The Futaba PCM system has a failsafe condition that adjusts each of the control servos to a specified position in the event of lost link, which includes conditions due to total loss of signal, loss of clean signal and low receiver battery. The failsafe settings are as follows:

(a) Throttle goes to idle

(b) Ailerons go to neutral

(c) Elevators go to neutral

(d) Rudders go to 9% left hand yaw

This condition causes the aircraft to descend with a continuous shallow left-hand spiral turn until impact.