# LOST LINK PROCEDURES

## Aeryon Scout
Proceed direct home way-point at last altitude.  After reaching home way-point, perform autonomous descent to surface

## AirRobot 100B
Continue flight for 30 seconds, climb to highest altitude reached on way to current position (in the TAAC Conference flight no higher than 400'), turn toward home way-point, fly direct home position, after reaching home way-point perform autonomous descent to surface.

## Draganflyer X6
Automatically descend at loss of link point to surface.

## T-Hawk
Proceed direct home way-point at last altitude.  After reaching home way-point , perform autonomous descent to surface.

## Raven B
Proceed direct home-way point at last altitude.  After reaching home way-point perform autonomous descent to surface.

## Wasp III
Proceed direct home-way point at last altitude.  After reaching home way-point perform autonomous descent to surface.