U.S. Department
of Transportation
**Federal Aviation
Administration**

800 Independence Ave., S.W.
Washington, D.C. 20591

September 21, 2015

Exemption No. 12953
Regulatory Docket No. FAA−2015−2621

Ms. Barbara M. Weinkle
dba TransCarolina Marketing/tcmphotos
P.O. Box 18053
Asheville, NC 28814

Dear Ms. Weinkle:

This letter is to inform you that we have granted your request for exemption. It transmits our decision, explains its basis, and gives you the conditions and limitations of the exemption, including the date it ends.

By letter dated June 15, 2015, you petitioned the Federal Aviation Administration (FAA) on behalf of Ms. Barbara M. Weinkle dba TransCarolina Marketing/tcmphotos (hereinafter petitioner or operator) for an exemption. The petitioner requested to operate an unmanned aircraft system (UAS) to conduct aerial photography, videography, and cinematography.

See Appendix A for the petition submitted to the FAA describing the proposed operations and the regulations that the petitioner seeks an exemption.

The FAA has determined that good cause exists for not publishing a summary of the petition in the Federal Register because the requested exemption would not set a precedent, and any delay in acting on this petition would be detrimental to the petitioner.

Airworthiness Certification

The UAS proposed by the petitioner is a DJI Phantom 2.

The petitioner requested relief from 14 CFR part 21, *Certification procedures for products and parts, Subpart H—Airworthiness Certificates*. In accordance with the statutory criteria provided in Section 333 of Public Law 112−95 in reference to 49 U.S.C. § 44704, and in consideration of the size, weight, speed, and limited operating area associated with the aircraft and its operation, the Secretary of Transportation has determined that this aircraft meets the conditions of Section 333. Therefore, the FAA finds that the requested relief from 14 CFR part 21, *Certification procedures for products and parts, Subpart H—Airworthiness Certificates*, and any associated noise certification and testing requirements of part 36, is not necessary.

The Basis for Our Decision

You have requested to use a UAS for aerial data collection[1]. The FAA has issued grants of exemption in circumstances similar in all material respects to those presented in your petition. In Grants of Exemption Nos. 11062 to Astraeus Aerial (*see* Docket No. FAA−2014−0352), 11109 to Clayco, Inc. (*see* Docket No. FAA−2014−0507), 11112 to VDOS Global, LLC (*see* Docket No. FAA−2014−0382), and 11213 to Aeryon Labs, Inc. (*see* Docket No. FAA−2014−0642), the FAA found that the enhanced safety achieved using an unmanned aircraft (UA) with the specifications described by the petitioner and carrying no passengers or crew, rather than a manned aircraft of significantly greater proportions, carrying crew in addition to flammable fuel, gives the FAA good cause to find that the UAS operation enabled by this exemption is in the public interest.

Having reviewed your reasons for requesting an exemption, I find that—

- They are similar in all material respects to relief previously requested in Grant of Exemption Nos. 11062, 11109, 11112, and 11213;
- The reasons stated by the FAA for granting Exemption Nos. 11062, 11109, 11112, and 11213 also apply to the situation you present; and
- A grant of exemption is in the public interest.

Our Decision

In consideration of the foregoing, I find that a grant of exemption is in the public interest. Therefore, pursuant to the authority contained in 49 U.S.C. 106(f), 40113, and 44701, delegated to me by the Administrator, TransCarolina Marketing/tcmphotos is granted an exemption from 14 CFR §§ 61.23(a) and (c), 61.101(e)(4) and (5), 61.113(a), 61.315(a), 91.7(a), 91.119(c), 91.121, 91.151(a)(1), 91.405(a), 91.407(a)(1), 91.409(a)(1) and (2), and 91.417(a) and (b), to the extent necessary to allow the petitioner to operate a UAS to perform

[1] Aerial data collection includes any remote sensing and measuring by an instrument(s) aboard the UA. Examples include imagery (photography, video, infrared, etc.), electronic measurement (precision surveying, RF analysis, etc.), chemical measurement (particulate measurement, etc.), or any other gathering of data by instruments aboard the UA.

aerial data collection. This exemption is subject to the conditions and limitations listed below.

Conditions and Limitations

In this grant of exemption, TransCarolina Marketing/tcmphotos is hereafter referred to as the operator.

Failure to comply with any of the conditions and limitations of this grant of exemption will be grounds for the immediate suspension or rescission of this exemption.

1. Operations authorized by this grant of exemption are limited to the DJI Phantom 2 when weighing less than 55 pounds including payload. Proposed operations of any other aircraft will require a new petition or a petition to amend this exemption.

2. Operations for the purpose of closed-set motion picture and television filming are not permitted.

3. The UA may not be operated at a speed exceeding 87 knots (100 miles per hour). The exemption holder may use either groundspeed or calibrated airspeed to determine compliance with the 87 knot speed restriction. In no case will the UA be operated at airspeeds greater than the maximum UA operating airspeed recommended by the aircraft manufacturer.

4. The UA must be operated at an altitude of no more than 400 feet above ground level (AGL). Altitude must be reported in feet AGL.

5. The UA must be operated within visual line of sight (VLOS) of the PIC at all times. This requires the PIC to be able to use human vision unaided by any device other than corrective lenses, as specified on the PIC's FAA-issued airman medical certificate or U.S. driver's license.

6. All operations must utilize a visual observer (VO). The UA must be operated within the visual line of sight (VLOS) of the PIC and VO at all times. The VO may be used to satisfy the VLOS requirement as long as the PIC always maintains VLOS capability. The VO and PIC must be able to communicate verbally at all times; electronic messaging or texting is not permitted during flight operations. The PIC must be designated before the flight and cannot transfer his or her designation for the duration of the flight. The PIC must ensure that the VO can perform the duties required of the VO.

7. This exemption and all documents needed to operate the UAS and conduct its operations in accordance with the conditions and limitations stated in this grant of exemption, are hereinafter referred to as the operating documents. The operating

documents must be accessible during UAS operations and made available to the Administrator upon request. If a discrepancy exists between the conditions and limitations in this exemption and the procedures outlined in the operating documents, the conditions and limitations herein take precedence and must be followed. Otherwise, the operator must follow the procedures as outlined in its operating documents. The operator may update or revise its operating documents. It is the operator's responsibility to track such revisions and present updated and revised documents to the Administrator or any law enforcement official upon request. The operator must also present updated and revised documents if it petitions for extension or amendment to this grant of exemption. If the operator determines that any update or revision would affect the basis upon which the FAA granted this exemption, then the operator must petition for an amendment to its grant of exemption. The FAA's UAS Integration Office (AFS−80) may be contacted if questions arise regarding updates or revisions to the operating documents.

8. Any UAS that has undergone maintenance or alterations that affect the UAS operation or flight characteristics, e.g., replacement of a flight critical component, must undergo a functional test flight prior to conducting further operations under this exemption. Functional test flights may only be conducted by a PIC with a VO and must remain at least 500 feet from other people. The functional test flight must be conducted in such a manner so as to not pose an undue hazard to persons and property.

9. The operator is responsible for maintaining and inspecting the UAS to ensure that it is in a condition for safe operation.

10. Prior to each flight, the PIC must conduct a pre-flight inspection and determine the UAS is in a condition for safe flight. The pre-flight inspection must account for all potential discrepancies, e.g., inoperable components, items, or equipment. If the inspection reveals a condition that affects the safe operation of the UAS, the aircraft is prohibited from operating until the necessary maintenance has been performed and the UAS is found to be in a condition for safe flight.

11. The operator must follow the UAS manufacturer's maintenance, overhaul, replacement, inspection, and life limit requirements for the aircraft and aircraft components.

12. Each UAS operated under this exemption must comply with all manufacturer safety bulletins.

13. Under this grant of exemption, a PIC must hold either an airline transport, commercial, private, recreational, or sport pilot certificate. The PIC must also hold a current FAA airman medical certificate or a valid U.S. driver's license issued by a state, the District of Columbia, Puerto Rico, a territory, a possession, or the Federal

government. The PIC must also meet the flight review requirements specified in 14 CFR § 61.56 in an aircraft in which the PIC is rated on his or her pilot certificate.

14. The operator may not permit any PIC to operate unless the PIC demonstrates the ability to safely operate the UAS in a manner consistent with how the UAS will be operated under this exemption, including evasive and emergency maneuvers and maintaining appropriate distances from persons, vessels, vehicles and structures. PIC qualification flight hours and currency must be logged in a manner consistent with 14 CFR § 61.51(b). Flights for the purposes of training the operator's PICs and VOs (training, proficiency, and experience-building) and determining the PIC's ability to safely operate the UAS in a manner consistent with how the UAS will be operated under this exemption are permitted under the terms of this exemption. However, training operations may only be conducted during dedicated training sessions. During training, proficiency, and experience-building flights, all persons not essential for flight operations are considered nonparticipants, and the PIC must operate the UA with appropriate distance from nonparticipants in accordance with 14 CFR § 91.119.

15. UAS operations may not be conducted during night, as defined in 14 CFR § 1.1. All operations must be conducted under visual meteorological conditions (VMC). Flights under special visual flight rules (SVFR) are not authorized.

16. The UA may not operate within 5 nautical miles of an airport reference point (ARP) as denoted in the current FAA Airport/Facility Directory (AFD) or for airports not denoted with an ARP, the center of the airport symbol as denoted on the current FAA-published aeronautical chart, unless a letter of agreement with that airport's management is obtained or otherwise permitted by a COA issued to the exemption holder. The letter of agreement with the airport management must be made available to the Administrator or any law enforcement official upon request.

17. The UA may not be operated less than 500 feet below or less than 2,000 feet horizontally from a cloud or when visibility is less than 3 statute miles from the PIC.

18. If the UAS loses communications or loses its GPS signal, the UA must return to a pre-determined location within the private or controlled-access property.

19. The PIC must abort the flight in the event of unpredicted obstacles or emergencies.

20. The PIC is prohibited from beginning a flight unless (considering wind and forecast weather conditions) there is enough available power for the UA to conduct the intended operation and to operate after that for at least five minutes or with the reserve power recommended by the manufacturer if greater.

21. Air Traffic Organization (ATO) Certificate of Waiver or Authorization (COA). All operations shall be conducted in accordance with an ATO-issued COA. The

exemption holder may apply for a new or amended COA if it intends to conduct operations that cannot be conducted under the terms of the attached COA.

22. All aircraft operated in accordance with this exemption must be identified by serial number, registered in accordance with 14 CFR part 47, and have identification (N−Number) markings in accordance with 14 CFR part 45, Subpart C. Markings must be as large as practicable.

23. Documents used by the operator to ensure the safe operation and flight of the UAS and any documents required under 14 CFR §§ 91.9 and 91.203 must be available to the PIC at the Ground Control Station of the UAS any time the aircraft is operating. These documents must be made available to the Administrator or any law enforcement official upon request.

24. The UA must remain clear and give way to all manned aviation operations and activities at all times.

25. The UAS may not be operated by the PIC from any moving device or vehicle.

26. All Flight operations must be conducted at least 500 feet from all nonparticipating persons, vessels, vehicles, and structures unless:
    a. Barriers or structures are present that sufficiently protect nonparticipating persons from the UA and/or debris in the event of an accident. The operator must ensure that nonparticipating persons remain under such protection. If a situation arises where nonparticipating persons leave such protection and are within 500 feet of the UA, flight operations must cease immediately in a manner ensuring the safety of nonparticipating persons; and
    b. The owner/controller of any vessels, vehicles or structures has granted permission for operating closer to those objects and the PIC has made a safety assessment of the risk of operating closer to those objects and determined that it does not present an undue hazard.

    The PIC, VO, operator trainees or essential persons are not considered nonparticipating persons under this exemption.

27. All operations shall be conducted over private or controlled-access property with permission from the property owner/controller or authorized representative. Permission from property owner/controller or authorized representative will be obtained for each flight to be conducted.

28. Any incident, accident, or flight operation that transgresses the lateral or vertical boundaries of the operational area as defined by the applicable COA must be reported to the FAA's UAS Integration Office (AFS−80) within 24 hours. Accidents must be

reported to the National Transportation Safety Board (NTSB) per instructions contained on the NTSB Web site: www.ntsb.gov.

If this exemption permits operations for the purpose of closed-set motion picture and television filming and production, the following additional conditions and limitations apply.

29. The operator must have a motion picture and television operations manual (MPTOM) as documented in this grant of exemption.

30. At least 3 days before aerial filming, the operator of the UAS affected by this exemption must submit a written Plan of Activities to the local Flight Standards District Office (FSDO) with jurisdiction over the area of proposed filming. The 3-day notification may be waived with the concurrence of the FSDO. The plan of activities must include at least the following:
    a. Dates and times for all flights;
    b. Name and phone number of the operator for the UAS aerial filming conducted under this grant of exemption;
    c. Name and phone number of the person responsible for the on-scene operation of the UAS;
    d. Make, model, and serial or N−Number of UAS to be used;
    e. Name and certificate number of UAS PICs involved in the aerial filming;
    f. A statement that the operator has obtained permission from property owners and/or local officials to conduct the filming production event; the list of those who gave permission must be made available to the inspector upon request;
    g. Signature of exemption holder or representative; and
    h. A description of the flight activity, including maps or diagrams of any area, city, town, county, and/or state over which filming will be conducted and the altitudes essential to accomplish the operation.

31. Flight operations may be conducted closer than 500 feet from participating persons consenting to be involved and necessary for the filming production, as specified in the exemption holder's MPTOM.

Unless otherwise specified in this grant of exemption, the UAS, the UAS PIC, and the UAS operations must comply with all applicable parts of 14 CFR including, but not limited to, parts 45, 47, 61, and 91.

This exemption terminates on September 30, 2017, unless sooner superseded or rescinded.

Sincerely,

/s/
John S. Duncan
Director, Flight Standards Service

Enclosures

Barbara M. Weinkle, d/b/a

TransCarolina Marketing/tcmphotos

P.O. Box 18053

Asheville, NC 28814

June 15, 2015

U.S. Department of Transportation, Docket Operations

West Building Ground Floor, Room W12-140

1200 New Jersey Av., SE

Washington, D.C. 20590

Re: Exemption request under Section 333 of the Federal Aviation Administration Reform Act of 2012. Specifically, I request exemption from 14 CFR Part 21; 45.23(b); 61.113 (a) and (b); 91.7 (a); 91.9(b) (2); 91.103(b); 91.109; 119.121; 91.151(a); 91.203(a) & (b); 91.405(a); 91.407(a)(1); 91.409(a) (2); 91.417(a)&(b)

To Whom it may concern:

I am petitioning for an exemption in accordance with the Federal Aviation Administration (FAA) Modernization and Reform Act of 2012 and procedures contained in 14 Code of Federal Regulations (CFR) 11 to request that I, an owner and operator of a small unmanned aircraft, be exempted from the Federal Aviation Regulations (FARS) listed herein so that I may operate a small, ultralight unmanned aircraft system (UAS) commercially in the National Airspace System (NAS). Given the nature of my operations and exemptions granted to others, it would seem that my request may qualify for a "summary grant."

For the past 37 years I have been providing real estate photography for the regional real estate companies and local government agencies to better exhibit and promote this mountainous region of North Carolina. I am a licensed driver in North Carolina with a sterling driving record. My husband is a licensed commercial pilot, and former Naval Aviator with more than 6000 hours fixed and rotary wing flight time. He has served as a squadron Chief Safety Officer; helicopter flight instructor; chief safety officer, and Director of Operations for a FAR Part 135 helicopter

charter company. He will serve as my supervisor. I have purchased a DJI Phantom 2 ultralight UAS equipped with a GoPro Hero 3+ camera for aerial photography/videography/cinematography for commercial and private real estate sales and development, scientific and other lawful purposes in the mountains and piedmont of western North Carolina and upper South Carolina.

I plan to operate my UAS at or below 200' AGL, within line-of-sight, under VFR conditions, and in a manner not to hazard other aircraft or people or property. **Under direct supervision** of my husband, I or other persons with a current driver's license or pilot's license will fly the UAS using sound judgement and concern for safety.

My request falls under the Secretary of Transportation's authority granted in Section 333 of the FAA Modernization and Reform Act of 2012. By granting my petition to operate my UAS for commercial purposes I will contribute to responsible development in environmentally sensitive western North Carolina and upper South Carolina; provide technical and scientific data on the region; and provide more meaningful and useful real estate listings in the region at affordable prices.

I. Contact information:

Barbara M. Weinkle, d/b/a
TransCarolina Marketing/tcmphotos
P.O. 18053
Asheville, NC 28814
Office: 828-253-9755
Mobile: 828-231-2354
Email: tcmphotos@charter.net

II. **Extent and rationale for relief:**

This application is submitted in accordance with the FAA Modernization and Reform Act of 2012 (PL 112-95) §§ 331-334 seeking relief from applicable FAR's that would prevent me from operating a UAS for commercial, cinematic/videographic, and scientific/technical purposes within the NAS. In addition, I live in mountainous terrain, and every year people become lost or fall over precipices or waterfalls. My UAS would be invaluable to rescue personnel allowing them to search impassable or hazardous areas. Section 332 provides for integration of civil unmanned aircraft systems since it is in the public's interest to do so. My UAS meets the definition of "small unmanned aircraft" as defined in Section 331. I wish to operate my UAS prior to promulgation of the rules governing such aircraft. Those operations would help provide data for future operations of all such systems.

My UAS is a Phantom 2 quadracopter manufactured by DJI which weighs 1 kg., including battery. Maximum take-off weight is 1.3 kg. The aircraft maximum speed is 15 meters/sec. Climb/descent velocities are 6m/s and 2m/s, respectively. Additional specifications are found in Enclosure (2).

My flight supervisor's 6000+ hours of accident-free flight time reflect an overriding concern for flight safety. That also reflects a respect for other air traffic and the general public and it is not my intention to hazard either with my UAS operations. Further, when operated responsibly, the characteristics and capabilities of my UAS preclude many operational hazards inherent in other aircraft operations. It has very limited range, airspeed, and altitude capabilities. The UAS is protected by a failsafe system which will return the aircraft to the point of takeoff in the event of failed communication with the controller. It carries no volatile fuel and is emission free.

III. **Benefit to the public:**

Passage of the FAA Modernization and Reform Act signaled Congress's belief that it is in the public's interest to integrate UAS's into the NAS. That interest is abundantly clear in western North Carolina. Western North Carolina's environment invites development, but its mountainous terrain makes it difficult to screen land for potential, responsible, safe development. Much of the area is subject to sometime fatal landslides, and often, unstable slopes are detectable only from the air. A UAS provides potential real estate clients with airborne assessments of properties inexpensively, and enables detection of potential development issues and hazards inherent to steep terrain. The region, with its national forests and wilderness areas and waterfalls is also attractive to hikers and campers. However, every year there are several incidents of lost hikers or people being swept over waterfalls resulting in expensive, and sometimes hazardous, search and rescue efforts. Often, a UAS would complement other aerial and ground search assets by extending searches into limited, but otherwise hazardous or inaccessible cliffs, caves, grottoes, or ravines.

IV. **A summary for the Federal Register:**

A. 14 CFR. 21 and 14 CFR 91: Airworthiness certificates, etc.

1. 14 CFR 21, Subpart H (Airworthiness Certificates) sets forth a requirement for obtaining airworthiness certificates as prescribed by FAR §91.202(a) 1. The size, weight, and operational area of my UAS permits exemption from Part 21, because my UAS meets and exceeds the level of safety dictated by Section 333 of the Reform Act. The FAA is authorized to exempt aircraft from the airworthiness certificate requirement under both the Act (49 USC §44701 (f), and Section 333 of the Reform Act. Both pieces of legislation allow UAS exemptions from the airworthiness certification based on weight, size, speed, maneuverability and proximity to areas such as airports and densely populated areas.

2. 14 CFR §91.7 (a) prohibits the operation of an aircraft without an airworthiness certificate. Airworthiness certification is not applicable as contemplated by the FARs.

3. 14 CFR §91.9 (b) 2 requires an aircraft flight manual in every aircraft. This regulation does not apply since my aircraft is unmanned by definition. An equivalent level of safety can be achieved by the remote pilot following the procedures laid down in the flight manual. The FAA has already issued many exemptions to this requirement.

4. 14 CFR §91.121 does not apply since my UAS uses GPS for position fixing and altitude sensing. 14 CFR §91.203 (a) and (b) do not apply since this is a UAS.

B. **14 CFR §45.23: Aircraft marking**

1. Regulations require certain markings. However, my UAS has no cockpit, crew station, or cabin. Further, there is no surface large enough to place two inch lettering. However, I will mark the UAS registration number with the largest numerals possible at the intersection of the pylons or on the pylons as required by CFR §45.29 (f). In addition, common sense dictates that I label it with ownership identification. The FAA has set a precedent by granting exemptions to these requirements.

C. **14 CFR §61.113: Private pilot restrictions and pilot in command (PIC)**

1. Private pilots are restricted to non-commercial operations. I can achieve an equivalent level of safety required by current regulations since my UAS carries no crew or passengers. Remote controlled aircraft the nature of my UAS do not require the same skill as those required of either a commercial or private pilot. For a UAS, the primary safety requirement is avoidance of other aircraft, structures or people. The skills required of a remote pilot of a small UAS easily meet those requirements or exceed them. Finally, my supervisor holds both private and commercial licenses for both fixed wing and rotary wing aircraft.

D. **14 CFR 91.119: Minimum safe altitudes**

1. My UAS will not operate above 200 feet AGL, safely below the standard 400 foot ceiling. I intend to operate my UAS away from air traffic and in a manner not to threaten people. The size, weight, maneuverability, and speed of my UAS allow me to meet or exceed the safety level prescribed by the FAR's.

E. **14 CFR §91.405(a), 407(a) 1, 409 (a) 2, 417 (a) & (b): Maintenance inspections**

1. The regulations listed above require regular, periodic inspections, and require discrepancies repaired. However, those regulations apply only to certificated aircraft, and will not apply to my UAS. However, both safety and financial considerations require inspections of the UAS before and after each flight.

I, Barbara M. Weinkle seek an exemption from the regulations listed and discussed above in order to operate a UAS for commercial purposes as described herein. Those operations can be conducted in a manner that meets or exceeds those imposed by the FARs and will provide a public benefit.

Respectfully submitted,

Barbara M Weinkle

Barbara M. Weinkle

Enclosures: (2)

PHANTOM 2 User Manual V1.4

For PHANTOM 2 Flight Controller Firmware version V3.10

& PHANTOM 2 Assistant version V3.8

& PHANTOM RC Assistant version V1.1

2015.01

Congratulations on purchasing your new DJI product. Please thoroughly read the entire contents of this manual to fully use and understand the product.

It is advised that you regularly check the PHANTOM 2 's product page at **www.dji.com** which is updated on a regular basis. This will provide services such as product information, technical updates and manual corrections. Due to any unforeseen changes or product upgrades, the information contained within this manual is subject to change without notice.

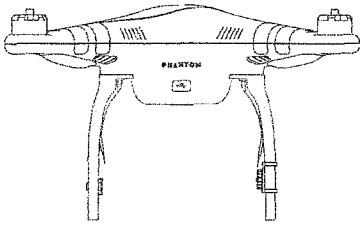
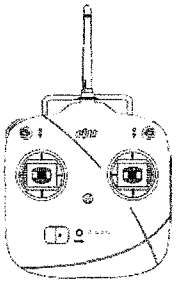
DJI and PHANTOM 2 are registered trademarks of DJI. Names of product, brand, etc., appearing in this manual are trademarks or registered trademarks of their respective owner companies. This product and manual are copy righted by DJI with all rights reserved.

If you have any questions or concerns regarding your product, please contact your dealer or DJI Customer Service.

Encl (2)

Content

In the Box

PHANTOM 2	Remote Controller-2.4GHz	Propeller Pair
		
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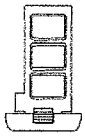		
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		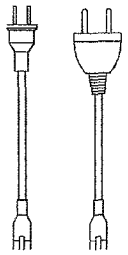
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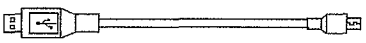
		

Legend

Forbidden(Important) Caution Tip Reference

4 of 36

1 PHANTOM 2 Aircraft

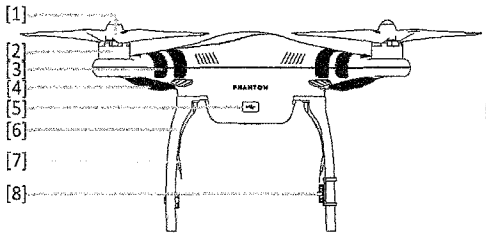


Figure 1-1

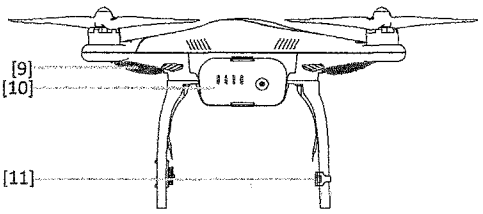


Figure 1-2

[1]Propeller [2]Motor [3]Front Side [4]Front LEDs [5]Micro-USB Port [6]Landing Gear [7]Receiver Antenna [8]CAN-Bus Connector [9]LED Flight Indicators [10]DJI Intelligent Battery [11]Compass

1.1 Built-in Flight Control System Instructions

The built-in flight control system is used to control the entire aircraft's functions in flight such as Pitch (forwards and backwards), Roll (left and right), Elevator (up and down) and Yaw (turn left or right). The flight controller contains the MC (Main Controller), IMU, GPS, compass, receiver.

The IMU (Inertial Measurement Unit) has a built-in inertial sensor and a barometric altimeter that measures both attitude and altitude. The compass reads geomagnetic information which assists the GPS (Global Position System) to accurately calculate the aircrafts position and height in order to lock the aircraft in a stable hover. The receiver is used to communicate with the remote controller and the MC acts as the brains of the complete flight control system connecting and controlling all the modules together.

> The PHANTOM 2 can be configured in the Assistant, by choosing Naza-M mode or Phantom 2 mode. This manual is for Phantom 2 mode. Please refer to the Naza-M V2 Quick Start Manual for more information.

1.2 Connections with Other DJI Products

PHANTOM 2 is compatible with other DJI products, including ZENMUSE H3-2D and H3-3D gimbal , iOSD mini , iOSD Mark II. Below are connections for these products and wireless video transmission module.

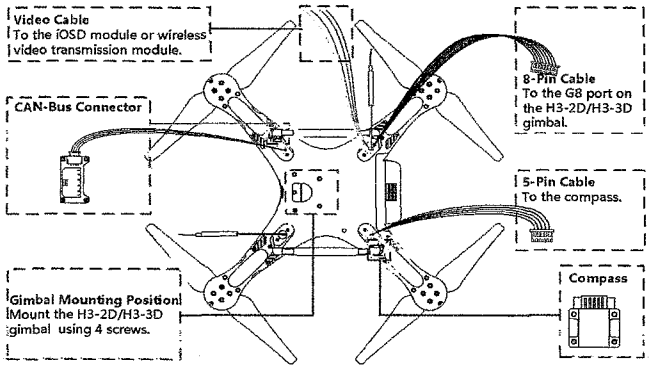


Figure 1-3

Important Notes of Using with Other DJI Products

(1) The video cable can provide power for the wireless video transmission module with a battery voltage (11.1V~12.6V) and a maximum current 2A.

(2) Make sure the working current of the wireless video transmission module you connect can work with an operational voltage between 11.1V 12.6V and the total working current of the iOSD and wireless video transmission module is under 2A, as an overcurrent will damage the central board's components. If the total current exceeds 2A, please be sure to provide power supplied from a separate power source for the wireless video transmission module.

(3) PHANTOM 2 uses a 2.4GHz RC system. To avoid communication interference, it's not recommended to use other 2.4GHz devices (including 2.4G Wi-Fi or 2.4G wireless video transmission module) except the 2.4G Bluetooth and 2.4G Datalink.

(4) Be sure to keep the wireless video transmission module and other communicating devices away from the compass during installation and connection to avoid interference.

(5) To improve the compatibility with ZENMUSE gimbals, the latest factory deliveries of PHANTOM 2 has updated to the Version 2 shown below. H3-2D/H3-3D gimbal can be directly installed for the Version 2 while for Version 1, a H3-3D adapter kit (coming soon) is required to install the H3-3D gimbal.

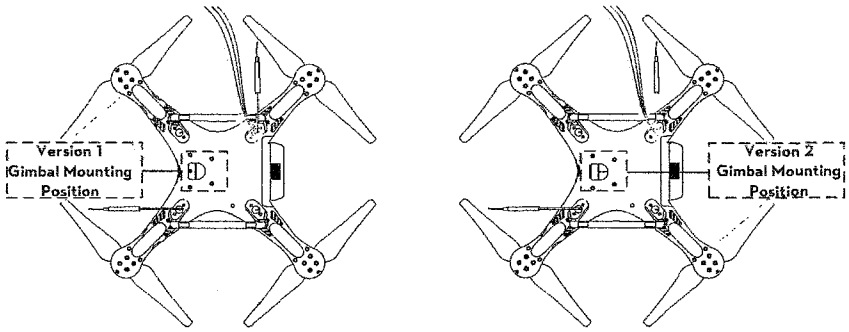


Figure 1-4

(6) When using the H3-3D gimbal, please connect the 8-Pin cable of PHANTOM 2 to the G8 port of H3-3D shown below.

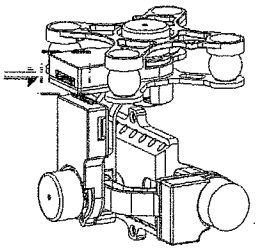


Figure 1-5

Connections with Other DJI Products

(1) Connecting the H3-2D and H3-3D gimbal and wireless video transmission module, the figure below uses H3-2D as an example.

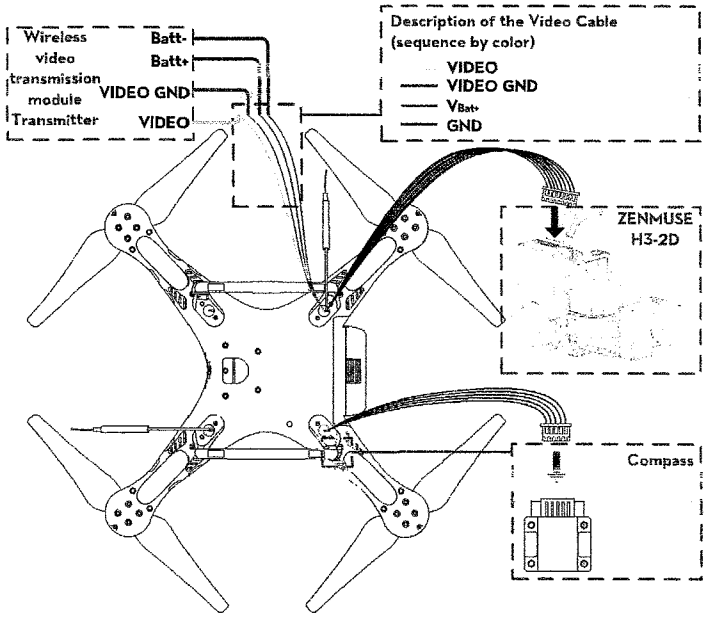


Figure 1-6

(2) Connecting the H3-2D and H3-3D gimbal, iOSD mini and wireless video transmission module, the figure below uses H3-2D as an example.

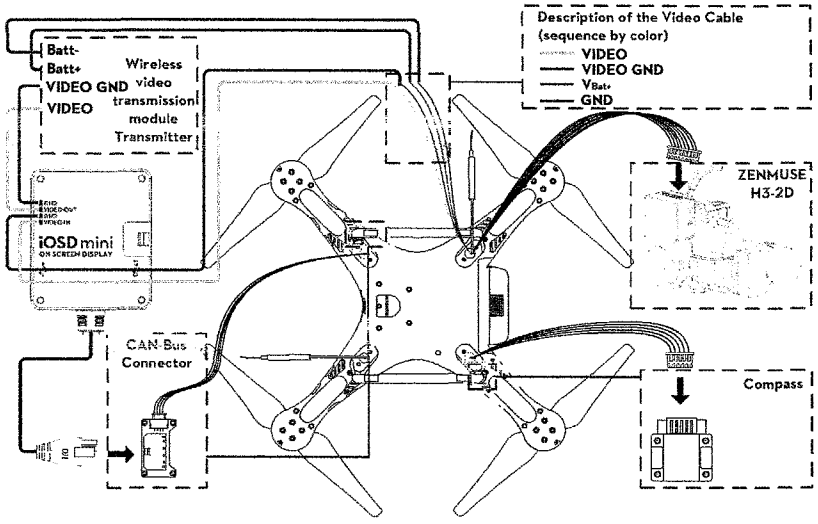


Figure 1-7

(3) Connecting the H3-2D and H3-3D gimbal, iOSD mini and DJI specified wireless video transmission module AVL58, the figure below uses H3-2D as an example.

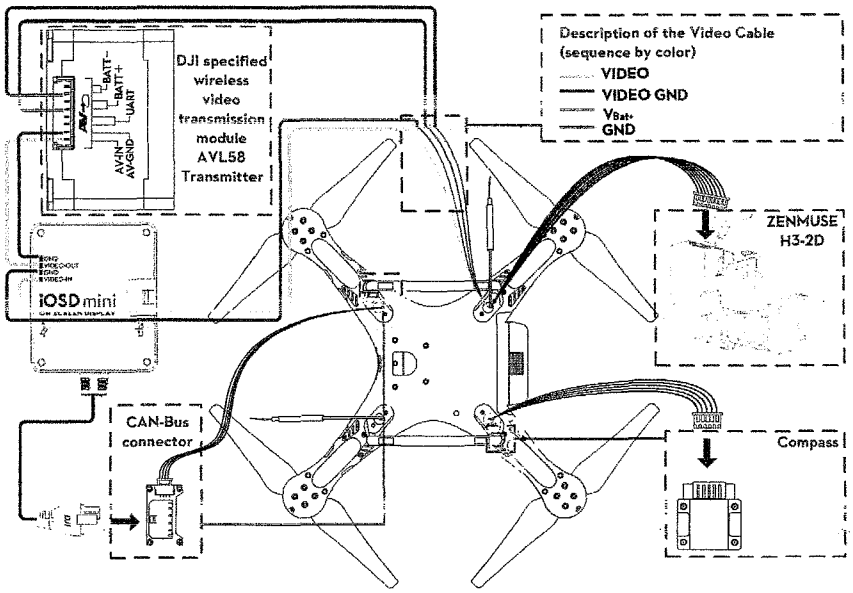


Figure 1-8

> We recommend connecting the V_{Bat+} port of the video cable to the two BATT+ ports of the AVL58 simultaneously. The same is true of the GND port of the video cable and two BATT- ports.

(4) Connecting the H3-2D and H3-3D gimbal, iOSD Mark II and wireless video transmission module, the figure below uses H3-2D as an example.

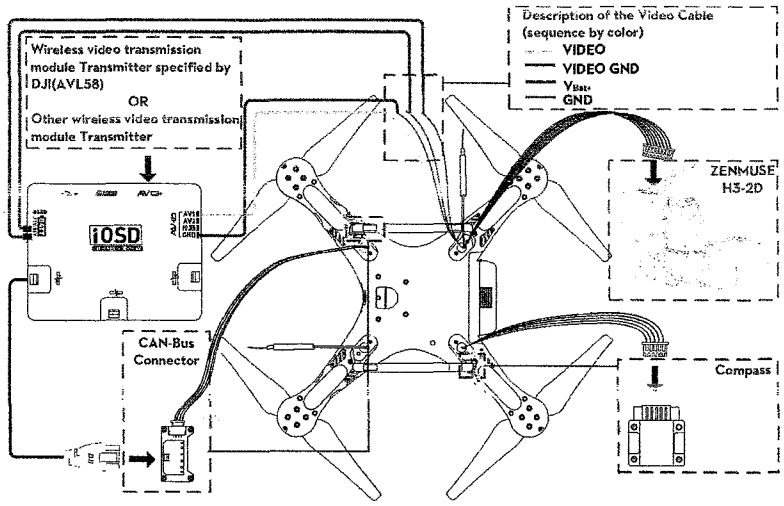
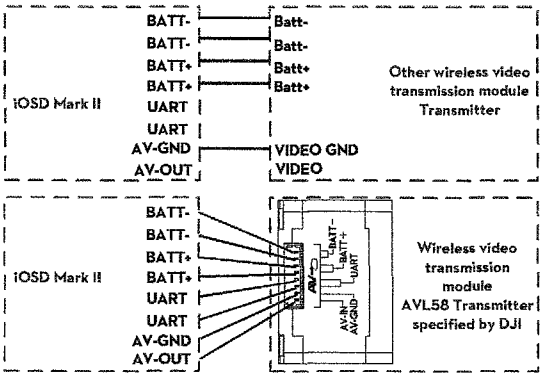


Figure 1-9

The diagram below illustrates the conneciton between the iOSD Mark II and the wireless video transmission module.

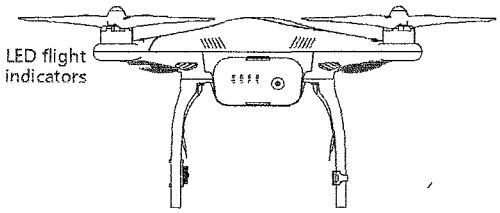


Use the 8-Pin cable in the iOSD Mark II package when connecting to the DJI specified wireless video transmission module AVL58.

(5) Using the iPad Ground Station

1.3 LED Flight Indicators Description

1. **LED flight indicators** are used to show the aircraft 's current status. Once powered on, the indicators will light up.

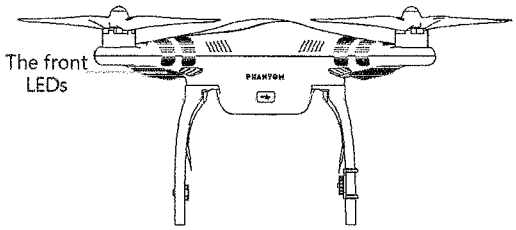


Aircraft in Normal status	**Descriptions**
	Power On Self-Test
	Warming Up & Aircraft cannot take off during warming up
	Ready to Fly
	Ready to Fly (non-GPS)
Aircraft in abnormal status	**Warnings and errors**
	Remote Controller Signal Lost
	1st Level Low Battery Capacity Warning
	2nd Level Low Battery Capacity Warning
	Not Stationary or Sensor Bias is too big
	Errors & Aircraft cannot fly.
	Compass data abnormal because of ferro-magnetic interference or the compass needs calibration.

(1) The LED indicators diagram above are for Phantom 2 mode. In Naza-M mode, LED indicators will work according to the Naza-M flight control system.

(2) Connect to the PHANTOM 2 Assistant for detailed information about warnings and errors.

2. The front LEDs are for indicating where the nose of the aircraft is. They light up solid red only after the motors have spooled up.



1.4 Notes for PHANTOM 2 using with other DJI products

Before using PHANTOM 2 with other DJI products, users should connecting the products correctly and upgrade the firmware as requirements below .

Items to upgrade	Firmware versions required	Assistant for upgrading	Assistant version
P330CB (built-in central board)	V1.0.1.19 or above	PHANTOM 2	V1.08 or above
Zenmuse H3-2D	CMU V1.0 , IMU V1.6 or above	PHANTOM 2	V1.08 or above
iOSD Mark II	V3.01 or above	iOSD	V4.0 or above
iOSD mini	V1.06 or above	iOSD	V4.0 or above

*The iOSD Assistant is applied to both iOSD Mark II and iOSD mini.

2 Propellers

PHANTOM 2 uses the original 9-inch propellers which are classified by the color of each central nut. Damaged propellers should be replaced by purchasing new ones if necessary.

Propellers	Grey Nut (9450)	Black Nut (9450 R)
Diagram		
Assembly Location	Attach to the motor thread that **does not have a black dot.**	Attach to the motor thread that **has a black dot.**
Fastening/Un-fastening Instructions	Lock: Tighten the propeller in this direction. Unlock: Remove the propeller in this direction.	

2.1 Assembly

1. (Figure 2-1) Remove the four warning cards from the motors after you've read them.
2. (Figure 2-2) Prepare the two grey nut propellers and two black nut propellers. Make sure to match the black nut propellers with the correctly marked black dot motors. Tighten the propellers according to the fastening instructions.

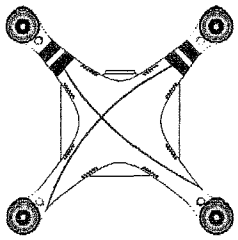


Figure 2-1

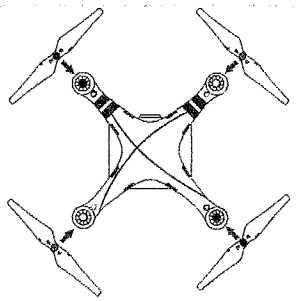


Figure 2-2

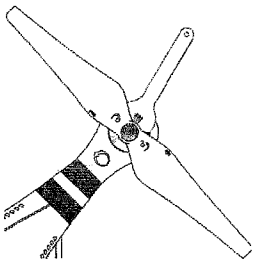


Figure2-3

2.2 Disassembly

(Figure 2-3) Keep the motor deadlocked in place with the assistant wrench (or one hand) and remove the propeller according to the un-fastening instructions.

2.3 Notes

1. Propellers are self tightening during flight. DO NOT use any thread locker on the threads.
2. Make sure to match the propeller nut colors with the corresponding motors.
3. It is advised to wear protective gloves during propeller assembly and removal.
4. Check that the propellers and motors are installed correctly and firmly before every flight.
5. Check that all propellers are in good condition before flight. DO NOT use any ageing, chipped, or broken propellers.
6. To avoid injury, STAND CLEAR of and DO NOT touch the propellers or motors when they are spinning.
7. ONLY use original DJI propellers for a better and safer flight experience.

3.2 Remote Controller LED Indicator Status

3.2.1 Remote Controller Power LED Indicator Status

Power LED Indicator	Sound	Remote Controller Status
▬▬▬	None	Functioning normally.
▬▬▬	None	Charging(remote controller is powered off)
	None	Remote controller joysticks calibration error, need to be re-calibrate.
▬▬▬	BB--BB--BB	Low voltage (from 3.5V-3.53V), recharge the remote controller.
●●●●●●	B-B-B.....	Critical low voltage (from 3.45V-3.5V). Recharge the remote controller immediately.
● ● ● ●	B--B--B.....	Alert will sound after 15 minutes of inactivity. It will stop once you start using the remote controller.

⚠ The remote controller will power off automatically when battery voltage drops below 3.45V. Land and recharge the battery as soon as possible when the low voltage alert occurs to avoid loss of control during flight.

3.2.2 Remote Controller Battery Level Indicator Status

The battery level indicators will show the current battery level during both the discharging process. The following is a description of the indicators.

■ : The LED is solid on ● : The LED will blink regularly

■ : The LED is light off

Discharging process				
LED1	LED2	LED3	LED4	**Current battery level**
■	■	■	■	75%~100%
■	■	■	■	50%~75%
■	■	■	■	25%~50%
■	■	■	■	12.5%~25%
●	■	■	■	0%~12.5%
■	■	■	■	<0%

3.3 Antenna Orientation

The remote controller's antenna should point skywards without obstructions for maximum communication range during flight.

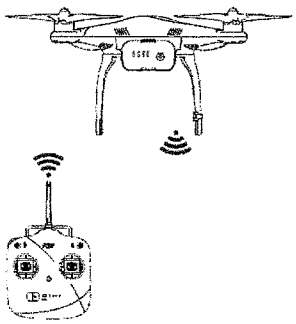


Figure 3-3

3.4 Remote Controller Operation

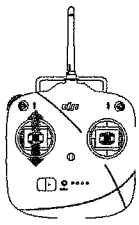
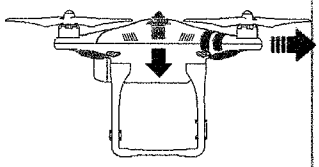
The operations of remote controller are based on mode 2 stick configuration.

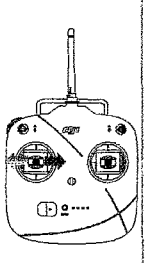
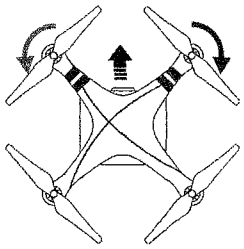
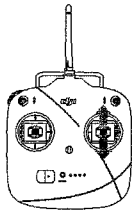
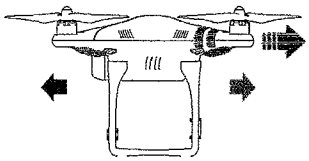
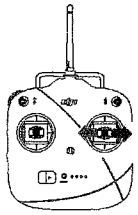
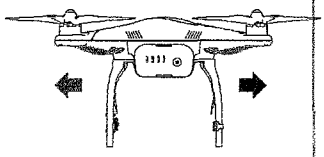
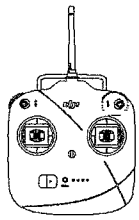
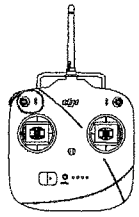
Definitions

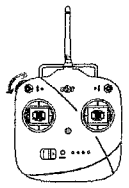
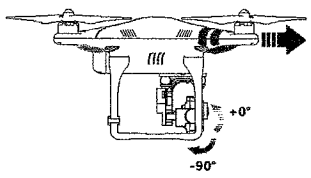
The '**stick neutral**' positions and '**stick released**' mean the control sticks of the remote controller are placed at the central position.

To '**move the stick**' means that the stick of remote controller is pushed away from the central position.

Slide Lever is used for the pitch control of the H3-2D and H3-3D gimbal.

Remote Controller (Mode 2)	**Aircraft** (◀ nose direction)	**Operation details**
		The throttle stick controls aircraft altitude/elevation. Push the stick up and the aircraft will rise. Pull the stick down and the aircraft will descend. The aircraft will automatically hover and hold its altitude if the sticks are centered. Push the throttle stick above the centered (mid-point) position to make the aircraft take off. When flying, we suggest that you push the throttle stick slowly to prevent the aircraft from sudden and unexpected elevation changes.

		The yaw stick controls the aircraft rudder. Push the stick left and the aircraft will rotate counter clock-wise. Push the stick right and the aircraft will rotate clock-wise. If the stick is centered, the aircraft will remain facing the same direction. The yaw stick controls the rotating angular velocity of the aircraft. Pushing the stick further away from center results in a faster aircraft rotation velocity.
		The pitch stick controls the aircraft's front & back tilt. Push the stick up and the aircraft will tilt and fly forward. Pull the stick down and the aircraft will tilt and fly backward. The aircraft will keep level and straight if the stick is centered. Pushing or pulling the stick further away from center will result in a larger tilt angle (maximum of is 35°) and faster flight velocity.
		The roll stick controls the aircraft's left & right tilt. Push the stick left and the aircraft will tilt and fly left. Push the stick right and the aircraft will tilt and fly right. The aircraft will keep level and straight if the stick is centered. Pushing the stick further away from center will result in a larger tilt angle (maximum of 35°) and faster flight velocity.
	 Position-1 Position-2 Position-3	S1 is for compass calibration. Toggle the S1 switch from position-1 to position-3 and back to position-1 at least 5 times, which will force the aircraft to enter into compass calibration mode. Users can configure position 3(bottom position) of the S1 switch to trigger the Failsafe in the Assistant.
	 OFF Course Lock point Lock Home	S2 is the IOC mode switch. IOC (Intelligent Orientation Control) function can be enabled in the Assistant when in Naza-M mode. Only use the IOC function after you are familiar with flying.

		The left dial controls the pitch of the H3-2D and H3-3D gimbal. The position of left dial determines the pitch angle relative to the horizontal level. Turn the left dial to the right to make the gimbal pitch up. Turn the left dial to the left to make the gimbal pitch down. The gimbal will keep its current position if the dial is static.

(1) For ' Ready to Fly ' the aircraft will hover when all sticks are released.

(2) For ' Ready to Fly (non-GPS) ' the aircraft will only keep the altitude when all sticks are released.

3.5 Linking the Remote Controller & Built-in Receiver

PHANTOM 2 has a built-in receiver, the link button and indicator located on the bottom of the aircraft as illustrated in the Figure 3-4.

The link between the remote controller and aircraft is already established for you so you can initially skip this procedure. If you ever replace the remote controller, re-establishing the link is required.

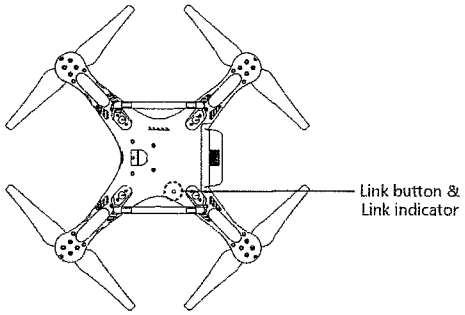


Figure 3-4

Linking procedures

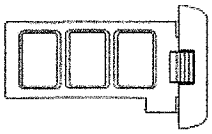
1. Power on the PHANTOM 2.
2. Turn on the remote controller and place it 0.5m~1m away from the aircraft.
3. Push the link button with a thin object and hold it until the Link indicator blinks red, then release it.
4. When the Link indicator turns solid green, the link between the remote controller and the built-in receiver has been successfully established.

Link Indicator	Status
▬▬▬	The remote controller is turned off and there is no 2.4GHz signal around, please turn on the remote controller.
●●●●●●	The receiver is ready for linking.
●●●●●●	There is 2.4GHz signal around but the remote controller is not linked with the receiver,

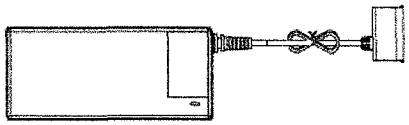
	please carry out the linking procedures.
[redacted]	The remote controller is linked with the receiver successfully.

4 Intelligent Battery

The intelligent battery is specially designed for the PHANTOM 2, with a battery capacity of 5200mAh, voltage of 11.1V and charge-discharge management functionality. The battery should only be charged with the DJI charger.



Intelligent Battery



Charger

DJI Intelligent Battery Functions

(1) Balance Charging	Automatically balance the voltage of each battery cell during charging.
(2) Capacity Display	Display the current battery level.
(3) Communicating	The main controller communicates with the battery via communication ports for battery voltage, capacity, current and other information.
(4) Overcharging Protection	Charging stops automatically when the battery voltage reaches 12.8V to prevent overcharging damage.
(5) Over Discharging Protection	Discharging stops automatically when the battery voltage reaches 8.4V to prevent over discharging damage.
(6) Short Circuit Protection	Automatically cuts off the power supply when a short circuit is detected.
(7) Sleep Protection	The battery will enter sleep mode after 10 minutes of inactivity to save power. The static current is 10nA in sleep mode when the battery is powered on without connecting to other devices.
(8) Charging Temperature Detection	The battery will charge only when its temperature is within 0°C-55°C. If the battery temperature is out of this range, the battery will stop charging.

(1) Before use, please read and follow the user manual, disclaimer, and the warnings on the battery. Users take full responsibility for all operations and usage.

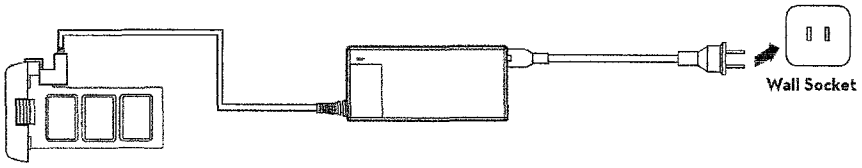
(2) The battery should only be charged with the charger provided by DJI. DJI does not take any responsibility for operation of any charger from a third party.

4.1 Charging Procedures

1. Connect the charger to a wall socket (Use the plug set if necessary).
2. Connect the battery to the charger. If the current capacity of the battery is over 75%, you should power on the battery to begin charging.
3. The Battery Level indicators display current capacity level as the battery charges. Please refer to battery

level indicator description for details.

4. The battery is fully charged when the Battery Level indicator lights are off. Please disconnect the charger and battery when the charging is completed.



4.2 Install the Battery

Push the battery into the battery compartment correctly as the following diagram shows. Make sure to push the battery into the compartment until you hear a 'click' sound.

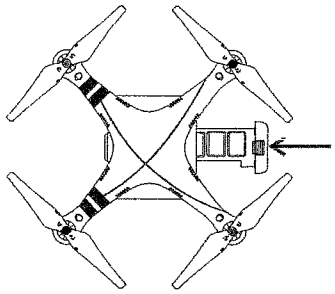


Figure 4-1

> An incorrectly inserted battery may cause one of the following to occur: (1) Bad contact. (2) Unavailable battery information. (3) Unsafe for flight. (4) Unable to take off.

4.3 Battery Usage

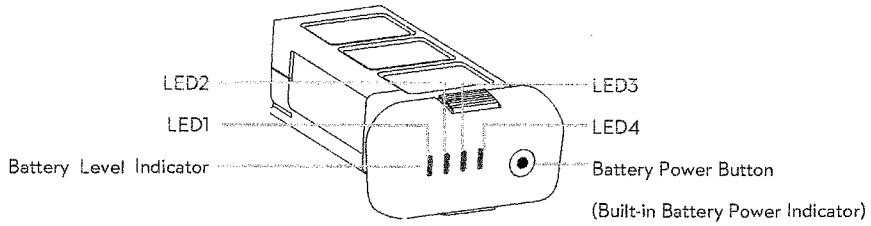


Figure 4-2

(1) Checking the battery level: When the battery is powered off; pressing the battery power button once will indicate the current battery level. Refer to < Battery Level Indicator Description> for details.

(2) Powering on: When the battery is powered off; press the battery power button once and then press and hold for 2 seconds to turn on the intelligent battery.

(3) Powering off: When the battery is powered on; press the battery power button once and then press and hold for 2 seconds to turn off the intelligent battery.

(4) Checking the battery life: When the battery is powered off; press and hold the battery power button for 5 seconds to check the battery life. The battery level indicators will show the life and the battery power indicator will blink for 10 seconds, then all LEDs will light out and the intelligent battery will turn off. Refer to < Battery Level Indicator Description> for details.

More battery information is available in the battery tab of the PHANTOM 2 Assistant.

4.4 Description of the Battery Level Indicator

The battery level indicators will show the current battery level during both the charging and discharging process as well as battery life. The following is a description of the indicators.

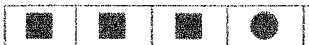
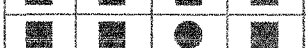
: The LED is solid on : The LED will blink regularly

: The LED is light off

Charging process				
LED1	LED2	LED3	LED4	**Current battery level**
				0%~25%
				25%~50%
				50%~75%
				75%~100%
				Full charged

Discharging process				
LED1	LED2	LED3	LED4	**Current battery level**
				87.5%~100%
				75%~87.5%
				62.5%~75%
				50%~62.5%
				37.5%~50%
				25%~37.5%
				12.5%~25%
				0%~12.5%
				<0%

Battery life				
LED1	LED2	LED3	LED4	**Current battery life**
				90%~100%

	80%~90%
	70%~80%
	60%~70%
	50%~60%
	40%~50%
	30%~40%
	20%~30%
	Less than 20%

4.5 Correct Battery Usage Notes

1. Never plug or unplug the battery into the aircraft when it is powered on.
2. The battery should be charged in an environment that is between 0℃ to 40℃, and be discharged in an environment that is between -20℃ to 50℃. Both charging and discharging should be in an environment where the relative humidity is lower than 80%.
3. It's recommended to charge and discharge the battery thoroughly once every 20 charge/discharge cycles. Users should discharge the battery until there is less than 8% power left or until the battery can no longer be turned on. Users should then fully recharge the battery to maximum capacity. This power cycling procedure will ensure the battery is working at its optimal level.
4. For long term storage please place the battery with only a 40~50% capacity in a strong battery box securely. We recommend discharging and charging the battery completely once every 3 months to keep it in good condition. The capacity should be varied in such a cycle (40%~50%)—0%—100%—(40%~50%).
5. It's suggested you purchase a new battery after you have discharged your current battery over 300 times. Please completely discharge a battery prior to disposal.
6. It's suggested that you purchase a new battery if the current battery is swollen or damaged in any way.
7. Never try to recharge or fly with a battery that is swollen or damaged in any way.
8. Never charge the battery unattended. Always charge the battery on a non-flammable surface such as concrete and never near any flammable materials.
9. Safety is extremely important and users can get more information in the DISCLAIMER.

5 Calibrating the Compass

IMPORTANT: Make sure to perform the Compass Calibration procedures prior to the first flight.

The compass is very sensitive to electromagnetic interference which causes abnormal compass data and leads to poor flight performance or even flight failure. Regular calibration of the compass enables the compass to perform at its optimal level.

5.1 Calibration Warnings

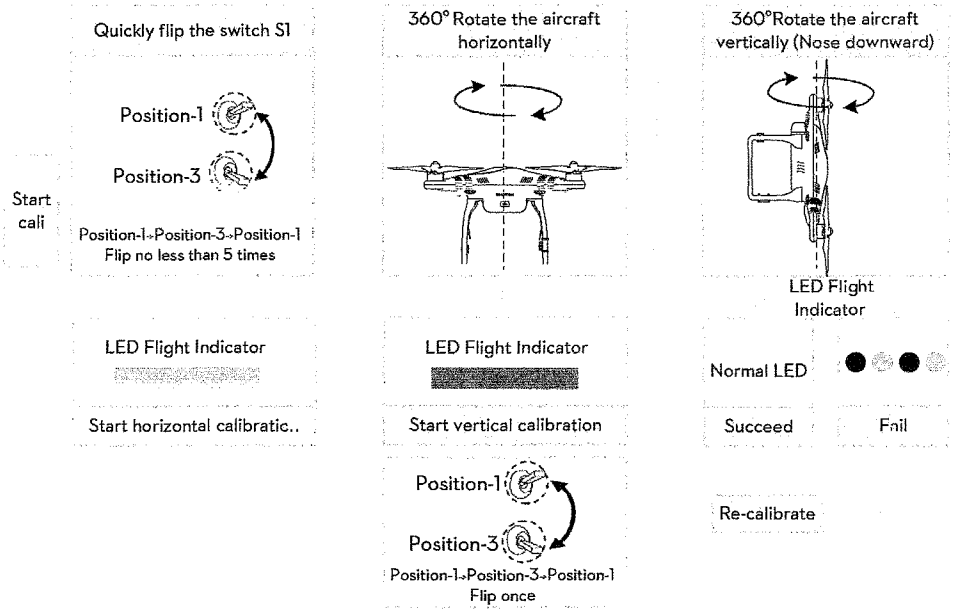
(1) DO NOT calibrate your compass where there is a possibility for the existence of strong magnetic interference such as magnetite, parking structures, and steel reinforcement underground.

(2) DO NOT carry ferromagnetic materials with you during calibration such as keys or cellular phones.

(3) Compass Calibration is very important; otherwise the flight control system will work abnormally.

5.2 Calibration Procedures

Please carry out the calibrating procedures in the flight field before flight. Please watch the quick start video of the PHANTOM 2 for more compass calibration details.



5.3 When Recalibration is required

(1) When Compass Data is abnormal, the LED flight indicator will blink alternating between red and yellow.

(2) Last compass calibration was performed at a completely different flying field/location.

(3) The mechanical structure of the aircraft has changed, i.e. changed mounting position of the compass.

(4) Evident drifting occurs in flight, i.e. the aircraft doesn't fly in straight lines.

6 Flight

6.1 Flying Environment Requirements

(1) Before your first flight, please allow yourself some flight training (Using a flight simulator to practice flying, getting instruction from an experienced person, etc.).

(2) DO NOT fly in bad weather, such as rain or wind (more than moderate breeze) or fog.

(3) The flying field should be open and void of tall buildings or other obstacles; the steel structure within buildings may interfere with the compass.

(4) Keep the aircraft away from obstacles, crowds, power lines, trees, lakes and rivers etc.

(5) Try to avoid interference between the remote controller and other wireless equipment (No base stations or cell towers around).

(6) The flight control system will not work properly at the South Pole or North Pole.

(7) Never use the aircraft in a manner that infringes upon or contravenes international or domestic lays and regulations.

6.2 Starting the Motors

A Combination Stick Command (CSC) is used to start the motors. Push the sticks according to one of the options below to start motors. Once the motors have started, release both sticks simultaneously. The same CSC is used to stop the motors.

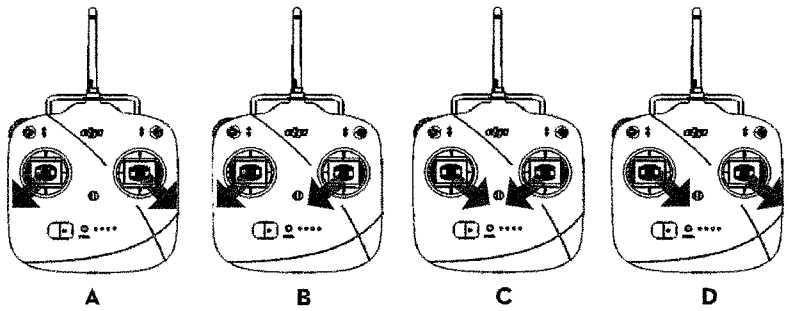


Figure 6-1

6.3 Takeoff/Landing Procedures

1. Start by placing the PHANTOM 2 on the ground with the battery level indicators facing you.
2. Turn on the remote controller.
3. Power on the aircraft by turning on the intelligent battery.
4. When LED flight indicator blinks green/yellow, the PHANTOM 2 is entering Ready to Fly/Ready to Fly (non-GPS) mode. Start the motors with the CSC command.
5. Push the throttle stick up slowly to lift the aircraft off the ground. Refer to <Remote Controller Operation> for more details.
6. Be sure you are hovering over a level surface. Pull down the throttle stick to descend. The stick will lock into

place and the aircraft will descend steadily.

7. After landing, leave the throttle stick down for 3 to 5 seconds to stop the motors. Return throttle stick to middle position after the motors have stopped.

You SHOULD NOT execute the CSC during normal flight! This will stop the motors and cause the aircraft to descend rapidly and drop without any type of control.

(1) When the LED flight indicator blinks yellow rapidly during flight, the aircraft has entered into Failsafe mode, refer to <Failsafe Function> for details.

(2) A low battery capacity warning is indicated by the LED flight indicator blinking red slowly or rapidly during flight. Refer to the <Low Battery Capacity Warning Function> for details.

(3) Watch the quick start video about flight for more flight information.

(4) Aircraft and battery performance is subject to environmental factors such as air density and temperature. Be very careful when flying 3000 meters (9800 feet) or more above sea level, as battery and aircraft performance may be reduced.

(5) When used with a H3-3D gimbal, a GoPro camera, and the iOSD mini, your Phantom 2 will be very close to its maximum takeoff weight. It is not recommended that you attach the Phantom 2 propeller guards at this weight. Otherwise, the aircraft will be unable to fly normally.

6.4 Failsafe Function

The aircraft will enter Failsafe mode when the connection from the remote controller is lost. The flight control system will automatically control the aircraft to return to home and land to reduce injuries or damage. The following situations would make the aircraft fail to receive a signal from the remote controller and enter Failsafe mode:

(1) The remote controller is powered off.

(2) The remote controller is powered on but the S1 is toggled in the position triggering the Failsafe (this must have been configured in the PHANTOM 2 Assistant).

(3) The aircraft has flown out of the effective communication range of the remote controller.

(4) There is an obstacle obstructing the signal between the remote controller and the aircraft, essentially reducing the distance the signal can travel.

(5) There is interference causing a signal problem with the remote controller.

Failsafe works differently depending on the mode the aircraft is in when Failsafe mode is initiated whether it is in the Ready to Fly or Ready to Fly (non-GPS) mode.

Ready to Fly (non-GPS) --- Automatic landing

The flight control system will try to keep the aircraft level during descent and landing. Note that the aircraft may be drifting during the descent and landing process.

Ready to Fly --- Automatic go home and land

The flight control system will automatically control the aircraft to fly back to the home point and land.

Home Point

When the aircraft is initializing the Ready to Fly status, the aircraft will record the current GPS coordinates as the home point. It is recommended to lift off only after Ready to Fly status is confirmed for the safety of being able to fly back to home point successfully in case the Failsafe mode is initiated.

Go Home Procedures

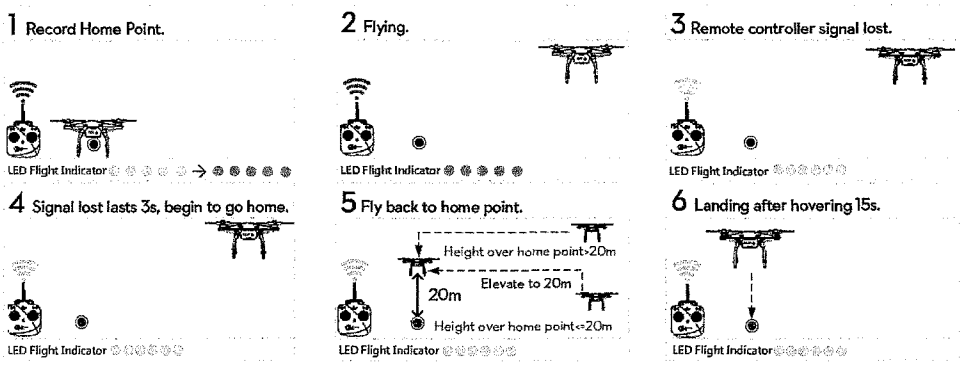


Figure 6-2

(1) In a Failsafe situation, if less than 6 GPS satellites are found for more than 20 seconds, the aircraft will descend automatically.

(2) When the aircraft is landing automatically, users can control the aircraft's position and altitude if the remote controller signal is recovered.

In Phantom 2 mode, users can set a new home point manually when the aircraft is in "Ready to fly" status as long as a home point has been recorded automatically. Quickly flipping the S2 switch of the remote controller from upper most to lower most positions 5 times or more will reset the current aircraft position as a new home point of PHANTOM 2. When successfully reset, you will see a series of rapid green blinks on the LED Flight Indicator. The definition of "home point" is:

(1) The home point is the place PHANTOM 2 returns to when the control signal is lost, which is recorded last time.

(2) The home point is used to calculate the horizontal distance between you and the aircraft, the distance will be displayed as D if using iOSD module.

Regaining Control during Failsafe Procedure

Position of Switch S1	Position-1	Position-2	Position-3 (No triggering the Failsafe)
How to regain control	When the S1 switch is switched to Position-1, toggle the S1 switch to any other position once to regain control. If remote controller's signal is recovered, control is returned back to the pilot.	Regain control as soon as signal is recovered.	

6.5 Low Battery Capacity Warning Function

The low battery capacity warning alerts users when the battery is close to depletion during flight. When it appears, users should promptly fly back and land to avoid accidental damage. The PHANTOM 2 has two levels of low battery capacity warning. The first appears when the battery has less than 30% power and the second appears when it has less than 15% power.

(1) When battery power drops below 30% and LED indicator will blink red slowly.

(2) At lower than 15% the LED indicator will blink red rapidly, the PHANTOM 2 will also begin to descend and land automatically. After it has landed, keep the throttle stick at its lowest point or execute CSC.

(3) There is a hidden third low battery threshold in addition to the 1st and 2nd level warnings. This uses 10.65V as its threshold. Both this voltage threshold and the 2nd Level Low Battery Warning will trigger auto-landing. Altitude can be maintained if necessary by pushing up on the throttle stick.

(1) Remember to fly your PHANTOM 2 back as soon as you see a low battery capacity warning.

(2) Keeping the battery contact needles and pads clean is very important. Any dirt and dust may cause a communication failure.

6.6 Flight Limits Function

All UAV (unmanned aerial vehicle) operators should abide by all regulations from such organizations at ICAO (International Civil Aviation Organization) and per country airspace regulations. For safety reasons, the flight limits function is enabled by default to help users use this product safely and legally. The flight limits function includes height, distance limits.

In Ready to Fly status, height, distance limits works together to restrict the flight. In Ready to Fly (non-GPS) status, only height limit works and the flying height restricted to be not over 120m.

(1) The default parameters in the Assistant is compliant within the definitions of class G ruled by ICAO. (Refer to Airspace Classification to get more details). As each country has its own rules, make sure to configure the parameters to comply with these rules too, before using the PHANTOM 2.

(2) Users in Mainland China can refer to 民用航空空域使用办法.

Max Height & Radius Limits

The Max Height & Radius restricts the flying height and distance. Configuration can be done in the PHANTOM 2 Assistant. Once complete, your aircraft will fly in a restricted cylinder.

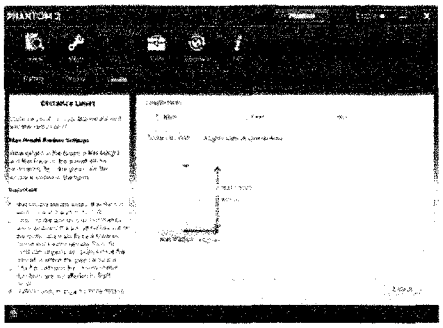


Figure 6-3

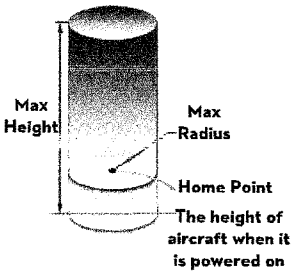


Figure 6-4

Ready to Fly			
	Limits	**Ground Station**	**Rear LED flight indicator**
Max Height	The flight height is restricted to fly under the max height.	Warning: Height limit reached.	None.
Max Radius	The flight distance is restricted to fly within the max radius.	Warning: Distance limit reached.	Rapid red flashings when close to the Max radius limit.

Ready to Fly(non-GPS)			
	Flight Limits	**Ground Station**	**Rear LED flight indicator**
Max Height	The flight height is restricted to fly under the minor height between the Max height and 120m.	Warning: Height limit reached.	None.
Max Radius	Not limited, no warnings or LED indicators.		

(1) If the aircraft flies out of the limits, you can still control your aircraft except to fly it further away.

(2) If the aircraft is flying out of the max radius in Ready to Fly (non-GPS) status, it will fly back within the limits range automatically if 6 or more GPS satellites have been found.

6.7 Flight Limits of Special Areas

Special areas include airports worldwide. All special areas are listed on the DJI official website. Please refer to http://www.dji.com/fly-safe/category-mc for details. These areas have been divided into category A and category B.

Semi-automatic descent: All stick commands are available except the throttle stick command during the descent and landing process. Motors will stop automatically after landing. Users will regain control once the motors have stopped. There is no need to toggle the S1 switch.

(1) When flying in the airspace (A/B/C) of restricted special area, LED flight indicators will blink red  quickly and continue for 3 seconds, then switch to indicate current flying status and continue for 5 seconds at which point it will switch back to red blinking.

(2) For safety reasons, please do not fly close to airports, highways, railway stations, railway lines, city centers and other special areas. Try to ensure the aircraft is visible.

6.8 Conditions of Flight Limits

In different working modes and flight modes, flight limits will differ according to number of GPS satellites found. The following table demonstrates all the cases(**√: available;** ×:unavailable).

All flights are restricted by height, distance and special areas simultaneously.

Phantom mode			
Flight Status	**Limits of Special Area**	**Max Height**	**Max Radius**
Ready to Fly	√	√	√
Ready to Fly (non-GPS)	×	√	×

Naza-M mode				
Control Mode	**number of GPS found**	**Limits of Special Area**	**Max Height**	**Max Radius**
GPS	≥6	√	√	√
	<6	×	√	×
ATTI.	≥6	√	√	×
	<6	×	√	×
Manual	≥6	×	×	×
	<6	×	×	×

Disclaimer

Please ensure that you are kept up to date with International and Domestic airspace rules and regulations before using this product. By using this product, you hereby agree to this disclaimer and signify that you have read this fully. You agree that you are responsible for your own conduct and content while using this product, and for any direct or indirect consequences caused by not following this manual, violate or disregard any other applicable local laws, administrative rules and social habits thereof.

'7 Assistant Installation and Configuration

7.1 Installing Driver and PHANTOM 2 Assistant

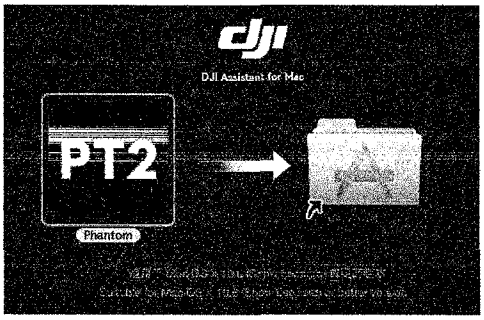
Installing and running on Windows

1. Download driver installer and Assistant installer in EXE format from the download page of PHANTOM 2 on the DJI website.
2. Connect the PHANTOM 2 to a PC via a Micro-USB cable.
3. Run the driver installer and follow the prompts to finish installation.
4. Next, run the Assistant installer and follow the prompts to finish installation.
5. Double click the PHANTOM 2 icon on your Windows desktop to launch the software.

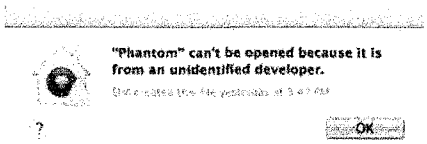
The installer in EXE format only supports Windows operating systems (Win XP, Win7, Win8 (32 or 64 bit)).

Installing and running on Mac OS X

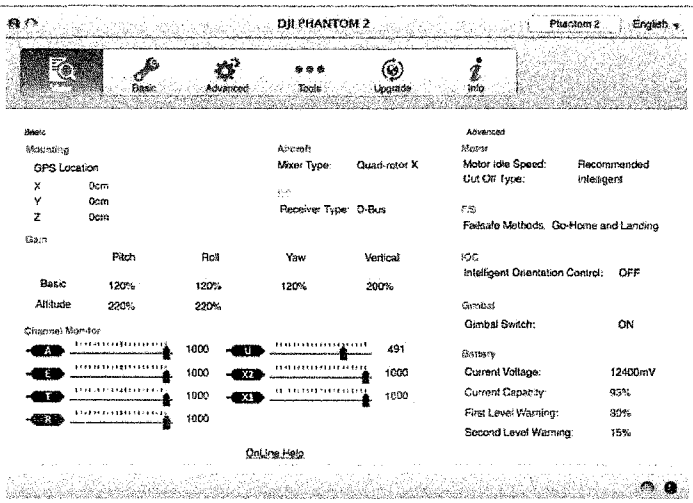
1. Download the Assistant installer in DMG format from the download page of PHANTOM 2 on the DJI website.
2. Run the installer and follow the prompts to finish installation.



3. When launching for the first time if use Launchpad to run the PHANTOM 2 Assistant, Launchpad won' t allow access because the software has not been reviewed by Mac App Store.



4. Locate the PHANTOM 2 icon in the Finder, press the Control key and then click the PHANTOM 2 icon (or right-click the PHANTOM 2 icon using a mouse). Choose Open from the shortcut menu, click open in the prompt dialog box and then software will launch.
5. After the first successful launch, directly launching of the software can be achieved by double-clicking the PHANTOM 2 icon in the Finder or using Launchpad.

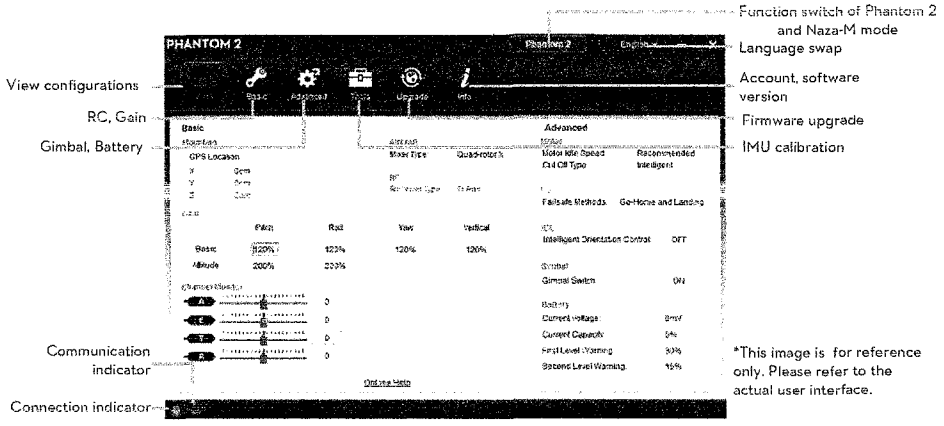


Installer in DMG format supports only Mac OS X 10.6 or above.

Usage of PHANTOM 2 Assistant on Mac OS X and Windows are exactly the same. The Assistant pages appear in other places of this manual are on the Windows for example.

7.2 Using the PHANTOM 2 Assistant on a PC

1. Start up the PC, power on the PHANTOM 2, then connect the PHANTOM 2 to the PC with a Micro-USB cable. DO NOT disconnect until configuration is finished.
2. Run the PHANTOM 2 Assistant and wait for the PHANTOM 2 to connect to the Assistant. Observe the indicators on the bottom of the screen. When connected successfully, the connection indicator is and communication indicator is blinking .
3. Choose [Basic] or [Advanced] configuration pages.
4. View and check the current configuration in the [View] page.



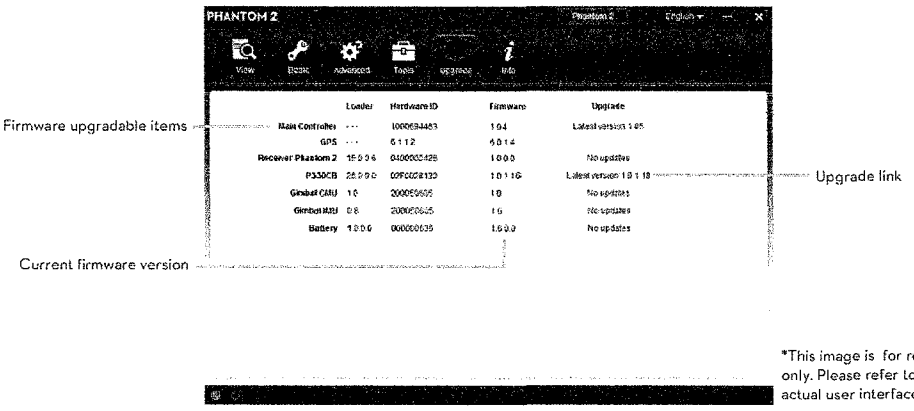
(1) Users should not enable the Naza-M function before finishing Advanced Flight Maneuvers procedure in the " PHANTOM Pilot Training Guide". If the Naza-M mode is enabled, users can switch the control mode between ATTI. Mode, GPS Mode or Manual Mode, and access the advanced settings (e.g. IOC). In addition, the LED located on the rear frame arms will display Naza-M flight status indications instead of the PHANTOM 2's indicators. Do not enable the Naza-M mode unless you are an experienced user or guided by a professional.

(2) You can change to the Phantom 2 mode by clicking the same button used to turn on the Naza-M mode. This operation will disable the Naza-M mode and enable Phantom 2 mode. All parameters will be returned to factory settings.

7.3 Firmware upgrade of PHANTOM 2

Please refer to the PHANTOM 2 Assistant to install driver and PHANTOM RC Assistant, and then follow the procedures below to upgrade the software and firmware; otherwise the PHANTOM 2 might not work properly.

1. An internet connection is required to upgrade PHANTOM 2's firmware.
2. Click the [Upgrade] icon to check the current firmware version and whether the installed firmware is the latest version. If not, click the relative links to upgrade.
3. Be sure to wait until the Assistant shows "finished". Click OK and power cycle the PHANTOM 2 after 5 seconds. Once completed, the firmware is up to date.



*This image is for reference only. Please refer to the actual user interface.

(1) DO NOT power off until the upgrade is finished.

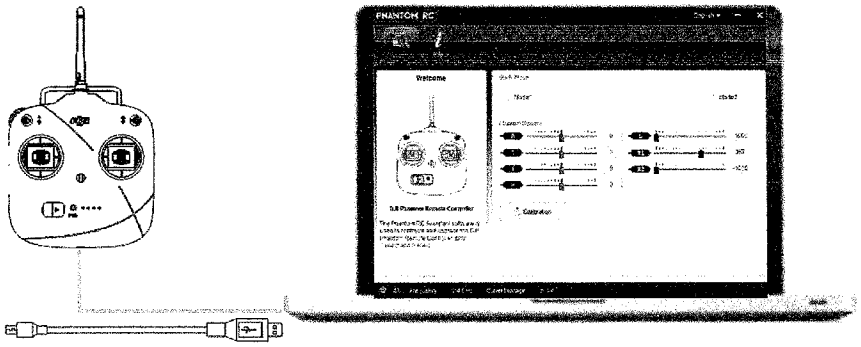
(2) If the firmware upgrade failed, the main controller will enter a waiting for firmware upgrade status automatically. If this happens, repeat the above procedures.

Firmware upgradable items: (1) Main Controller (2) P330CB(Main Board) (3) Receiver (4) Gimbal CMU (5) Gimbal IMU (6) Battery

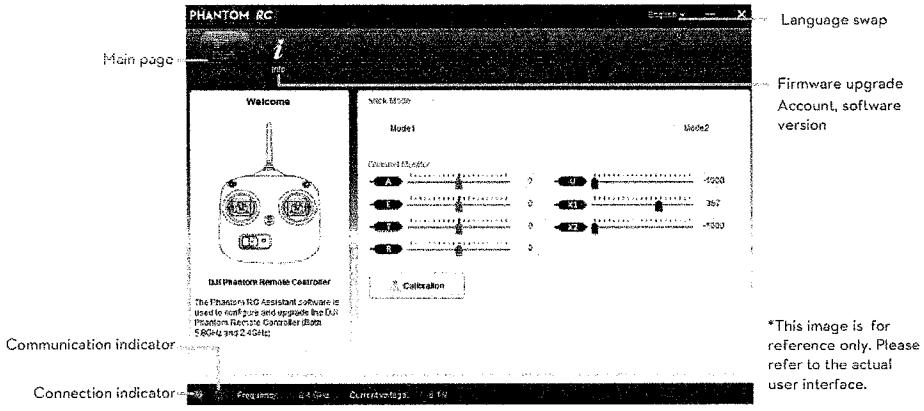
7.4 PHANTOM RC Assistant Description

Please follow the procedures to finish the configuration of the remote controller.

1. Turn off the remote controller and find the Micro-USB port on the bottom of it.
2. Start up the PC, power on the remote controller, and then connect the remote controller to the PC with a Micro-USB cable. DO NOT disconnect until the configuration is finished.
3. Run the PHANTOM RC Assistant and wait for the remote controller to connect to the Assistant. Observe the indicators on the bottom left of the screen. When connected successfully, the connection indicator is and communication indicator is blinking.
4. Finish configuration in the [Main] page.
5. Finish upgrade in the [Info] page if necessary.



Main Page of the 2.4GHz Remote Controller



8 Appendix

8.1 Specifications

Aircraft	
Operating environment temperature	-10°C to 50°C
Power consumption	5.6W
Supported Battery	DJI Intelligent battery
Weight (including the battery)	1000g
Take-off Weight	≤1300g
Hovering Accuracy (Ready to Fly)	Vertical: 0.8m; Horizontal: 2.5m
Max Yaw Angular Velocity	200°/s
Max Tilt Angle	35°
Max Ascent / Descent Speed	Ascent: 6m/s; Descent: 2m/s
Max Flight Speed	15m/s (Not Recommended)
Wheelbase	350mm
2.4GHz Remote Controller	
Operating Frequency	2.4GHz ISM
Communication Distance (open area)	1000m
Receiver Sensitivity (1%PER)	-97dBm
Working Current/Voltage	120 mA@3.7V
Built-in LiPo Battery Working Current/Capacity	3.7V, 2000mAh
DJI Intelligent Battery	
Type	3S LiPo Battery
Capacity	5200mAh, 11.1V
Charging Environment Range	0°C to 40°C
Discharging Environment Range	-20°C to 50°C

8.2 LED Flight Indicators Description

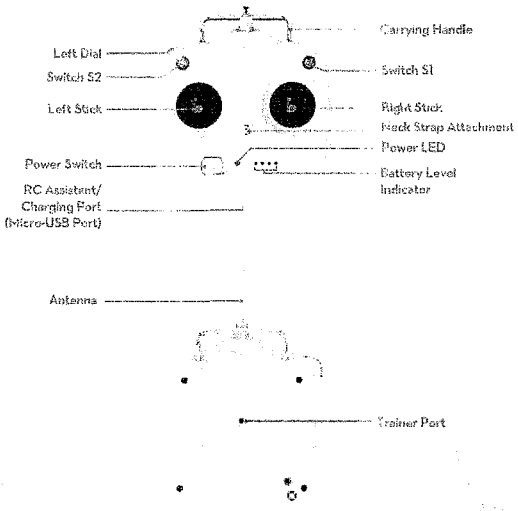
Aircraft in Normal status	**Descriptions**
	Power On Self-Test
	Warming Up & Aircraft cannot take off during warming up
	Ready to Fly
	Ready to Fly (non-GPS)
Aircraft in abnormal status	**Warnings and errors**
	Remote Controller Signal Lost
	1st Level Low Battery Capacity Warning

●●●●●●	2nd Level Low Battery Capacity Warning
●●●	Not Stationary or Sensor Bias is too big
[redacted]	Errors & Aircraft cannot fly.*
● ● ●	Compass data abnormal because of ferro-magnetic interference or the compass needs calibration.

* Users can connect to the PHANTOM 2 Assistant to get detailed information about warnings and errors.

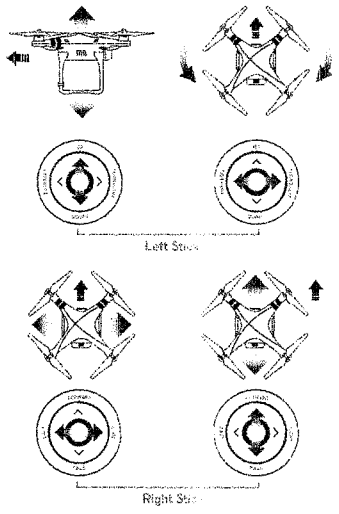
PHANTOM 2

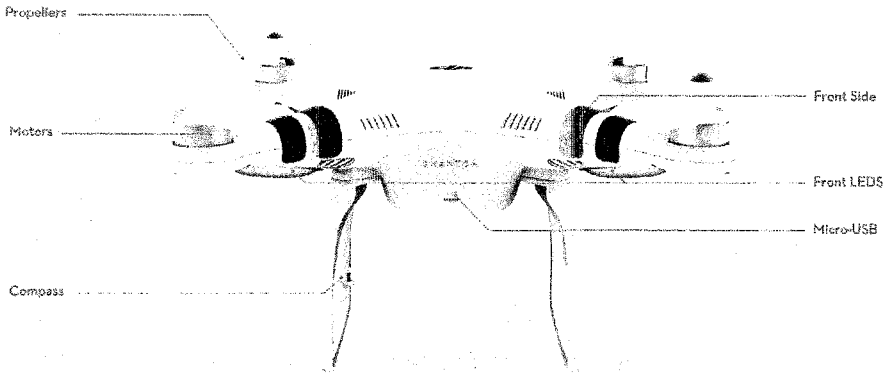
QUICK START GUIDE

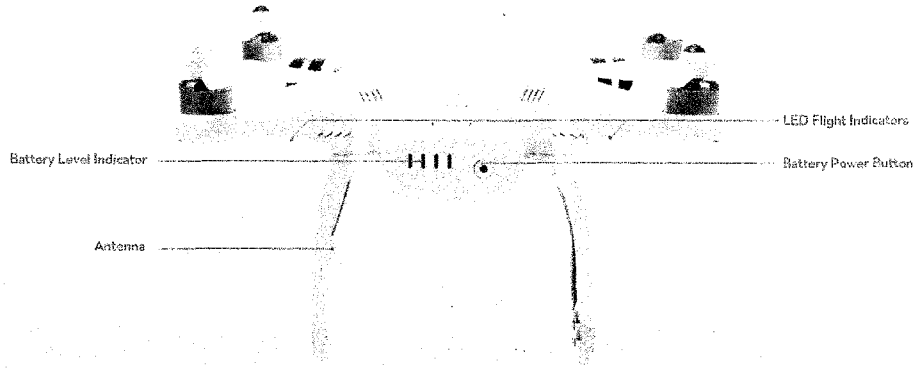


Basic Flight Operations

Forward Direction (Indicates Front Side)







PHANTOM 2

QUICK START GUIDE

0

Scan QR Code to Watch the Quick Start Video or browse direct to www.dji.com/tutorial/phantom-2-tutorial/

① Product Introduction

② Quick Start Guide

③ H3-2D Gimbal Assembly

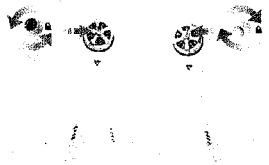
⚠ ATTENTION: For SAFETY reasons and for further flight instruction, it is advised that you watch the videos above in full before attempting to use the Phantom 2.

1

ATTACHING THE PROPELLERS

- Remove the four warning cards from the motors.
- Screw the propellers, clockwise for gray nuts and anticlockwise for black nuts, onto the four motors. Be sure to match the black propeller nuts with the black dot motors.

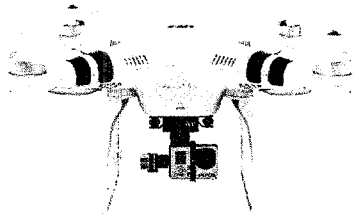
⚠ ATTENTION: DO NOT use thread lock on the propeller shafts.



2

SETUP OF THE ZENMUSE H3-2D GIMBAL (OPTIONAL)

- The ZENMUSE H3-2D gimbal is recommended for a better aerial photography experience. The installation is quick and convenient, as the GCU and other control interfaces have been built into the Phantom 2.
  Please refer to the "H3-2D Gimbal Quick Start Guide" for more details.

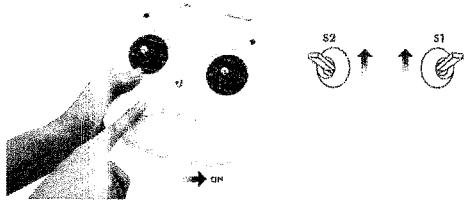


3

PREPARING THE REMOTE CONTROLLER

- Be sure S1 and S2 are switched to the upper most position.
- Push the Power Switch to the right to power on the Remote Controller. The LED will go green if the Remote Controller is functioning. The Battery Level Indicator displays the current battery level.

⚠ Important: A red blinking and a continuous beeping from the Remote Controller indicate LOW BATTERY VOLTAGE. Recharge the Battery when there is only one LED remains blinking.

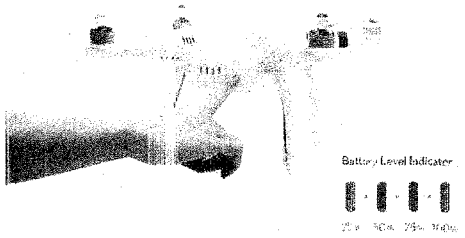


4

TURNING THE FLIGHT BATTERY ON/OFF

- Press the circular button once, then press and hold for 2 seconds to turn on the flight battery.
- Press the circular button once, then press and hold for 2 seconds to turn off the flight battery.

⚠ ATTENTION: Pressing the circular button once with no further action will indicate current BATTERY LEVEL.



5

LED FLIGHT INDICATORS

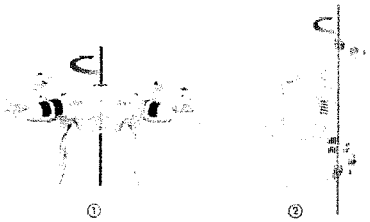
- Slow green flashing indicates ready to fly with GPS.
- Slow yellow flashing indicates ready to fly without GPS.
- Fast yellow flashing indicates your Remote Controller is switched off.
- Fast red flashing indicates low flight battery level.
- Please refer to the card attached to the Remote Controller for more details.

6

CALIBRATING THE COMPASS

- Rapidly flip the S1 switch from the "fully up" to the "fully down" positions for at least 5 times.
- Once the LED Flight Indicators change to display solid yellow, the compass calibration mode has been initiated.
- Holding the Phantom 2 horizontally, rotate it 360° on its center axis until the LED Flight Indicators switch to solid green.
- Then while holding the Phantom 2 vertically, rotate 360° on its center axis until the LED Flight Indicators light disappears.

⚠ ATTENTION: If the LED Flight Indicators flash between yellow and red, then the process has FAILED. You must start over and repeat the previous steps until the process is successful.

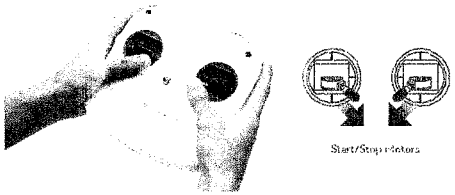


7

BEGINNING YOUR FIRST FLIGHT

- Start by placing the Phantom 2 on the ground with the Battery Level Indicator facing yourself.
- Switch on the Remote Controller.
- Turn on the flight battery.
- Pull both sticks on the remote controller to lower corners as shown to start/stop the motors.
- Start flying.

⚠ ATTENTION: ONLY stop the motors after the Phantom 2 has landed. DO NOT stop the motors during flight!



PHANTOM 2 User Manual V1.4

For PHANTOM 2 Flight Controller Firmware version V3.10

& PHANTOM 2 Assistant version V3.8

& PHANTOM RC Assistant version V1.1

2015.01

Congratulations on purchasing your new DJI product. Please thoroughly read the entire contents of this manual to fully use and understand the product.

It is advised that you regularly check the PHANTOM 2 's product page at **www.dji.com** which is updated on a regular basis. This will provide services such as product information, technical updates and manual corrections. Due to any unforeseen changes or product upgrades, the information contained within this manual is subject to change without notice.

If you have any questions or concerns regarding your product, please contact your dealer or DJI Customer Service.