

Luncheon Panel: Have We Arrived In the Jetsons' Orbit City?



- **Moderator: Earl Lawrence**, Director, FAA UAS Integration Office
- **Anil Nanduri**, Vice President, New Technology Group, Intel
- **Charles Bergan**, Vice President, Engineering, Qualcomm Technologies, Inc.
- **Travis Mason**, Vice President of Public Policy & Regulatory Affairs, A³ by Airbus
- **Mark Moore**, Engineering Director of Aviation, Uber

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Future sUAS Challenges

The background features several faint, light-blue icons: a location pin, a thumbs-up gesture, and a circular arrow, all overlaid on a pattern of concentric dashed circles.

Charles Bergan
VP Engineering, Qualcomm Research
Qualcomm Technologies, Inc.
March 28, 2017



Why Wait™

30

years of driving
the evolution of
wireless

#1

fabless
semiconductor
company

#1

in 3G/4G
LTE modem

#1

in wireless
semiconductors



Qualcomm's application processor and communications expertise bring critical technologies to drones

Cellular connectivity



Safety enhancement for autonomous operation



Media sharing and payload status updates



Safety and operational communication for beyond operator's visual line of sight (BLOS)

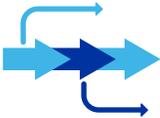


Redundant link within the operator's visual line of sight

On-board intelligence



Professional videography



Autonomous navigation

Machine Intelligence



Computer vision



High-fidelity sensor processing



Precise localization



Challenges in achieving scale

Can we do onboard obstacle recognition?

Can we do onboard obstacle avoidance?

Can we detect dangerous situations?

Can LTE work at 400 feet AGL?

Thank you

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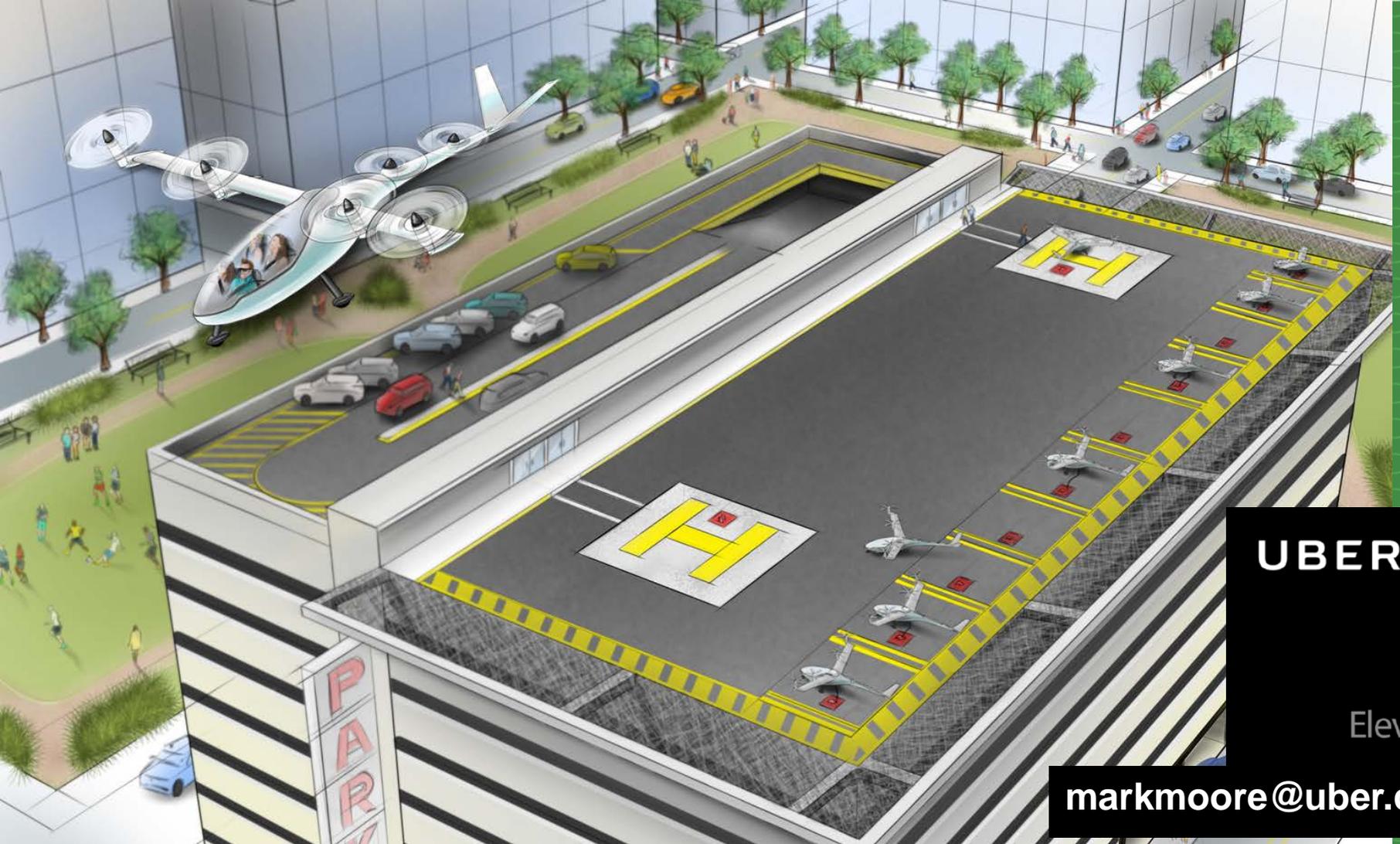
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UBER

Elevate

markmoore@uber.com

Helicopters Haven't Been A Sufficient Solution To Enable Aerial Urban Mobility





Stop The Helipad

San Francisco Residents Opposed to the San Francisco General Hospital Helipad

HOME SAVE LIVES SAFETY HEALTH FLIGHTS FAQs HELP US

San Francisco available Helicopter Landing Sites

In the event of a natural or man-made disaster, helicopters would land in any parking lot or wide intersection. The emergency landing sites shown below, are listed in the [SF Emergency Medical Services Agency Manual, Appendix B](#):



Helipad History in San Francisco

San Francisco residents have successfully battled helicopter danger and noise since the early 1960s. In the past, all helipad and helipad proposals have been defeated by concerned residents. For example:

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[Who will use SFGH helipad?](#)
[Environmental Impact](#)
[Property Values](#)
[Noise](#)
[Flight Paths](#)
[Helicopter Flight Costs](#)
[Fatal Helicopter Crashes](#)
[SFGH Neighbors' Comment](#)

Helicopter Barriers

Community Noise: 15+ dB Above Background Noise

Affordability: High Energy and Maintenance Cost

Safety: ~10x Lower than Autos

Scaled Market Barriers

Infrastructure Availability

Pilot Availability and Proficiency

Airspace for High Volume Urban Operations

Enabling Technologies

Electric Propulsion: Scale-free, Distributed Thrust

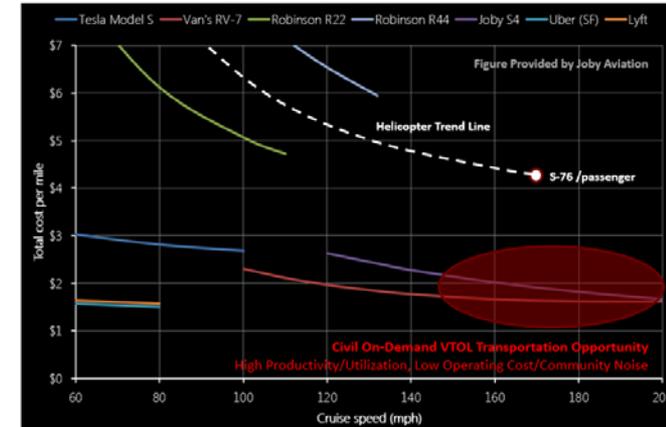
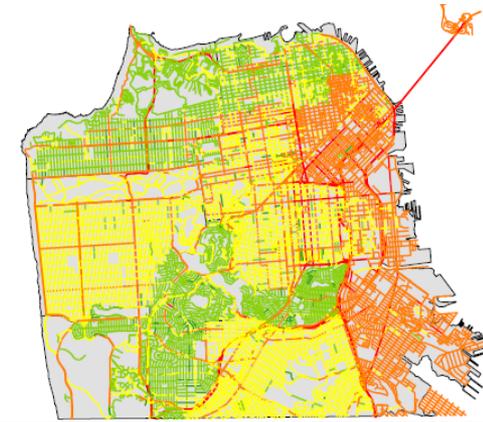
Noise: Match Background Urban Noise Levels

Safety: Multi-Engine Thrust Redundancy

Affordability: 3x Higher Lift/Drag, 3.2x Higher Motor Efficiency

Autonomy: Smart Avionics Linked to Sensors and Network

Safety: Reduced Pilot Error and Workload, Future Autonomous Ops





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Electric VTOL Gold Rush



Future of urban mobility

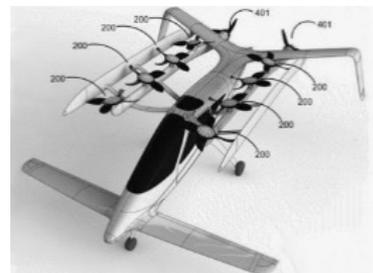
My kind of flyover

AVIATIONWEEK

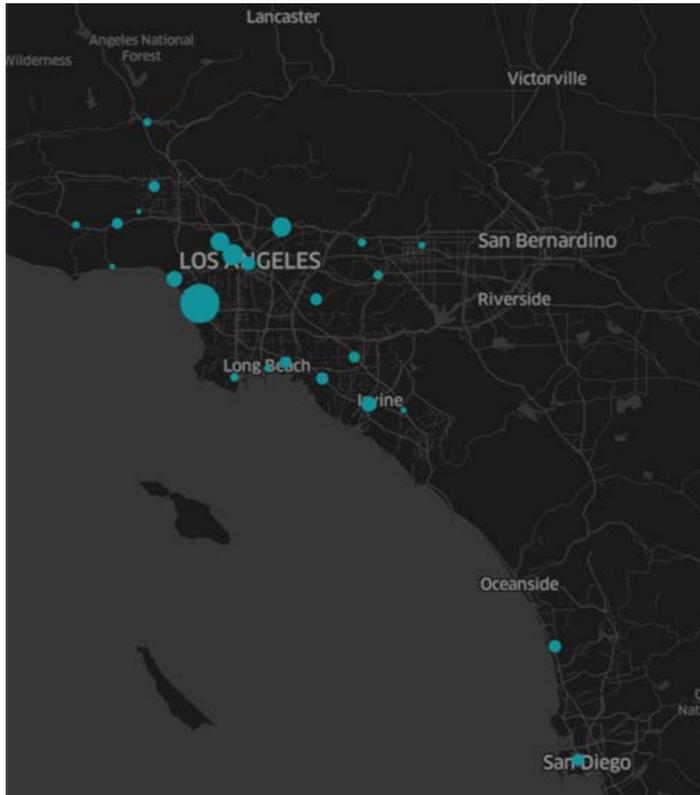
& SPACE TECHNOLOGY



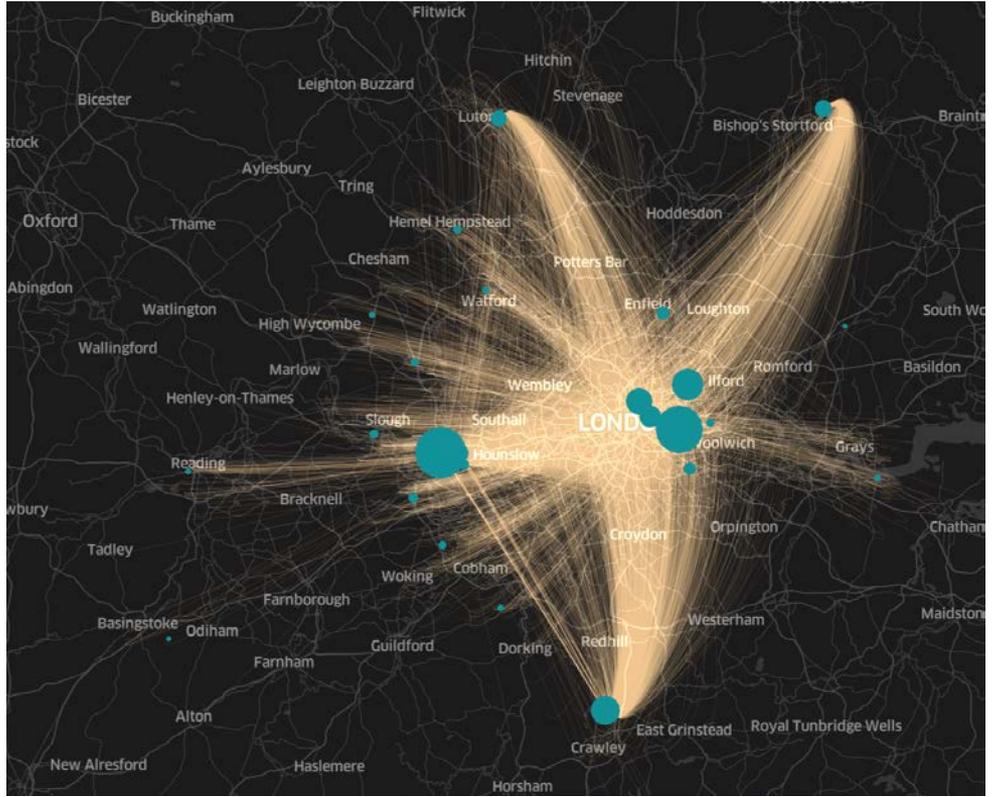
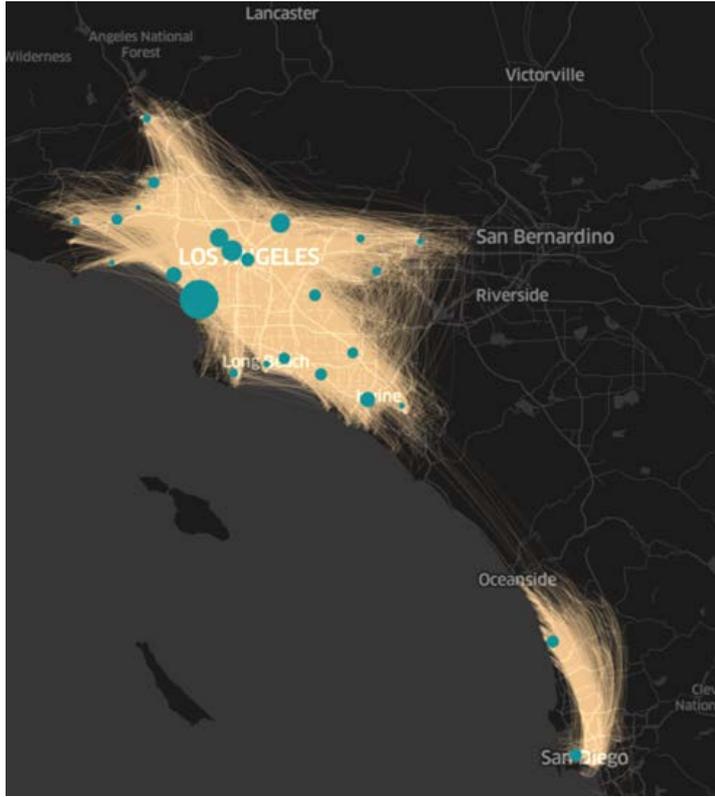
Venture Capital Moves In



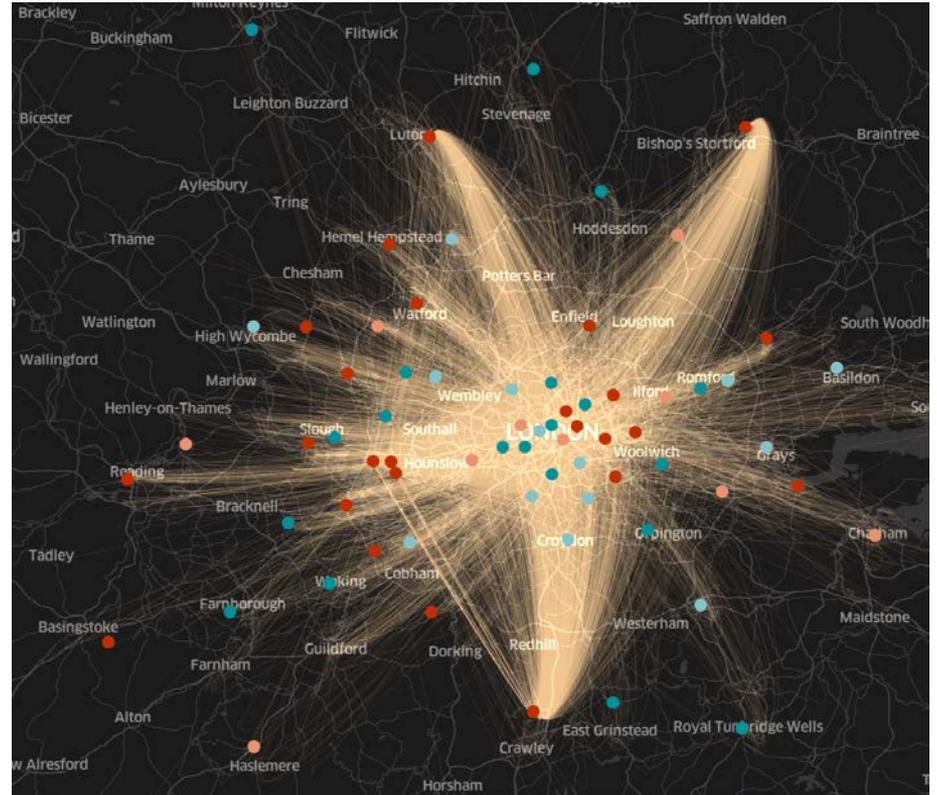
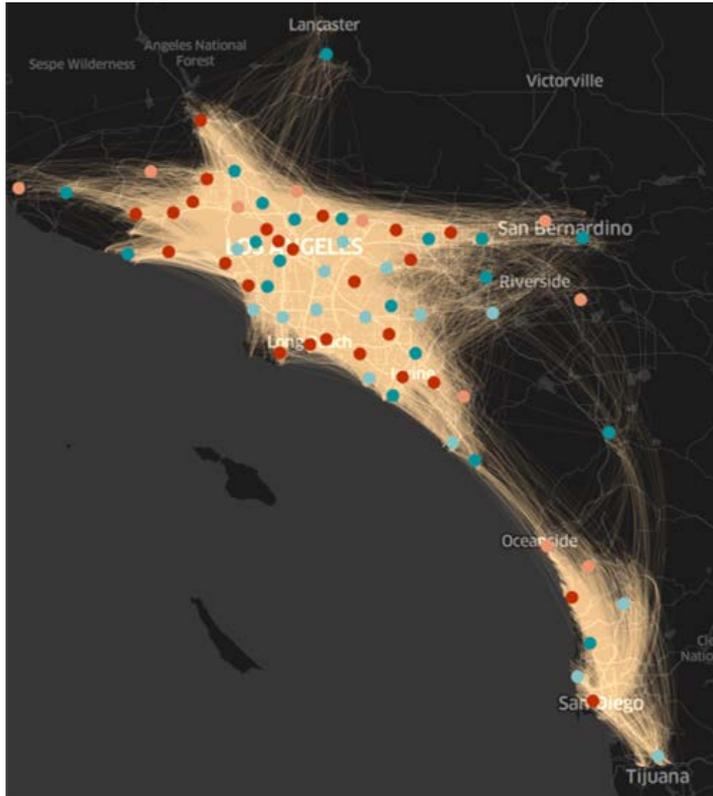
Demand Modeling and Infrastructure

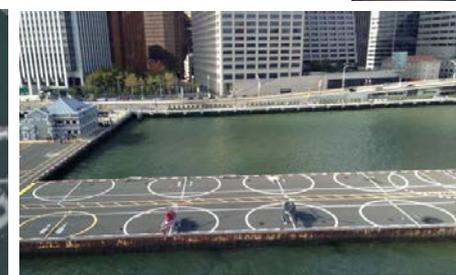


60% of LA's 20-100 mile Trips Satisfied with 25 Vertiports



Over Time, Even Greater Time Savings and Accessibility





2017 2018 2019 2020 2021 2022 2023 2024 2025 2026 2027 2028

**VEHICLE
PROTOTYPING**

**Experimental
certification
FAR Part 21.193**

**Initial Aircraft
Testing
(1-2 Aircraft)**

**Aircraft Test
Program
(3-5 Aircraft)**

**Production
Certificate
Development**

**Low Volume
Production
(10-50 Aircraft)**

**Urban
Public
Flight
Operations**

**FAA Part 135
Operation Cert
Approval**

Type Certificate Development

**Initial Demonstrator
Development/Fabrication
(VTOL Powered-Lift,
Electric, Fly-By-Wire,
Pilot-Aids)**

**Electric Propulsion System Cert
Triply Redundant Digital Fly By Wire
Control Cert
Software Cert**

**Performance
Validation
Testing**

**Flight Training
Maintenance
Testing**

**Operation Restrictions
Professional Pilot
Visual Flight Rules
20 min Reserves
15db Reduction
Helipad Infrastructure**

**FAA/ASTM
Electric Propulsion
Certification Rules**

**Initial Flight Operations
Testing in Urban
Environment Validated
Noise Acceptance**

**FAA/GAMA
Reduced Short
Range Electric
IFR Reserves**

\$10M - \$20M

\$150M - \$300M

Likely cost of initial flight demonstrator at 2-4 place

Likely cost of certification + production tooling

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Earl Lawrence, Director, FAA UAS Integration Office



Earl Lawrence is the Director of the Unmanned Aircraft Systems (UAS) Integration Office within the Federal Aviation Administration, which is responsible for the facilitation of all regulations, policies, and procedures required to support the FAA's UAS integration efforts. The office serves as a central point of contact for the international aviation community on UAS issues. Mr. Lawrence also represents the FAA on the Senior Steering Group of the UAS Executive Committee (ExCom) focusing on coordination and alignment of efforts among key federal government agencies.



Mr. Lawrence previously served as the Manager of the FAA's Small Airplane Directorate in Kansas City, Missouri, where he managed airworthiness standards, continued operational safety, policy, and guidance for small aircraft, gliders, light sport aircraft, airships, and balloons.

Prior to joining the FAA in 2010, Mr. Lawrence was the vice president of industry and regulatory affairs for the Experimental Aircraft Association (EAA) in Oshkosh, Wisconsin. Mr. Lawrence is a graduate of Northrop University in Los Angeles.

A pilot since 1987, Mr. Lawrence holds a commercial multi-engine pilot certificate as well as an airframe and power plant mechanic certificate with an Inspection Authorization. He currently owns and flies a Piper Twin Comanche.

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Anil Nanduri, Vice President, New Technology Group, Intel



Anil V. Nanduri is Vice President in the New Technology Group and General Manager of Unmanned Aviation Systems for the Perceptual Computing Group at Intel Corporation. He is responsible for Intel's unmanned aviation systems business and pursuing opportunities for growth in this segment. Prior to his current role, he was most recently responsible for new business opportunities for Intel® RealSense™ technology and building awareness.

During his Intel career, Mr. Nanduri has held roles encompassing chip design, platform enabling, and technical and product marketing. He served as chief of staff and technical assistant to the general manager of Intel's PC Client Group. From 2008 to 2010, Mr. Nanduri led netbook marketing at Intel, a role that included establishing the category and promoting its growth through marketing strategies and design wins. Earlier in his Intel career, he managed platform strategy and marketing for Intel's next-generation mobile platform.

Mr. Nanduri initially joined Intel in 1997 as a chipset design engineer. In 2007, he left to serve as director of marketing at Powercast Corporation, then rejoined Intel in 2008. His contributions to Intel's mobile platforms have earned him three Intel Achievement Awards.

Mr. Nanduri received his bachelor's degree in electrical and electronics engineering from the College of Engineering, Trivandrum, in India; and his master's degree in electrical engineering from Pennsylvania State University. He holds one U.S. patent, with another patent pending.



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Charles Bergan, Vice President, Engineering, Qualcomm Technologies, Inc.



Charles Bergan leads the software department for Qualcomm Research. He also oversees Qualcomm Research's robotics program. While at Qualcomm, he has been involved in the research and development of most of the modern cellular radio standards, including CDMA, UMTS, UMB and LTE.

Previously, Mr. Bergan led the software development team at Ensemble Communications, a start-up company which pioneered the development of LMDS point-to-multipoint wireless backhaul systems.

Mr. Bergan has a B.S. in computer engineering, and an M.S. in computer science, both from the University of California, San Diego.



Travis Mason, Vice President of Public Policy & Regulatory Affairs, A³ by Airbus



Travis G. Mason is the Vice-President of Public Policy and Government Affairs at A³ by Airbus managing public policy across the A3 project teams, Airbus' new commercial UAS business and the Airbus Corporate Technology Office (CTO) urban air mobility group. Mr. Mason joins A³ after six years at Alphabet and Google focused on public policy issues facing the company's advanced technology efforts in aviation, renewable energy and life sciences. Before Google, Mr. Mason worked at Booz Allen Hamilton designing collaborative technology solutions across the Departments of Homeland Security, Defense and State.

Graduating from the Maxwell School of Citizenship at Syracuse University, Mr. Mason was recognized as a Harry S. Truman Scholar, one of the country's most prestigious undergraduate awards. He earned his master's from the University of Michigan and has also studied at Princeton University's Woodrow Wilson School of Public Policy and Harvard University's Kennedy School of Government as a Galbraith Scholar.



Mark Moore, Engineering Director of Aviation, Uber



Mark Moore worked for NASA for 32 years before becoming the Uber Engineering Director of Aviation. Uber has developed a transformative vision for urban mobility called Elevate to implement short-range aerial ridesharing to provide a low infrastructure alternative to ground highway gridlock.

Throughout his entire career, Mr. Moore has performed conceptual design studies of advanced aircraft, with a focus on small powered-lift vehicles. Over the past decade, he has focused his attention on the development of Distributed Electric Propulsion (DEP) and autonomy technologies as enablers of new types of vertical flight aircraft. He led three rapid concept to flight demonstrator teams that resulted in the NASA GL-10 VTOL UAV, the LEAPTech Mobile Ground Rig full-scale DEP wing, and the SCEPTOR X-57 (the first NASA X-plane in over a decade). His research focuses on understanding how to best integrate emerging technologies to achieve ultra-low noise, redundant propulsion, robust control and low operating cost ESTOL and VTOL aircraft. He has authored many technical publications promoting a future vision of large-scale distributed and on-demand aviation.



Mr. Moore received his master's degree in aeronautical engineering from Stanford University and is currently completing his PhD at Georgia Tech.

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