finder or using Launchped.

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- Start up the PC, power on the PHANTOM 2, then connect the PHANTOM 2 to the PC with a Micro-USB cable. DO NOT disconnect until configuration is finished.
- Run the PHANTOM 2 Assistant and wait for the PHANTOM 2 to connect to the Assistant. Observe the
  indicators 
   on the bottom of the screen. When connected successfully, the connection indicator is
  and communication indicator is blinking.
- 3. Choose [Basic] or [Advanced] configuration pages.
- 4. View and check the current configuration in the [View] page.



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- (1) Users should not enable the Naza-M function before finishing Advanced Flight Maneuvers procedure in the "PHANTOM Pilot Training Guide". If the Naza-M mode is enabled, users can switch the control mode between ATTI. Mode, GPS Mode or Manual Mode, and access the advanced settings (e.g. IOC). In addition, the LED located on the rear frame arms will display Naza-M flight status indications instead of the PHANTOM 2's indicators. Do not enable the Naza-M mode unless you are an experienced user or guided by a professional.
- (2) You can change to the Phantom 2 mode by clicking the same button used to turn on the Naza-M mode. This operation will disable the Naza-M mode and enable Phantom 2 mode. All parameters will be returned to factory settings.

## 7.3 Firmware upgrade of PHANTOM 2

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Please refer to the PHANTOM 2 Assistant to install driver and PHANTOM RC Assistant, and then follow the procedures below to upgrade the software and firmware; otherwise the PHANTOM 2 might not work properly.

- 1. An internet connection is required to upgrade PHANTOM 2's firmware.
- Click the [Upgrade] icon to check the current firmware version and whether the installed firmware is the latest version. If not, click the relative links to upgrade.
- Be sure to wait until the Assistant shows "finished". Click OK and power cycle the PHANTOM 2 after 5 seconds. Once completed, the firmware is up to date.



(1) DO NOT power off until the upgrade is finished.



(2) If the firmware upgrade failed, the main controller will enter a waiting for firmware upgrade status automatically. If this happens, repeat the above procedures.



Firmware upgradable items: (1) Main Controller (2) P330CB(Main Board) (3) Receiver (4) Gimbal CMU (5) Gimbal IMU (6) Battery

## 7.4 PHANTOM RC Assistant Description

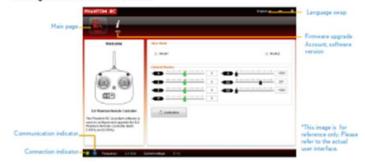
Please follow the procedures to finish the configuration of the remote controller.

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- 1. Turn off the remote controller and find the Micro-USB port on the bottom of it.
- Start up the PC, power on the remote controller, and then connect the remote controller to the PC with a Micro-USB cable. DO NOT disconnect until the configuration is finished.
- Run the PHANTOM RC Assistant and wait for the remote controller to connect to the Assistant. Observe
  the indicators • on the bottom left of the screen. When connected successfully, the connection
  indicator is on and communication indicator is blinking on.
- 4. Finish configuration in the [Main] page.
- 5. Finish upgrade in the [Info] page if necessary.



## Main Page of the 2.4GHz Remote Controller



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## 8 Appendix

8.1		

Aircraft		
Operating environment temperature	-10°C to 50°C	
Power consumption	5.6W	
Supported Bettery	DJI Intelligent bettery	
Weight (including the bettery)	1000g	
Take-off Weight	≤1300g	
Hovering Accuracy (Ready to Fly)	Vertical: 0.8m; Horizontal: 2.5m	
Max Yaw Angular Velocity	200°/s	
Max Tilt Angle	35*	
Max Ascent / Descent Speed	Ascent: ôm/s; Descent: 2m/s	
Max Flight Speed	15m/s (Not Recommended)	
Wheelbase	350mm	
2.4GHz Remote Controller		
Operating Frequency	2.4GHz ISM	
Communication Distance (open area)	1000m	
Receiver Sensitivity (1%PER)	-97dBm	
Working Current/Voltage	120 mA@3.7V	
Built-in LIPo Battery Working Current/Capacity	3.7V, 2000mAh	
DJI Intelligent Battery		
Туре	3S LiPo Battery	
Capacity	5200mAh, 11.1V	
Charging Environment Range	OrC to 40rC	
Discharging Environment Range	-20°C to 50°C	

8.2 LED Flight Indicators Description

Aircraft in Normal status	Descriptions
00000	Power On Self-Test
	Warming Up & Aircraft cannot take off during warming up
	Ready to Fly
	Ready to Fly (non-GPS)
Aircraft in abnormal status	Warnings and errors
000000	Remote Controller Signal Lost
••••	1" Level Low Battery Capacity Warning

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•••••	2 <sup>-st</sup> Level Low Battery Capacity Warning				
•••	Not Stationary or Sensor Bias is too big				
	Errors & Aircraft cannot fly."				
••••	Compass data abnormal because of ferro-magnetic interference or the compass needs calibration.				

<sup>\*</sup> Users can connect to the PHANTOM 2 Assistant to get detailed information about warnings and errors.

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## APPENDIX – C

## MONTHLY MAINTENANCE LOG

				month:( year:
UA\$#:\$	Date(Issue( Discovered	Date(Issue( Addressed	Issue (Description (& (Maintenance (Conducted	Maintenance(Performed(By:((( Print(&(Sign
Software(Updates				
Airframe(				
Engines				
Propellers				
Camera(Gimbal				
Landing(Gear				
Vibration(Dampening				
Other:				

## Pilot Log

DAIL	LIAV MAKE AND MODEI	UAV IDENTIFICATION	POINTS OF DEPARTURE & ARRIVAL		REMARKS, PROCEDURES, MANEUVERS, ENDORSEMENTS	NO. I DG	UAV CATEGORY & CLASS		CONDITIONS OF FI IGHT		TYPE OF PILOTING TIME		DURATION OF FLIGHT
			FROM	то			MULTI- ROTOR	FIXED	DAY	NIGHT	TRAINING	PIC	