U.S. Department
of Transportation
**Federal Aviation
Administration**

800 Independence Ave., S.W.
Washington, D.C. 20591

August 5, 2015

Exemption No. 12333
Regulatory Docket No. FAA–2015–2239

Mr. Austin Church
Vice President
Biological & Environmental Consulting LLC
PO Box 94435
Las Vegas, NV 89193

Dear Mr. Church:

This letter is to inform you that we have granted your request for exemption. It transmits our decision, explains its basis, and gives you the conditions and limitations of the exemption, including the date it ends.

By letter posted to the public docket on June 12, 2015, you petitioned the Federal Aviation Administration (FAA) on behalf of Biological & Environmental Consulting LLC (hereinafter petitioner or operator) for an exemption. The petitioner requested to operate an unmanned aircraft system (UAS) to conduct bird nesting surveys in cell towers to ensure telecom companies stay in compliance with the National Environmental Protection Act.

See Appendix A for the petition submitted to the FAA describing the proposed operations and the regulations that the petitioner seeks an exemption.

The FAA has determined that good cause exists for not publishing a summary of the petition in the Federal Register because the requested exemption would not set a precedent, and any delay in acting on this petition would be detrimental to the petitioner.

Airworthiness Certification

The UAS proposed by the petitioner is a DJI Phantom Vision 2+.

In accordance with the statutory criteria provided in Section 333 of Public Law 112−95 in reference to 49 U.S.C. § 44704, and in consideration of the size, weight, speed, and limited

operating area associated with the aircraft and its operation, the Secretary of Transportation has determined that this aircraft meets the conditions of Section 333. Therefore, the FAA finds that relief from 14 CFR part 21, *Certification procedures for products and parts, Subpart H—Airworthiness Certificates*, and any associated noise certification and testing requirements of part 36, is not necessary.

The Basis for Our Decision

You have requested to use a UAS for aerial data collection[1]. The FAA has issued grants of exemption in circumstances similar in all material respects to those presented in your petition. In Grants of Exemption Nos. 11062 to Astraeus Aerial (*see* Docket No. FAA−2014−0352), 11109 to Clayco, Inc. (*see* Docket No. FAA−2014−0507), 11112 to VDOS Global, LLC (*see* Docket No. FAA−2014−0382), and 11213 to Aeryon Labs, Inc. (*see* Docket No. FAA−2014−0642), the FAA found that the enhanced safety achieved using an unmanned aircraft (UA) with the specifications described by the petitioner and carrying no passengers or crew, rather than a manned aircraft of significantly greater proportions, carrying crew in addition to flammable fuel, gives the FAA good cause to find that the UAS operation enabled by this exemption is in the public interest.

Having reviewed your reasons for requesting an exemption, I find that—

- They are similar in all material respects to relief previously requested in Grant of Exemption Nos. 11062, 11109, 11112, and 11213;
- The reasons stated by the FAA for granting Exemption Nos. 11062, 11109, 11112, and 11213 also apply to the situation you present; and
- A grant of exemption is in the public interest.

Our Decision

In consideration of the foregoing, I find that a grant of exemption is in the public interest. Therefore, pursuant to the authority contained in 49 U.S.C. 106(f), 40113, and 44701, delegated to me by the Administrator, Biological & Environmental Consulting LLC is granted an exemption from 14 CFR §§ 61.23(a) and (c), 61.101(e)(4) and (5), 61.113(a), 61.315(a), 91.7(a), 91.119(c), 91.121, 91.151(a)(1), 91.405(a), 91.407(a)(1), 91.409(a)(1) and (2), and 91.417(a) and (b), to the extent necessary to allow the petitioner to operate a UAS to perform aerial data collection. This exemption is subject to the conditions and limitations listed below.

[1] Aerial data collection includes any remote sensing and measuring by an instrument(s) aboard the UA. Examples include imagery (photography, video, infrared, etc.), electronic measurement (precision surveying, RF analysis, etc.), chemical measurement (particulate measurement, etc.), or any other gathering of data by instruments aboard the UA.

Conditions and Limitations

In this grant of exemption, Biological & Environmental Consulting LLC is hereafter referred to as the operator.

Failure to comply with any of the conditions and limitations of this grant of exemption will be grounds for the immediate suspension or rescission of this exemption.

1. Operations authorized by this grant of exemption are limited to the DJI Phantom Vision 2+ when weighing less than 55 pounds including payload. Proposed operations of any other aircraft will require a new petition or a petition to amend this exemption.

2. Operations for the purpose of closed-set motion picture and television filming are not permitted.

3. The UA may not be operated at a speed exceeding 87 knots (100 miles per hour). The exemption holder may use either groundspeed or calibrated airspeed to determine compliance with the 87 knot speed restriction. In no case will the UA be operated at airspeeds greater than the maximum UA operating airspeed recommended by the aircraft manufacturer.

4. The UA must be operated at an altitude of no more than 400 feet above ground level (AGL). Altitude must be reported in feet AGL.

5. The UA must be operated within visual line of sight (VLOS) of the PIC at all times. This requires the PIC to be able to use human vision unaided by any device other than corrective lenses, as specified on the PIC's FAA-issued airman medical certificate or U.S. driver's license.

6. All operations must utilize a visual observer (VO). The UA must be operated within the visual line of sight (VLOS) of the PIC and VO at all times. The VO may be used to satisfy the VLOS requirement as long as the PIC always maintains VLOS capability. The VO and PIC must be able to communicate verbally at all times; electronic messaging or texting is not permitted during flight operations. The PIC must be designated before the flight and cannot transfer his or her designation for the duration of the flight. The PIC must ensure that the VO can perform the duties required of the VO.

7. This exemption and all documents needed to operate the UAS and conduct its operations in accordance with the conditions and limitations stated in this grant of exemption, are hereinafter referred to as the operating documents. The operating documents must be accessible during UAS operations and made available to the Administrator upon request. If a discrepancy exists between the conditions and

limitations in this exemption and the procedures outlined in the operating documents, the conditions and limitations herein take precedence and must be followed. Otherwise, the operator must follow the procedures as outlined in its operating documents. The operator may update or revise its operating documents. It is the operator's responsibility to track such revisions and present updated and revised documents to the Administrator or any law enforcement official upon request. The operator must also present updated and revised documents if it petitions for extension or amendment to this grant of exemption. If the operator determines that any update or revision would affect the basis upon which the FAA granted this exemption, then the operator must petition for an amendment to its grant of exemption. The FAA's UAS Integration Office (AFS−80) may be contacted if questions arise regarding updates or revisions to the operating documents.

8. Any UAS that has undergone maintenance or alterations that affect the UAS operation or flight characteristics, e.g., replacement of a flight critical component, must undergo a functional test flight prior to conducting further operations under this exemption. Functional test flights may only be conducted by a PIC with a VO and must remain at least 500 feet from other people. The functional test flight must be conducted in such a manner so as to not pose an undue hazard to persons and property.

9. The operator is responsible for maintaining and inspecting the UAS to ensure that it is in a condition for safe operation.

10. Prior to each flight, the PIC must conduct a pre-flight inspection and determine the UAS is in a condition for safe flight. The pre-flight inspection must account for all potential discrepancies, e.g., inoperable components, items, or equipment. If the inspection reveals a condition that affects the safe operation of the UAS, the aircraft is prohibited from operating until the necessary maintenance has been performed and the UAS is found to be in a condition for safe flight.

11. The operator must follow the UAS manufacturer's maintenance, overhaul, replacement, inspection, and life limit requirements for the aircraft and aircraft components.

12. Each UAS operated under this exemption must comply with all manufacturer safety bulletins.

13. Under this grant of exemption, a PIC must hold either an airline transport, commercial, private, recreational, or sport pilot certificate. The PIC must also hold a current FAA airman medical certificate or a valid U.S. driver's license issued by a state, the District of Columbia, Puerto Rico, a territory, a possession, or the Federal government. The PIC must also meet the flight review requirements specified in 14 CFR § 61.56 in an aircraft in which the PIC is rated on his or her pilot certificate.

14. The operator may not permit any PIC to operate unless the PIC demonstrates the ability to safely operate the UAS in a manner consistent with how the UAS will be operated under this exemption, including evasive and emergency maneuvers and maintaining appropriate distances from persons, vessels, vehicles and structures. PIC qualification flight hours and currency must be logged in a manner consistent with 14 CFR § 61.51(b). Flights for the purposes of training the operator's PICs and VOs (training, proficiency, and experience-building) and determining the PIC's ability to safely operate the UAS in a manner consistent with how the UAS will be operated under this exemption are permitted under the terms of this exemption. However, training operations may only be conducted during dedicated training sessions. During training, proficiency, and experience-building flights, all persons not essential for flight operations are considered nonparticipants, and the PIC must operate the UA with appropriate distance from nonparticipants in accordance with 14 CFR § 91.119.

15. UAS operations may not be conducted during night, as defined in 14 CFR § 1.1. All operations must be conducted under visual meteorological conditions (VMC). Flights under special visual flight rules (SVFR) are not authorized.

16. The UA may not operate within 5 nautical miles of an airport reference point (ARP) as denoted in the current FAA Airport/Facility Directory (AFD) or for airports not denoted with an ARP, the center of the airport symbol as denoted on the current FAA-published aeronautical chart, unless a letter of agreement with that airport's management is obtained or otherwise permitted by a COA issued to the exemption holder. The letter of agreement with the airport management must be made available to the Administrator or any law enforcement official upon request.

17. The UA may not be operated less than 500 feet below or less than 2,000 feet horizontally from a cloud or when visibility is less than 3 statute miles from the PIC.

18. If the UAS loses communications or loses its GPS signal, the UA must return to a pre-determined location within the private or controlled-access property.

19. The PIC must abort the flight in the event of unpredicted obstacles or emergencies.

20. The PIC is prohibited from beginning a flight unless (considering wind and forecast weather conditions) there is enough available power for the UA to conduct the intended operation and to operate after that for at least five minutes or with the reserve power recommended by the manufacturer if greater.

21. Air Traffic Organization (ATO) Certificate of Waiver or Authorization (COA). All operations shall be conducted in accordance with an ATO-issued COA. The exemption holder may apply for a new or amended COA if it intends to conduct operations that cannot be conducted under the terms of the attached COA.

22. All aircraft operated in accordance with this exemption must be identified by serial number, registered in accordance with 14 CFR part 47, and have identification (N−Number) markings in accordance with 14 CFR part 45, Subpart C. Markings must be as large as practicable.

23. Documents used by the operator to ensure the safe operation and flight of the UAS and any documents required under 14 CFR §§ 91.9 and 91.203 must be available to the PIC at the Ground Control Station of the UAS any time the aircraft is operating. These documents must be made available to the Administrator or any law enforcement official upon request.

24. The UA must remain clear and give way to all manned aviation operations and activities at all times.

25. The UAS may not be operated by the PIC from any moving device or vehicle.

26. All Flight operations must be conducted at least 500 feet from all nonparticipating persons, vessels, vehicles, and structures unless:
    a. Barriers or structures are present that sufficiently protect nonparticipating persons from the UA and/or debris in the event of an accident. The operator must ensure that nonparticipating persons remain under such protection. If a situation arises where nonparticipating persons leave such protection and are within 500 feet of the UA, flight operations must cease immediately in a manner ensuring the safety of nonparticipating persons; and
    b. The owner/controller of any vessels, vehicles or structures has granted permission for operating closer to those objects and the PIC has made a safety assessment of the risk of operating closer to those objects and determined that it does not present an undue hazard.

    The PIC, VO, operator trainees or essential persons are not considered nonparticipating persons under this exemption.

27. All operations shall be conducted over private or controlled-access property with permission from the property owner/controller or authorized representative. Permission from property owner/controller or authorized representative will be obtained for each flight to be conducted.

28. Any incident, accident, or flight operation that transgresses the lateral or vertical boundaries of the operational area as defined by the applicable COA must be reported to the FAA's UAS Integration Office (AFS−80) within 24 hours. Accidents must be reported to the National Transportation Safety Board (NTSB) per instructions contained on the NTSB Web site: www.ntsb.gov.

If this exemption permits operations for the purpose of closed-set motion picture and television filming and production, the following additional conditions and limitations apply.

29. The operator must have a motion picture and television operations manual (MPTOM) as documented in this grant of exemption.

30. At least 3 days before aerial filming, the operator of the UAS affected by this exemption must submit a written Plan of Activities to the local Flight Standards District Office (FSDO) with jurisdiction over the area of proposed filming. The 3-day notification may be waived with the concurrence of the FSDO. The plan of activities must include at least the following:
    a. Dates and times for all flights;
    b. Name and phone number of the operator for the UAS aerial filming conducted under this grant of exemption;
    c. Name and phone number of the person responsible for the on-scene operation of the UAS;
    d. Make, model, and serial or N−Number of UAS to be used;
    e. Name and certificate number of UAS PICs involved in the aerial filming;
    f. A statement that the operator has obtained permission from property owners and/or local officials to conduct the filming production event; the list of those who gave permission must be made available to the inspector upon request;
    g. Signature of exemption holder or representative; and
    h. A description of the flight activity, including maps or diagrams of any area, city, town, county, and/or state over which filming will be conducted and the altitudes essential to accomplish the operation.

31. Flight operations may be conducted closer than 500 feet from participating persons consenting to be involved and necessary for the filming production, as specified in the exemption holder's MPTOM.

Unless otherwise specified in this grant of exemption, the UAS, the UAS PIC, and the UAS operations must comply with all applicable parts of 14 CFR including, but not limited to, parts 45, 47, 61, and 91.

This exemption terminates on August 31, 2017, unless sooner superseded or rescinded.

Sincerely,

/s/
John S. Duncan
Director, Flight Standards Service

Enclosures

Petition for Section 333 Exemption

Biological & Environmental Consulting LLC
PO Box 94435
Las Vegas, NV 89193
Austin Church, Vice President
504-994-6662
abchurch@bioenvconsulting.com

Dear Sirs/Madams,

RE: Request for Exemption, Section 333 of the FAA Reform Act pertaining to Federal Aviation Regulations: 14 CFR 61.56(a)(1) and (2); 91.7(a); 91.119(c); 91.121; 91.151(a)(l) 91.405(a); 91.407(a)(l); 91.409(a)(l) and (2); 91.417(a) & (b)

In accordance with the guidelines for submitting a Petition for Exemption under Section 333 of the FAA Modernization and Reform Act of 2012, I, Austin Church, DBA Biological & Environmental Consulting LLC, hereafter referred as "Petitioner", respectfully submit my exemption request.

The Petitioner requests exemptions in order to legally operate Unmanned Aircraft Systems, the DJI Vision 2+ with integral camera system, in the National Airspace System for the purpose of commerce relating to performing bird nesting surveys in cell towers to ensure telecom companies stay in NEPA (National Environmental Protection Act) compliance. The Petitioner conveys the use of the DJI Phantom is more economical and safer than using manned aircraft for similar purposes and allows for a more accurate site assessment than ground only surveys. All flights will be conducted on secure, private property (unoccupied by other humans) and the UAS will remain within a maximum of 20 feet horizontally from the cell tower, will never exceed the tower height AGL and will never leave the foot print of the property horizontally.

Unmanned Aircraft System

DJI Phantom 2+ specifications

SUPPORTED BATTERY: DJI 5200mAh LiPo Battery

WIDTH: 350MM

LENGTH: 350MM

HEIGHT: 190MM

WEIGHT (BATTERY & PROPELLERS INCLUDED): 1242g

HOVER ACCURACY (READY TO FLY): Vertical: 0.8m; Horizontal: 2.5m

MAX YAW ANGULAR VELOCITY: 200°/s

MAX TILTABLE ANGLE: 35°

MAX ASCENT / DESCENT SPEED: Ascent: 6m/s; Descent: 2m/s

MAX FLIGHT SPEED: 15m/s (Not Recommended)

DIAGONAL MOTOR-MOTOR DISTANCE: 350mm

OPERATING FREQUENCY: 5.728 GHz－5.85 GHz

COMMUNICATION DISTANCE (OPEN AREA): CE Compliance: 400m; FCC Compliance: 800m

RECEIVER SENSITIVITY (1%PER): -93dBm

TRANSMITTER POWER: CE Compliance: 25mW; FCC Compliance: 100mW

WORKING VOLTAGE: 120 mA@3.7V

BUILT-IN LIPO BATTERY WORKING CURRENT/CAPACITY: 3.7V, 2000mAh

The petitioner shall reference prior exemptions: 1. January 6, 2015 to Douglas Trudeau, Exemption No. 11138, Regulatory Docket No. FAA-2014-0481. 2. Clayco Inc, Exemption No. 11109 and Joel A. Glastetter Exemption No. 11218 Regulatory Docket No. FAA−2014−0953

1. EXEMPTION REQUEST BY PART AND SUBPART OF THE FAA REGULATIONS. 14 CFR 61.56(a)(l) and (2)(c)(l) and (2)

FLIGHT REVIEW:
(a) Consists of 1 hour flight training and 1 hour of ground training.
(1) Review of current general operating and flight rules of this chapter.
(2) Review of those maneuvers and procedures that are necessary for the pilot to demonstrate the safe exercise of the privileges of the pilot certificate.
(c) No person may act as pilot in command of an aircraft unless, since the beginning of the 24th calender month before the month in which that pilot acts as pilot in command, that person has-
(1) Accomplished a flight review given in an aircraft for which that pilot is rated by an authorized instructor; and
(2) A logbook endorsement from an authorized instructor who gave the review certifying that the person has satisfactorily completed the review.

PETITION FOR EXEMPTION

The petitioner, a FAA certified pilot, is aware through previous training, curriculum and aeronautical training the necessity of Federal Aviation Regulations pertinent for safe operations in the National Airspace System. With reference given to Exemption 11138, the petitioner believes he is in compliance with the "two reasons" set forth regarding Pilot in Command of the UAS. First, the petitioner meets the statutory requirement by holding an airman certificate, as prescribed in 49 USC 44 711. Second, as a certificated airman, the petitioner meets the requirements established by the Department of Homeland Security for security screening. It is the position of the petitioner that a flight review, as outlined above, does not pertain to the use of a UAS, and is not applicable in this instance.

14 CFR 91.7(a)

Civil Aircraft Airworthiness:
(a) No person may operate a civil aircraft unless it is in an airworthy condition
Based on the exemption No. 11138, the petitioner requests an exemption from 14 CFR 91.7(a).The FAA has determined this make and model does not require an airworthiness certificate. The petitioner, pilot in command, will ensure airworthiness through the combined use and application of the company Operations Manual, Flight Log/Preflight and Maintenance Form.

14 CFR 91.119(c)

Minimum Safe Altitudes:(c) Over other than congested areas. An altitude of 500 feet above the surface, except over open water or sparsely populated areas. In those cases, the aircraft may not be operated closer than 500 feet to any person, vessel, vehicle or structure.

Based on the exemption No. 11138 and 11109, the petitioner requests an exemption from 14 CFR 91.119(c). The petitioner request consistent relief as granted in those exemptions. The petitioner will adhere to policy and practices that the UAS will be flown on/above secured, unoccupied private property only and that the UAS has a fail safe mode that allows it to return to the origin of flight automatically if the radio transmitter signal is lost.

14 CFR 91.121

Altimeter Settings:
Based on the exemption granted, No. 11138, the petitioner requests an exemption from 14 CFR 91.121. The petitioner, UAS, does not incorporate a barometric altimeter, but instead, GPS derived altitude capabilities. The petitioner will limit flights to a maximum altitude of 400 feet above ground level (AGL), with any altitude reports to ATC in AGL.

14 CFR 91.151(a)(l)

Fuel requirements for flight in VFR conditions:(a) No person may begin a flight in an airplane under VFR conditions unless (considering wind and forecast weather conditions) there is enough fuel to fly to the first point of intended landing and, assuming normal cruising speed-
(1) During the day, to fly after that for at least
30 minutes.

The petitioner, requests relief consistent with exemption No. 11138. The petitioner will be utilizing the same make and model of UAS.

14 CFR 91.405(a)

Maintenance required: Each owner or operator of an aircraft-

(a) Shall have that aircraft inspected as prescribed in Subpart E of this part and shall between required inspections, except as provided in paragraph (c) of this section, have discrepancies repaired as prescribed in part 43 of this chapter.
The petitioner, pilot in command, shall inspect the aircraft prior to every flight. Reference given to the Flight Log/Preflight and Maintenance Form in the Operations Manual. The petitioner requests an exemption similar to Exemption No. 11138.

14 CFR 91.407(a)(l)

Operation after maintenance, preventive maintenance, rebuilding, or alteration.

(a) No person may operate any aircraft that has undergone maintenance, preventive maintenance, rebuilding, or alteration unless-

(1)It has been approved for returned to service by a person authorized under 43.7 of this chapter

The petitioner, pilot in command, who has final authority and responsibility for the operation and safety of the UAS flight, shall insure through the use of protocols and procedures listed in the Maintenance Form, Operations Manual, proper maintenance and subsequent approval for return to service. The petitioner requests an exemption, reference Exemption No. 11138.

14 CFR 91.409(a)(l) and (2)

Inspections:

(a) Except as provided in paragraph (c) of this section, no person may operate an aircraft unless, within the preceding 12 calendar months, it has had-

(1) An annual inspection in accordance with part 43 of this chapter and has been approved for return to service by a person authorized by 43.7 of this chapter; or

(2) An inspection for the issuance of an airworthiness certificate in accordance with part 21 of this chapter.

No inspection performed under paragraph (b) of this section may be substituted for any inspection required by this paragraph unless it is performed by a person authorized to perform annual inspections and is entered as an "annual" inspection in the required maintenance records

.

The petitioner, in accordance with the Operations Manual will ensure that the UAS is in a condition for safe flight. The petitioner requests exemption from 14 CFR 91.409 (a)(l) and (2). Reference given to Exemption No.lll38.

14 CFR 91.417(a) and (b)

Maintenance Records: (a) Except for work performed in accordance with 91.411 and 91.413, each registered owner or operator shall keep the following records (l)(i) (ii)(iii) (2)(i)(ii)(iii)(iv)(v)(vi) for the periods specified in paragraph (b) of this section: (1)(2)(3)The petitioner, through the use of diligent record keeping as outlined in the Operations Manual and Maintenance Form will adhere to 14 CFR 91.417(a) and (b) in accordance and relation to the operation of a UAS. The petitioner request an exemption based on variables associated with the operation of a UAS in the NAS, similar to Exemption No. 11138.

2. RELIEF REQUEST FROM AIRPORT PROXIMITY AND LIMITATIONS

The Petitioner, a certificated pilot, understands the concerns associated with the operation of UAS aircraft in the vicinity of airports. Some of our clients cell towers are located less than 5 miles from airports. Said towers are all FAA approved and are referenced on FAA approved aeronautical charts. The Petitioner, will operate the UAS with safety and common sense directives and adhere to the following criteria:

1. The UAS will be operated on secured, private property only.
2. The UAS, while in flight will remain a maximum of 20 feet horizontally from the structure.
3. The UAS, while in flight, will not exceed the height of the structure.
4. The airport tower will be notified prior to any surveys being conducted
5. The UAS has fail safe mode to ensure that it returns to the origin of flight if the transmitter signal is lost.

Based on these flight parameter restrictions, all structures referenced on aeronautical charts, making the airport tower aware of our activities and the fail safe mode of the UAS, I feel we should be able to conduct surveys within 5 miles or less of an airport.

3. PUBLIC INTEREST

The public interest is safety. The Petitioner through the use of the exemption process contained in Section 333, requests safe and legal entry into the NAS. The public will benefit wholeheartedly knowing the national airspace is operated in an organized manner with open dialog. Through this process, illegal operations will be minimized and legal commerce will thrive. The full benefits of this new facet of Aviation is yet to be realized.

PHANTOM 2+ Flight Manual V1.4

For PHANTOM 2 Flight Controller Firmware version V3.10

& PHANTOM 2 Assistant version V3.8

& PHANTOM RC Assistant version V1.1

2015.01

Congratulations on purchasing your new DJI product. Please thoroughly read the entire contents of this manual to fully use and understand the product.

It is advised that you regularly check the PHANTOM 2's product page at www.dji.com which is updated on a regular basis. This will provide services such as product information, technical updates and manual corrections. Due to any unforeseen changes or product upgrades, the information contained within this manual is subject to change without notice.

If you have any questions or concerns regarding your product, please contact your dealer or DJI Customer Service.

Content

In the Box

PHANTOM 2 Remote Controller-2.4GHz Propeller Pair

Intelligent Battery Charger Plug Set

Screwdriver Assistant Wrench Cables

Micro-USB Cable Screws Accessories Box

Legend

Forbidden(Important)

Caution

Tip

Reference

1 PHANTOM 2 Aircraft

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Figure 1-1 Figure 1-2

[1]Propeller [2]Motor [3]Front Side [4]Front LEDs [5]Micro-USB Port [6]Landing Gear [7]Receiver Antenna [8]CAN-Bus Connector [9]LED Flight Indicators [10]DJI Intelligent Battery [11]Compass

1.1 Built-in Flight Control System Instructions

The built-in flight control system is used to control the entire aircraft's functions in flight such as Pitch (forwards and backwards), Roll (left and right), Elevator (up and down) and Yaw (turn left or right). The flight controller contains the MC (Main Controller), IMU, GPS, compass, receiver.

The IMU (Inertial Measurement Unit) has a built-in inertial sensor and a barometric altimeter that measures both attitude and altitude. The compass reads geomagnetic information which assists the GPS (Global Position System) to accurately calculate the aircrafts position and height in order to lock the aircraft in a stable hover. The receiver is used to communicate with the remote controller and the MC acts as the brains of the complete flight control system connecting and controlling all the modules together.

The PHANTOM 2 can be configured in the Assistant, by choosing Naza-M mode or Phantom 2 mode.

This manual is for Phantom 2 mode. Please refer to the Naza-M V2 Quick Start Manual for more information.

1.2 Connections with Other DJI Products

PHANTOM 2 is compatible with other DJI products, including ZENMUSE H3-2D and H3-3D gimbal，iOSD mini，iOSD Mark II. Below are connections for these products and wireless video transmission module.

Compass
Gimbal Mounting Position
Mount the H3-2D/H3-3D gimbal using 4 screws.
CAN-Bus Connector
Video Cable
To the iOSD module or wireless video transmission module.
8-Pin Cable
To the G8 port on the H3-2D/H3-3D gimbal.
5-Pin Cable
To the compass.

Figure 1-3

Important Notes of Using with Other DJI Products

（1）The video cable can provide power for the wireless video transmission module with a battery voltage (11.1V~12.6V) and a maximum current 2A.

（2）Make sure the working current of the wireless video transmission module you connect can work with an operational voltage between 11.1V~12.6V and the total working current of the iOSD and wireless video transmission module is under 2A, as an overcurrent will damage the central board's components. If the total current exceeds 2A, please be sure to provide power supplied from a separate power source for the wireless video transmission module.

（3）PHANTOM 2 uses a 2.4GHz RC system. To avoid communication interference, it's not recommended to use other 2.4GHz devices (including 2.4G Wi-Fi or 2.4G wireless video transmission module) except the 2.4G Bluetooth and 2.4G Datalink.

（4）Be sure to keep the wireless video transmission module and other communicating devices away from the compass during installation and connection to avoid interference.

（5）To improve the compatibility with ZENMUSE gimbals, the latest factory deliveries of PHANTOM 2 has updated to the Version 2 shown below. H3-2D/H3-3D gimbal can be directly installed for the Version 2 while for Version 1, a H3-3D adapter kit (coming soon) is required to install the H3-3D gimbal.

Version 1
Gimbal Mounting Position
Version 2
Gimbal Mounting Position

Figure 1-4

（6）When using the H3-3D gimbal, please connect the 8-Pin cable of PHANTOM 2 to the G8 port of H3-3D shown below.

Figure 1-5

Connections with Other DJI Products

（1）Connecting the H3-2D and H3-3D gimbal and wireless video transmission module, the figure below uses H3-2D as an example.

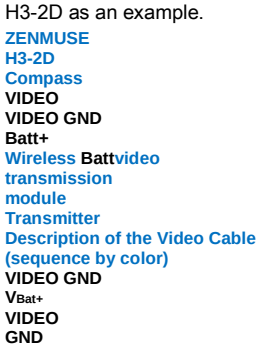


Figure 1-6

（2）Connecting the H3-2D and H3-3D gimbal, iOSD mini and wireless video transmission module, the figure below uses H3-2D as an example.

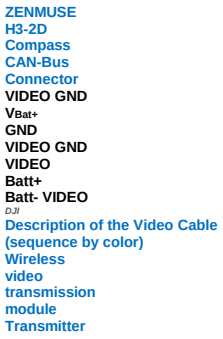


Figure 1-7

（3）Connecting the H3-2D and H3-3D gimbal, iOSD mini and DJI specified wireless video transmission module AVL58, the figure below uses H3-2D as an example.

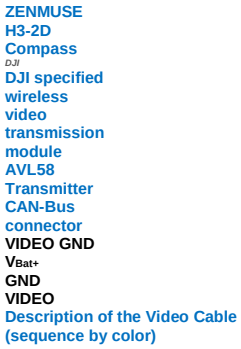
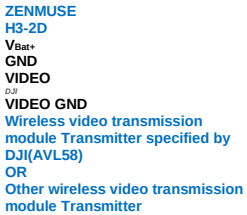


Figure 1-8

We recommend connecting the V_{Bat+} port of the video cable to the two BATT+ ports of the AVL58 simultaneously. The same is true of the GND port of the video cable and two BATT- ports.

（4）Connecting the H3-2D and H3-3D gimbal, iOSD Mark II and wireless video transmission module, the figure below uses H3-2D as an example.



CAN-Bus
Connector
Compass
Description of the Video Cable
(sequence by color)

Figure 1-9

The diagram below illustrates the conneciton between the iOSD Mark II and the wireless video transmission module.

iOSD Mark II
Other wireless video
transmission module
Transmitter
VIDEO GND
VIDEO
BATT- Batt-
BATTBATT+
BATT+
UART
UART
AV-OUT
AV-GND
Batt-
Batt+
Batt+
Wireless video
transmission
module
AVL58 Transmitter
specified by DJI
iOSD Mark II
AV-OUT
AV-GND
BATTBATTBATT+
BATT+
UART
UART

Use the 8-Pin cable in the iOSD Mark II package when connecting to the DJI specified wireless video transmission module AVL58.

（5）Using the iPad Ground Station

iPad Ground
Station
+ -
3S-6S
Battery
Air End
Ground End

Figure 1-10

Connect the Air End of 2.4G Bluetooth Datalink to a spared CAN-Bus port of iOSD if an iOSD is used.

（6）Using the PC Ground Station

Air End
Ground End
PC Ground
Station

Figure 1-11

1.3 LED Flight Indicators Description

1. LED flight indicators are used to show the aircraft's current status. Once powered on, the indicators will light up.

LED flight
indicators

Aircraft in Normal status Descriptions

Power On Self-Test

Warming Up & Aircraft cannot take off during warming up

Ready to Fly

Ready to Fly (non-GPS)

Aircraft in abnormal status Warnings and errors

Remote Controller Signal Lost

1st Level Low Battery Capacity Warning

2nd Level Low Battery Capacity Warning

Not Stationary or Sensor Bias is too big

Errors & Aircraft cannot fly.

Compass data abnormal because of ferro-magnetic interference or
the compass needs calibration.
（1） The LED indicators diagram above are for Phantom 2 mode. In Naza-M mode, LED indicators
will work according to the Naza-M flight control system.
（2） Connect to the PHANTOM 2 Assistant for detailed information about warnings and errors.
2. The front LEDs are for indicating where the nose of the aircraft is. They light up solid red only after the motors
have spooled up.
The front
LEDs

1.4 Notes for PHANTOM 2 using with other DJI products

Before using PHANTOM 2 with other DJI products, users should connecting the products correctly and upgrade
the firmware as requirements below .

Items to upgrade	Firmware versions required	Assistant for upgrading	Assistant version
P330CB (built-in central board)	V1.0.1.19 or above	PHANTOM 2	V1.08 or above
Zenmuse H3-2D	CMU V1.0，IMU V1.6 or above	PHANTOM 2	V1.08 or above
iOSD Mark II	V3.01 or above	iOSD	V4.0 or above
iOSD mini	V1.06 or above	iOSD	V4.0 or above

*The iOSD Assistant is applied to both iOSD Mark II and iOSD mini.

2 Propellers

PHANTOM 2 uses the original 9-inch propellers which are classified by the color of each central nut. Damaged
propellers should be replaced by purchasing new ones if necessary.

Propellers	Grey Nut (9450)	Black Nut (9450 R)
Diagram		
Assembly Location	Attach to the motor thread that does not have a black dot.	Attach to the motor thread that has a black dot.
Fastening/Un-fastening Instructions	Lock: Tighten the propeller in this direction.	Unlock: Remove the propeller in this direction.

2.1 Assembly

1. （Figure 2-1）Remove the four warning cards from the motors after you've read them.
2. （Figure 2-2）Prepare the two grey nut propellers and two black nut propellers. Make sure to match the
black nut propellers with the correctly marked black dot motors. Tighten the propellers according to the
fastening instructions.

Figure 2-1 Figure 2-2 Figure2-3

2.2 Disassembly

（Figure 2-3）Keep the motor deadlocked in place with the assistant wrench (or one hand) and remove the
propeller according to the un-fastening instructions.

2.3 Notes

1. Propellers are self tightening during flight. DO NOT use any thread locker on the threads.
2. Make sure to match the propeller nut colors with the corresponding motors.
3. It is advised to wear protective gloves during propeller assembly and removal.
4. Check that the propellers and motors are installed correctly and firmly before every flight.
5. Check that all propellers are in good condition before flight. DO NOT use any ageing, chipped, or broken

propellers.

6. To avoid injury, STAND CLEAR of and DO NOT touch the propellers or motors when they are spinning.

7. ONLY use original DJI propellers for a better and safer flight experience.

3 Remote Controller

The PHANTOM 2 remote controller can be configured in the PHANTOM RC Assistant. The sticks mode is Mode 2 on delivery.

For upgraded remote controller (models: NDJ6 or NRC900), select “Upgrade Version” in Phantom Assistant.

For basic remote controller (models: DJ6 or RC900), select “Basic Version” in Phantom Assistant.

[1]
[2]
[5] [4]
[9]
[10]
J2
J1
J3
J4 [7]
[8]
[6]
[3]
[11]
[12]
[13]
[14]

Figure 3-1 Figure 3-2

[1]Antenna [2]Carrying Handle [3]Left Dial [4]3-Position Switch S1 [5]3-Position Switch S2 [6]Joystick1(J1;J2) [7]Joystick2(J3;J4) [8]Neck Strap Attachment [9]Power Switch [10]Power Indicator [11]Battery Level Indicators LED1/LED2/LED3/LED4 (from left to right) [12]Trainer Port [13]Battery Charge & RC Assistant Port (micro-USB port) [14] Potentiometer

3.1 Power on the Remote Controller

1. Set the S1 and S2 switches to the upper most position and ensure both joysticks are at the mid-point position. Then toggle on the power switch.

2. Push the power switch to the right to power on the remote controller. If the power LED indicator is solid on, the remote controller is functioning normally. The battery level indicators display the current battery level.

1. Please make sure the battery level of remote controller is enough. If the low voltage warning alert sounds (refer to <Remote Controller Power LED Indicator Status>), please recharge the battery as soon as possible.

2. Charge the remote controller’s battery by using the included micro-USB cable. Using the incorrect type of charging cable may cause damage.

3. Turn off the remote controller before charging. The power LED indicator will display solid red when charging is in progress. The LED indicators will display solid green when the battery is fully charged.

3.2 Remote Controller LED Indicator Status

3.2.1 Remote Controller Power LED Indicator Status

Power LED Indicator	Sound	Remote Controller Status
None		Functioning normally.
None		Charging(remote controller is powered off)
None		Remote controller joysticks calibration error, need to be re-calibrate.
BB---BB---BB		Low voltage (from 3.5V-3.53V), recharge the remote controller.
B-B-B……		Critical low voltage (from 3.45V-3.5V). Recharge the remote controller immediately.

B--B--B……

Alert will sound after 15 minutes of inactivity. It will stop once you start using the remote controller.

The remote controller will power off automatically when battery voltage drops below 3.45V. Land and recharge the battery as soon as possible when the low voltage alert occurs to avoid loss of control during flight.

3.2.2 Remote Controller Battery Level Indicator Status

The battery level indicators will show the current battery level during both the discharging process. The following is a description of the indicators.

: The LED is solid on : The LED will blink regularly

: The LED is light off

Discharging process

LED1 LED2 LED3 LED4 Current battery level

75%~100%

50%~75%

25%~50%

12.5%~25%

0%~12.5%

<0%

3.3 Antenna Orientation

The remote controller's antenna should point skywards without obstructions for maximum communication range during flight.

Figure 3-3

3.4 Remote Controller Operation

The operations of remote controller are based on mode 2 stick configuration.

Definitions

The 'stick neutral' positions and 'stick released' mean the control sticks of the remote controller are placed at the central position.

To 'move the stick' means that the stick of remote controller is pushed away from the central position.

Slide Lever is used for the pitch control of the H3-2D and H3-3D gimbal.

Remote

Controller

(Mode 2)

Aircraft

（ nose direction ）

Operation details

The throttle stick controls aircraft altitude/elevation.

Push the stick up and the aircraft will rise.

Pull the stick down and the aircraft will descend.

The aircraft will automatically hover and hold its altitude if the sticks are centered.

Push the throttle stick above the centered (mid-point) position to make the aircraft take off. When flying, we suggest that you push the throttle stick slowly to prevent the aircraft from sudden and unexpected elevation changes.

The yaw stick controls the aircraft rudder.

Push the stick left and the aircraft will rotate counter clock-wise.
Push the stick right and the aircraft will rotate clock-wise. If the stick is centered, the aircraft will remain facing the same direction.
The yaw stick controls the rotating angular velocity of the aircraft. Pushing the stick further away from center results in a faster aircraft rotation velocity.
The pitch stick controls the aircraft's front & back tilt.
Push the stick up and the aircraft will tilt and fly forward.
Pull the stick down and the aircraft will tilt and fly backward. The aircraft will keep level and straight if the stick is centered.
Pushing or pulling the stick further away from center will result in a larger tilt angle (maximum of is 35˚) and faster flight velocity.
The roll stick controls the aircraft's left & right tilt.
Push the stick left and the aircraft will tilt and fly left.
Push the stick right and the aircraft will tilt and fly right.
The aircraft will keep level and straight if the stick is centered.
Pushing the stick further away from center will result in a larger tilt angle (maximum of 35˚) and faster flight velocity.
Position-1 Position-2 Position-3
S1 is for compass calibration. Toggle the S1 switch from position-1 to position-3 and back to position-1 at least 5 times, which will force the aircraft to enter into compass calibration mode.
Users can configure position 3(bottom position) of the S1 switch to trigger the Failsafe in the Assistant.
OFF Course Lock Home
point Lock
S2 is the IOC mode switch. IOC (Intelligent Orientation Control) function can be enabled in the Assistant when in Naza-M mode. Only use the IOC function after you are familiar with flying.

The left dial controls the pitch of the H3-2D and H3-3D gimbal. The position of left dial determines the pitch angle relative to the horizontal level.
Turn the left dial to the right to make the gimbal pitch up.
Turn the left dial to the left to make the gimbal pitch down.
The gimbal will keep its current position if the dial is static.
（1） For 'Ready to Fly' the aircraft will hover when all sticks are released.

（2） For ‘Ready to Fly (non-GPS)’ the aircraft will only keep the altitude when all sticks are released.

3.5 Linking the Remote Controller & Built-in Receiver

PHANTOM 2 has a built-in receiver, the link button and indicator located on the bottom of the aircraft as illustrated in the Figure 3-4.

The link between the remote controller and aircraft is already established for you so you can initially skip this procedure. If you ever replace the remote controller, re-establishing the link is required.

Figure 3-4

Linking procedures

1. Power on the PHANTOM 2.
2. Turn on the remote controller and place it 0.5m~1m away from the aircraft.
3. Push the link button with a thin object and hold it until the Link indicator blinks red, then release it.
4. When the Link indicator turns solid green, the link between the remote controller and the built-in receiver has been successfully established.

Link Indicator Status

The remote controller is turned off and there is no 2.4GHz signal around, please turn on the remote controller.

The receiver is ready for linking.

There is 2.4GHz signal around but the remote controller is not linked with the receiver, please carry out the linking procedures.

The remote controller is linked with the receiver successfully.

4 Intelligent Battery

The intelligent battery is specially designed for the PHANTOM 2, with a battery capacity of 5200mAh, voltage of 11.1V and charge-discharge management functionality. The battery should only be charged with the DJI charger.

Intelligent Battery Charger

DJI Intelligent Battery Functions

（1） Balance Charging Automatically balance the voltage of each battery cell during charging.

（2） Capacity Display Display the current battery level.

（3） Communicating

The main controller communicates with the battery via communication ports for battery voltage, capacity, current and other information.

（4） Overcharging Protection

Charging stops automatically when the battery voltage reaches 12.8V to prevent overcharging damage.

（5） Over Discharging Protection

Discharging stops automatically when the battery voltage reaches 8.4V to prevent over discharging damage.

（6） Short Circuit Protection Automatically cuts off the power supply when a short circuit is detected.

（7） Sleep Protection

The battery will enter sleep mode after 10 minutes of inactivity to save power. The static current is 10nA in sleep mode when the battery is powered on without connecting to other devices.

（8） Charging Temperature Detection

The battery will charge only when its temperature is within 0℃~55℃. If the battery temperature is out of this range, the battery will stop charging.

（1） Before use, please read and follow the user manual, disclaimer, and the warnings on the battery.

Users take full responsibility for all operations and usage.

（2） The battery should only be charged with the charger provided by DJI. DJI does not take any responsibility for operation of any charger from a third party.

4.1 Charging Procedures

1. Connect the charger to a wall socket (Use the plug set if necessary).

2. Connect the battery to the charger. If the current capacity of the battery is over 75%, you should power on the battery to begin charging.

3. The Battery Level indicators display current capacity level as the battery charges. Please refer to battery

level indicator description for details.

4. The battery is fully charged when the Battery Level indicator lights are off. Please disconnect the charger and battery when the charging is completed.

Wall Socket

4.2 Install the Battery

Push the battery into the battery compartment correctly as the following diagram shows. Make sure to push the battery into the compartment until you hear a ‘click’ sound.

Figure 4-1

An incorrectly inserted battery may cause one of the following to occur: (1) Bad contact. (2) Unavailable battery information. (3) Unsafe for flight. (4) Unable to take off.

4.3 Battery Usage

Figure 4-2

(1) Checking the battery level: When the battery is powered off; pressing the battery power button once will indicate the current battery level. Refer to < Battery Level Indicator Description> for details.

(2) Powering on: When the battery is powered off; press the battery power button once and then press and hold for 2 seconds to turn on the intelligent battery.

(3) Powering off: When the battery is powered on; press the battery power button once and then press and hold for 2 seconds to turn off the intelligent battery.

LED3

LED4

Battery Power Button

(Built-in Battery Power Indicator)

LED2

LED1

Battery Level Indicator

(4) Checking the battery life: When the battery is powered off; press and hold the battery power button for 5 seconds to check the battery life. The battery level indicators will show the life and the battery power indicator will blink for 10 seconds, then all LEDs will light out and the intelligent battery will turn off. Refer to < Battery Level Indicator Description> for details.

More battery information is available in the battery tab of the PHANTOM 2 Assistant.

4.4 Description of the Battery Level Indicator

The battery level indicators will show the current battery level during both the charging and discharging process as well as battery life. The following is a description of the indicators.

: The LED is solid on : The LED will blink regularly

: The LED is light off

Charging process

LED1 LED2 LED3 LED4 Current battery level

0%~25%

25%~50%

50%~75%

75%~100%
Full charged
Discharging process
LED1 LED2 LED3 LED4 Current battery level
87.5%~100%
75%~87.5%
62.5%~75%
50%~62.5%
37.5%~50%
25%~37.5%
12.5%~25%
0%~12.5%
<0%
Battery life
LED1 LED2 LED3 LED4 Current battery life
90%~100%

80%~90%
70%~80%
60%~70%
50%~60%
40%~50%
30%~40%
20%~30%
Less than 20%

4.5 Correct Battery Usage Notes

1. Never plug or unplug the battery into the aircraft when it is powered on.
2. The battery should be charged in an environment that is between 0℃ to 40℃, and be discharged in an environment that is between -20℃ to 50℃. Both charging and discharging should be in an environment where the relative humidity is lower than 80%.
3. It's recommended to charge and discharge the battery thoroughly once every 20 charge/discharge cycles. Users should discharge the battery until there is less than 8% power left or until the battery can no longer be turned on. Users should then fully recharge the battery to maximum capacity. This power cycling procedure will ensure the battery is working at its optimal level.
4. For long term storage please place the battery with only a 40~50% capacity in a strong battery box securely. We recommend discharging and charging the battery completely once every 3 months to keep it in good condition. The capacity should be varied in such a cycle (40%~50%)—0%—100%—(40%~50%).
5. It's suggested you purchase a new battery after you have discharged your current battery over 300 times. Please completely discharge a battery prior to disposal.
6. It's suggested that you purchase a new battery if the current battery is swollen or damaged in any way.
7. Never try to recharge or fly with a battery that is swollen or damaged in any way.
8. Never charge the battery unattended. Always charge the battery on a non-flammable surface such as concrete and never near any flammable materials.
9. Safety is extremely important and users can get more information in the DISCLAIMER.

5 Calibrating the Compass

IMPORTANT: Make sure to perform the Compass Calibration procedures prior to the first flight.

The compass is very sensitive to electromagnetic interference which causes abnormal compass data and leads to poor flight performance or even flight failure. Regular calibration of the compass enables the compass to perform at

its optimal level.

5.1 Calibration Warnings

（1）DO NOT calibrate your compass where there is a possibility for the existence of strong magnetic interference such as magnetite, parking structures, and steel reinforcement underground.

（2）DO NOT carry ferromagnetic materials with you during calibration such as keys or cellular phones.

（3）Compass Calibration is very important; otherwise the flight control system will work abnormally.

5.2 Calibration Procedures

Please carry out the calibrating procedures in the flight field before flight. Please watch the quick start video of the PHANTOM 2 for more compass calibration details.

Normal LED

Quickly flip the switch S1

360o Rotate the aircraft horizontally

360oRotate the aircraft vertically (Nose downward)

Position-1

Start horizontal calibration Start vertical calibration Succeed Fail

Position-1->Position-3->Position-1

Flip no less than 5 times

Start

cali

LED Flight Indicator

Position-1->Position-3->Position-1

Flip once

Position-3

LED Flight Indicator

LED Flight

Indicator

Re-calibrate

Position-1

Position-3

5.3 When Recalibration is required

（1）When Compass Data is abnormal, the LED flight indicator will blink alternating between red and yellow.

（2）Last compass calibration was performed at a completely different flying field/location.

（3）The mechanical structure of the aircraft has changed, i.e. changed mounting position of the compass.

（4）Evident drifting occurs in flight, i.e. the aircraft doesn't fly in straight lines.

6 Flight

6.1 Flying Environment Requirements

（1）Before your first flight, please allow yourself some flight training (Using a flight simulator to practice flying, getting instruction from an experienced person, etc.).

（2）DO NOT fly in bad weather, such as rain or wind (more than moderate breeze) or fog.

（3）The flying field should be open and void of tall buildings or other obstacles; the steel structure within buildings may interfere with the compass.

（4）Keep the aircraft away from obstacles, crowds, power lines, trees, lakes and rivers etc.

（5）Try to avoid interference between the remote controller and other wireless equipment (No base stations or cell towers around).

（6）The flight control system will not work properly at the South Pole or North Pole.

（7）Never use the aircraft in a manner that infringes upon or contravenes international or domestic

lays and regulations.

6.2 Starting the Motors

A Combination Stick Command (CSC) is used to start the motors. Push the sticks according to one of the options below to start motors. Once the motors have started, release both sticks simultaneously. The same CSC is used to stop the motors.

A B C D

Figure 6-1

6.3 Takeoff/Landing Procedures

1. Start by placing the PHANTOM 2 on the ground with the battery level indicators facing you.
2. Turn on the remote controller.
3. Power on the aircraft by turning on the intelligent battery.
4. When LED flight indicator blinks green/yellow, the PHANTOM 2 is entering Ready to Fly/Ready to Fly (non-GPS) mode. Start the motors with the CSC command.
5. Push the throttle stick up slowly to lift the aircraft off the ground. Refer to <Remote Controller Operation> for more details.
6. Be sure you are hovering over a level surface. Pull down the throttle stick to descend. The stick will lock into

place and the aircraft will descend steadily.

7. After landing, leave the throttle stick down for 3 to 5 seconds to stop the motors. Return throttle stick to middle position after the motors have stopped.

You SHOULD NOT execute the CSC during normal flight! This will stop the motors and cause the aircraft to descend rapidly and drop without any type of control.

（1）When the LED flight indicator blinks yellow rapidly during flight, the aircraft has entered into Failsafe mode, refer to <Failsafe Function> for details.

（2）A low battery capacity warning is indicated by the LED flight indicator blinking red slowly or rapidly during flight. Refer to the <Low Battery Capacity Warning Function> for details.

（3）Watch the quick start video about flight for more flight information.

（4）Aircraft and battery performance is subject to environmental factors such as air density and temperature. Be very careful when flying 3000 meters (9800 feet) or more above sea level, as battery and aircraft performance may be reduced.

（5）When used with a H3-3D gimbal, a GoPro camera, and the iOSD mini, your Phantom 2 will be very close to its maximum takeoff weight. It is not recommended that you attach the Phantom 2 propeller guards at this weight. Otherwise, the aircraft will be unable to fly normally.

6.4 Failsafe Function

The aircraft will enter Failsafe mode when the connection from the remote controller is lost. The flight control system will automatically control the aircraft to return to home and land to reduce injuries or damage. The following situations would make the aircraft fail to receive a signal from the remote controller and enter Failsafe mode:

（1）The remote controller is powered off.

（2）The remote controller is powered on but the S1 is toggled in the position triggering the Failsafe (this must have been configured in the PHANTOM 2 Assistant).

（3）The aircraft has flown out of the effective communication range of the remote controller.

（4）There is an obstacle obstructing the signal between the remote controller and the aircraft, essentially reducing the distance the signal can travel.

（5）There is interference causing a signal problem with the remote controller.

Failsafe works differently depending on the mode the aircraft is in when Failsafe mode is initiated whether it is in the Ready to Fly or Ready to Fly (non-GPS) mode.

Ready to Fly (non-GPS) ---- Automatic landing

The flight control system will try to keep the aircraft level during descent and landing. Note that the aircraft may be drifting during the descent and landing process.

Ready to Fly ---- Automatic go home and land

The flight control system will automatically control the aircraft to fly back to the home point and land.

Home Point

When the aircraft is initializing the Ready to Fly status, the aircraft will record the current GPS coordinates as the home point. It is recommended to lift off only after Ready to Fly status is confirmed for the safety of being able to fly back to home point successfully in case the Failsafe mode is initiated.

Go Home Procedures

1 Record Home Point. 2 Flying. 3 Remote controller signal lost.

5 Fly 4 Signal lost lasts 3s, begin to go home. back to home point. 6 Landing after hovering 15s.

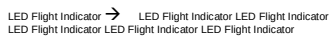


Figure 6-2

（1）In a Failsafe situation, if less than 6 GPS satellites are found for more than 20 seconds, the aircraft will descend automatically.

（2）When the aircraft is landing automatically, users can control the aircraft's position and altitude if the remote controller signal is recovered.

In Phantom 2 mode, users can set a new home point manually when the aircraft is in "Ready to fly" status as long as a home point has been recorded automatically. Quickly flipping the S2 switch of the remote controller from upper most to lower most positions 5 times or more will reset the current aircraft position as a new home point of PHANTOM 2. When successfully reset, you will see a series of rapid green blinks on the LED Flight Indicator. The definition of "home point" is:

（1）The home point is the place PHANTOM 2 returns to when the control signal is lost, which is recorded last time.

（2）The home point is used to calculate the horizontal distance between you and the aircraft, the distance will be displayed as

D

if using iOSD module.

Regaining Control during Failsafe Procedure

Position of

Switch S1

Position-1 Position-2

Position-3

(No triggering the Failsafe)

How to regain

control

When the S1 switch is switched to Position-1,

toggle the S1 switch to any other position once to

regain control. If remote controller's signal is

recovered, control is returned back to the pilot.

Regain control as soon as signal is

recovered.

6.5 Low Battery Capacity Warning Function

The low battery capacity warning alerts users when the battery is close to depletion during flight. When it appears, users should promptly fly back and land to avoid accidental damage. The PHANTOM 2 has two levels of low battery capacity warning. The first appears when the battery has less than 30% power and the second appears when it has less than 15% power.

（1）When battery power drops below 30% and LED indicator will blink red slowly.

（2）At lower than 15% the LED indicator will blink red rapidly, the PHANTOM 2 will also begin to descend and land automatically. After it has landed, keep the throttle stick at its lowest point or execute CSC.

（3）There is a hidden third low battery threshold in addition to the 1st and 2nd level warnings. This uses 10.65V as its threshold. Both this voltage threshold and the 2nd Level Low Battery Warning will trigger auto-landing. Altitude can be maintained if necessary by pushing up on the throttle stick.

（1）Remember to fly your PHANTOM 2 back as soon as you see a low battery capacity warning.

（2）Keeping the battery contact needles and pads clean is very important. Any dirt and dust may cause a communication failure.

6.6 Flight Limits Function

All UAV (unmanned aerial vehicle) operators should abide by all regulations from such organizations at ICAO (International Civil Aviation Organization) and per country airspace regulations. For safety reasons, the flight limits function is enabled by default to help users use this product safely and legally. The flight limits function includes height, distance limits.

In Ready to Fly status, height, distance limits works together to restrict the flight. In Ready to Fly (non-GPS) status, only height limit works and the flying height restricted to be not over 120m.

(1) The default parameters in the Assistant is compliant within the definitions of class G ruled by ICAO. (Refer to Airspace Classification to get more details). As each country has its own rules, make sure to configure the parameters to comply with these rules too, before using the PHANTOM 2.

(2) Users in Mainland China can refer to 民用航空空域使用办法.

Max Height & Radius Limits

The Max Height & Radius restricts the flying height and distance. Configuration can be done in the PHANTOM 2 Assistant. Once complete, your aircraft will fly in a restricted cylinder.

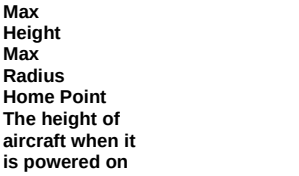


Figure 6-3 Figure 6-4

Ready to Fly

Limits Ground Station Rear LED flight indicator

Max Height

The flight height is restricted to fly under the max height.

Warning: Height limit reached.

None.

Max Radius

The flight distance is restricted to fly within the max radius.

Warning: Distance limit reached.

Rapid red flashings when close to the Max radius limit.

Ready to Fly(non-GPS)

Flight Limits Ground Station Rear LED flight indicator

Max Height

The flight height is restricted to fly
under the minor height between the
Max height and 120m.
Warning: Height limit reached.
None.
Max Radius Not limited, no warnings or LED indicators.
(1) If the aircraft flies out of the limits, you can still control your aircraft except to fly it further away.
(2) If the aircraft is flying out of the max radius in Ready to Fly (non-GPS) status, it will fly back
within the limits range automatically if 6 or more GPS satellites have been found.

6.7 Flight Limits of Special Areas

Special areas include airports worldwide. All special areas are listed on the DJI official website. Please refer to http://www.dji.com/fly-safe/category-mc for details. These areas have been divided into category A and category B.

Category A Category B
Ready to Fly
Airspace Limits
Rear LED
Flight Indicator
A
Orange
Motors will not start.
If the Phantom flies into a special area in Ready to Fly
(non-GPS) mode and Ready to Fly mode activates, it will
automatically descend and land then stop its motors.
B
Yellow
If the Phantom flies into a special area in Ready to Fly
(non-GPS) mode and Ready to Fly mode activates, it will
descend to airspace C and hover 5 meters below edge d.
C
Green
No restrictions of flight, but the Phantom will not enter
Category A, the aircraft can fly free, but it will not enter
Airspace B through Boundary b & d.
Around Category B sites, the phantom can fly freely, but it will
not enter into Airspace A through Boundary a.
D
Blue
No restrictions. None.
10.5m
2400m
Center of
Special
Area
8000m
120m
A B C
8100m

D

b

d

c b a a c

d

a

b

c

Airspace: A,B,C,D

Boundary: a, b, c, d

1000m

A C D

c a a c

a

2000m c

Center of

Special

Area

Airspace: A,C,D

Boundary: a, c,

Semi-automatic descent: All stick commands are available except the throttle stick command during the descent and landing process. Motors will stop automatically after landing. Users will regain control once the motors have stopped. There is no need to toggle the S1 switch.

(1) When flying in the airspace (A/B/C) of restricted special area, LED flight indicators will blink red quickly and continue for 3 seconds, then switch to indicate current flying status and continue for 5 seconds at which point it will switch back to red blinking.

(2) For safety reasons, please do not fly close to airports, highways, railway stations, railway lines, city centers and other special areas. Try to ensure the aircraft is visible.

6.8 Conditions of Flight Limits

In different working modes and flight modes, flight limits will differ according to number of GPS satellites found. The following table demonstrates all the cases(√: available; ×:unavailable).

All flights are restricted by height, distance and special areas simultaneously.

Phantom mode

Flight Status Limits of Special Area Max Height Max Radius

Ready to Fly √ √ √

Ready to Fly (non-GPS) × √ ×

Naza-M mode

Control Mode number of GPS found Limits of Special Area Max Height Max Radius

GPS

≥6 √ √ √

< 6 × √ ×

ATTI.

≥6 √ √ ×

< 6 × √ ×

Manual

≥6 × × ×

< 6 × × ×

Disclaimer

Please ensure that you are kept up to date with International and Domestic airspace rules and regulations before using this product. By using this product, you hereby agree to this disclaimer and signify that you have read this fully. You agree that you are responsible for your own conduct and content while using this product, and for any direct or indirect consequences caused by not following this manual, violate or disregard any other applicable local laws, administrative rules and social habits thereof.

7 Assistant Installation and Configuration

7.1 Installing Driver and PHANTOM 2 Assistant

Installing and running on Windows

1. Download driver installer and Assistant installer in EXE format from the download page of PHANTOM 2 on the DJI website.
2. Connect the PHANTOM 2 to a PC via a Micro-USB cable.
3. Run the driver installer and follow the prompts to finish installation.
4. Next, run the Assistant installer and follow the prompts to finish installation.
5. Double click the PHANTOM 2 icon on your Windows desktop to launch the software.

The installer in EXE format only supports Windows operating systems (Win XP, Win7, Win8 (32 or 64 bit)).

Installing and running on Mac OS X

1. Download the Assistant installer in DMG format from the download page of PHANTOM 2 on the DJI website.
2. Run the installer and follow the prompts to finish installation.
3. When launching for the first time if use Launchpad to run the PHANTOM 2 Assistant, Launchpad won't allow access because the software has not been reviewed by Mac App Store.
4. Locate the PHANTOM 2 icon in the Finder, press the Control key and then click the PHANTOM 2 icon (or right-click the PHANTOM 2 icon using a mouse). Choose Open from the shortcut menu, click open in the prompt dialog box and then software will launch.
5. After the first successful launch, directly launching of the software can be achieved by double-clicking the PHANTOM 2 icon in the Finder or using Launchpad.

Installer in DMG format supports only Mac OS X 10.6 or above.

Usage of PHANTOM 2 Assistant on Mac OS X and Windows are exactly the same. The Assistant pages appear in other places of this manual are on the Windows for example.

7.2 Using the PHANTOM 2 Assistant on a PC

1. Start up the PC, power on the PHANTOM 2, then connect the PHANTOM 2 to the PC with a Micro-USB cable. DO NOT disconnect until configuration is finished.
2. Run the PHANTOM 2 Assistant and wait for the PHANTOM 2 to connect to the Assistant. Observe the indicators on the bottom of the screen. When connected successfully, the connection indicator is and communication indicator is blinking .
3. Choose [Basic] or [Advanced] configuration pages.
4. View and check the current configuration in the [View] page.

Language swap
View configurations
Connection indicator
Communication indicator
RC, Gain
Gimbal, Battery IMU calibration
Firmware upgrade
Account, software version

*This image is for reference only. Please refer to the actual user interface.

Function switch of Phantom 2
and Naza-M mode

（1）Users should not enable the Naza-M function before finishing Advanced Flight Maneuvers procedure in the " PHANTOM Pilot Training Guide". If the Naza-M mode is enabled, users can switch the control mode between ATTI. Mode, GPS Mode or Manual Mode, and access the advanced settings (e.g. IOC). In addition, the LED located on the rear frame arms will display Naza-M flight status indications instead of the PHANTOM 2's indicators. Do not enable the Naza-M mode unless you are an experienced user or guided by a professional.

（2）You can change to the Phantom 2 mode by clicking the same button used to turn on the Naza-M mode. This operation will disable the Naza-M mode and enable Phantom 2 mode. All parameters will be returned to factory settings.

7.3 Firmware upgrade of PHANTOM 2

Please refer to the PHANTOM 2 Assistant to install driver and PHANTOM RC Assistant, and then follow the procedures below to upgrade the software and firmware; otherwise the PHANTOM 2 might not work properly.

1. An internet connection is required to upgrade PHANTOM 2's firmware.
2. Click the [Upgrade] icon to check the current firmware version and whether the installed firmware is the latest version. If not, click the relative links to upgrade.
3. Be sure to wait until the Assistant shows "finished". Click OK and power cycle the PHANTOM 2 after 5 seconds. Once completed, the firmware is up to date.

Firmware upgradable items
Current firmware version
Upgrade link
*This image is for reference only. Please refer to the actual user interface.

（1） DO NOT power off until the upgrade is finished.

（2） If the firmware upgrade failed, the main controller will enter a waiting for firmware upgrade status automatically. If this happens, repeat the above procedures.

Firmware upgradable items:（1）Main Controller（2）P330CB(Main Board)（3）Receiver（4）Gimbal CMU（5）Gimbal IMU（6）Battery

7.4 PHANTOM RC Assistant Description

Please follow the procedures to finish the configuration of the remote controller.

1. Turn off the remote controller and find the Micro-USB port on the bottom of it.
2. Start up the PC, power on the remote controller, and then connect the remote controller to the PC with a Micro-USB cable. DO NOT disconnect until the configuration is finished.
3. Run the PHANTOM RC Assistant and wait for the remote controller to connect to the Assistant. Observe the indicators on the bottom left of the screen. When connected successfully, the connection indicator is and communication indicator is blinking .
4. Finish configuration in the [Main] page.
5. Finish upgrade in the [Info] page if necessary.

Main Page of the 2.4GHz Remote Controller

Language swap
Main page
Connection indicator
Communication indicator
Firmware upgrade
Account, software version
*This image is for reference only. Please

refer to the actual
user interface.

8 Appendix

8.1 Specifications

Aircraft

Operating environment temperature -10℃ to 50℃

Power consumption 5.6W

Supported Battery DJI Intelligent battery

Weight (including the battery) 1000g

Take-off Weight ≤1300g

Hovering Accuracy (Ready to Fly) Vertical: 0.8m; Horizontal: 2.5m

Max Yaw Angular Velocity 200°/s

Max Tilt Angle 35°

Max Ascent / Descent Speed Ascent: 6m/s; Descent: 2m/s

Max Flight Speed 15m/s (Not Recommended)

Wheelbase 350mm

2.4GHz Remote Controller

Operating Frequency 2.4GHz ISM

Communication Distance (open area) 1000m

Receiver Sensitivity (1%PER) -97dBm

Working Current/Voltage 120 mA@3.7V

Built-in LiPo Battery Working Current/Capacity 3.7V, 2000mAh

DJI Intelligent Battery

Type 3S LiPo Battery

Capacity 5200mAh, 11.1V

Charging Environment Range 0℃ to 40℃

Discharging Environment Range -20℃ to 50℃

8.2 LED Flight Indicators Description

Aircraft in Normal status Descriptions

Power On Self-Test

Warming Up & Aircraft cannot take off during warming up

Ready to Fly

Ready to Fly (non-GPS)

Aircraft in abnormal status Warnings and errors

Remote Controller Signal Lost

1st Level Low Battery Capacity Warning